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A STUDY OF NEURAL NETWORK BASED IOT DEVICE INFORMATION SECURITY SYSTEM

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ABSTRACT

The development of ubiquitous computing environment has increased interest in IoT (Internet of Things) technology. As IoT has flexible and open characteristics applicable in various fields of industry, increased external accessibility has raised the possibility of external threats. As the existing IoT network was small on scale, there was less risk of security attack. However, continuous IoT development brought the large scale network environment by combining various networks, therefore causing higher risk of security attack compared to small scale network environment. By figuring out the response and implementation time while operating IoT devices to detect intrusion through virus or hacking, the artificial neural network learns various responses using a wide variety of mobile devices. This process may help to deal with current virus and hacking. In addition, by detecting virus and malware in real time, this process may also help to prevent future intrusion. As IoT security risk sharply arises, we suggested an intrusion detection system using artificial neural network model in this study. The system method which is developed in this study can be adjusted to fit various fields and situations of IoT by facilitating flexible modification of critical values. Considering limitations of IoT, the research method which detects anomaly through learning the response and implementation time is expected to be widely used for information security system of various fields which utilize IoT in the future from various angles.

Keywords: Anomaly, Intrusion Detection, Artificial Neural Network, Information System, IoT, Security System

1. INTRODUCTION

Nowadays, the development of ubiquitous computing environment has increased interest in IoT (Internet of Things) technology. IoT is the concept that devices form network by themselves and exchange information. By making the active network between objects and people possible, IoT introduced the environment that each object can freely exchange information with each other [1], and it increased flexibility and openness in various fields. However, on the other hand, increased external accessibility has raised the possibility of external threats. Together with the weakness of the source technology itself, new vulnerability may arise.

Therefore, by examining the response and implementation time while operating IoT devices, the artificial neural network may learn different responses using many other mobile devices to detect intrusion through virus or hacking. It helps to detect virus and hacking in real time and prevent them in advance. In addition, the artificial neural network detect and learn possible malwares and hacking attempts in real time, and this process may be helpful for continuous IoT security.

2. RELATED WORK

2.1 Internet of Things (IoT)

Internet of Things is a global infrastructure which interconnects intelligent objects and helps communication between objects and people combined with context-awareness based knowledge [2].

As shown on Figure 1, IoT concepts are adopted on existing network such as M2M (Machine-to-Machine) and WSN (Wireless Sensor Network) that devices form the network by itself and exchange information. <u>30th November 2018. Vol.96. No 22</u> © 2005 – ongoing JATIT & LLS

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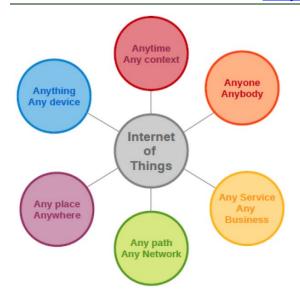


Figure 1: IoT Definition

In the aspect that IoT can connect physical and virtual things and enables communication between objects to exchange information freely, the IoT platform has now more flexible and open characteristics. As the recognition that flexibility and openness of IoT promotes the service quality throughout the industry, focusing on connectivity and data sharing, more studies are now in progress combining IoT with various fields of service such as home appliances and electronics, smart buildings, public utilities, transportation and health care.

2.2 Artificial Neural Network

Artificial neural network consists of various processing units, and it has resilience and learnability [3, 4]. The various processing units consisting artificial neural network are constructed by connection weights between each other [5]. Figure 2 shows the structure of an artificial neural network.

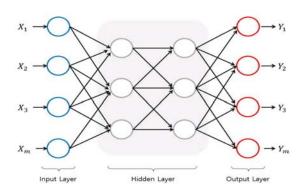


Figure 2: Structure of Artificial Neural Network

Compared to existing statistical models or inductive learning method models, artificial neural network models have relatively high predictability [6]. After applying probit analysis, ID3 and artificial neural network on each experiment, artificial neural network turned out to have the highest predictability. Probit analysis and inductive learning method did not show meaningful difference in predictability[7]. Artificial neural network has become one of the most accurate and widely used prediction models among programs which predict social, economic, engineering, foreign exchange and stock issues.[8]. Recently, artificial neural network models have high possibility to solve complicated issues which are hard to deal with computers, Therefore, many related studies are on rapid progress[9].

Among artificial neural network theory, back-propogation neural network is known as the generalized delta rule[10,11]. It is one of the most widely used and studied research method to train the neural network[12]. Back-propogation neural network consists of input and process units which are known as neurons, also known as neurodes and nodes. Neurons of each layer are completely linked to each other by connection stability called weights which save network information[13]. Backpropogation neural network is linked by process units of input, hidden and output layers. The process units have a learning function which learns input data and a transfer function which sends interconnected activation [14].

MLP (Multi-layer Perceptron) has been widely used in application issues based on the mathematical proof that a sufficient number of middle layer nodes can approximate a random function. Especially, MLP is also often used in pattern recognition issues [15]. MLP makes learning and recognition of a training set possible and it can be used as a mathematical tool to solve complicated classification issues of pattern recognition [16]. The learning process of the artificial neural network is as shown as below

1) According to the target, determine the cost function $(R(\theta))$.

$$R(\theta) = \sum_{k=1}^{K} \sum_{i=1}^{N} (y_{ik} - f_k(x_i))^2 \text{ (or } R(\theta) = -\sum_{k=1}^{K} \sum_{i=1}^{N} y_{ik} \log f_k(x_i) \text{ for classification})$$

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2) After randomly entering the initial weight, calculate the fitted value $(f_{k}(X))$.

3) Partially differentiate the cost function on each weight (Ban ani).

$$\begin{split} & \frac{\delta R_i}{\delta \beta_{km}} \!=\! -2(y_{ik}-f_k(x_i))g^f_{\ k}(\beta^r_{\ k}z_i)z_{mi} \\ & \frac{\delta R_i}{\delta \alpha_{mi}} \!=\! -\sum_{k=1}^{K} \! 2(y_{ik}-f_k(x_i))g^f_{\ k}(\beta^r_{\ k}z_i)\beta_{km}\sigma^f(a^r_{\ m}x_i)x_{il} \end{split}$$

4) By adding or subtracting rth weight (learning rate (a) x partial differentiation value), calculate $r+1^{th}$ weight.

$$\beta_{km}^{(r+1)} = \beta_{km}^{(r)} - \Upsilon_r \sum_{i=1}^{N} \frac{\delta R_i}{\delta \beta_{km}^{(r)}}$$
$$\alpha_{ml}^{(r+1)} = \alpha_{ml}^{(r)} - \Upsilon_r \sum_{i=1}^{N} \frac{\delta R_i}{\delta \alpha_{ml}^{(r)}}$$

5) Repeat from step 2 to step 4 until the error rate is within the margin of the error [17].

In the artificial neural network theory, backpropogation is adjusting the network to reflect the data connected by processing units of input, hidden and output lavers. Through backpropogation, aritificial neurons learn the data entered in processing units learning function, and transfer the activation data interconnected to each other transfer function. We used sigmoid (a mathmetical function having a characteristic of "S"shaped curve) which is generally used in the application of artificial neural network. The connection weights are decided by backpropogation. Backpropogation is most widely used in application of artificial neural network [18]. Figure 3 shows the sigmoid curve function used in this study.

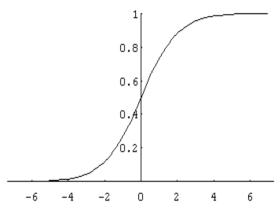


Figure 3: Sigmoid Function

2.3 Information Security System

Detecting network system intrusion accurately in real time is always a difficult goal for system administrators and information security researchers [19]. Nowadays, moreover, security attack technology has been more developed than information protection technology. However, as shown in the graph in Figure 4, it is difficult to solve the problem realistically. Due to the rapid development of Internet, the need to quickly establish protection system to deal with Internet security issues and threats is increasing sharply. However, realistically this issue is not easy to solve. [20]. For this reason, it is not surprising that most of the enterprises are investing more money in information security [21].



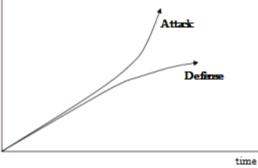


Figure 4: The difference between attack and defense

Based on man-made security attack patterns, the existing method to detect network intrusion is to monitor known security attacks and network anomaly to distinguish network intrusion. An intrusion detection system (IDS) can be classified into host-based intrusion detection system

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(HIDS) which monitors the single system and detects anomaly traffic and network intrusion detection system (NIDS) which monitors the whole network activity [22].

However, the main weak point of IDS is that it cannot detect unknown intrusion. Once a new pattern of attack is found, the whole system needs to be manually updated. However, as the speed and complexity of the network is increasing quickly, the frequency and type of network intrusion is also surging drastically. Therefore, it is regarded to be harder to manually update the system to solve the security issues.

Furthermore, an intrusion detection system identifies system intrusion by monitoring network anomaly[23]. An intrusion detection system is considerably noted for a mechanism that protects the network system by keeping confidentiality, integrity and availability of the network system. However, even though many researchers made considerable efforts, there are still serious weaknesses with an intrusion detection system such as FP(false positive) and FN(false negative)[24]. When an intrusion detection system wrongly interprets normal traffic against attack, it is called FP [22]. When an intrusion detection system regards data actually attacking the system as normal traffic, it is called FN [25]. Due to these critical weaknesses of the intrusion detection system, it is essential to lower FP and FN to increase the accuracy of detection process.

2.4 IoT Security System

IoT can be interpreted as a variety of forms and integrated technologies such as communication/network, device, light weight embedded network, user centered applied service and web service. Therefore, the application range of IoT security technology can be regarded as highly extensive and complicated [26].

As the existing IoT network was small in scale, there was less risk of security attack. However, continuous IoT development brought a large scale network environment integrating various network and it also raised security risk compared to a small scale network [27]. The security issue is becoming more important. Recently, Wifi, Bluetooth and ZigBee are most widely used as IoT network technology. However, each technology has its own weakness: It is difficult to apply high-level encryption technology on ZigBee. Wifi has weakness in security against the attack of information leakage, fabrication and modification. Recently, development of application level protocols such as CoAP and MQTT effectively deals with various linking functions between publish/subscribe sensing devices and services. In the future, it is expected to be widely used as IoT protocol [28].

3. SYSTEM IMPLEMANTATION

Currently, security technology is being widely used in IT industy and will be used more extensively in various fields. However, as ultralight and low cost are essential in commercial IoT environment, we can say that extensive prevention system does not match with IoT enviroment, which makes it difficult to measure and control various data.

Therefore, we used the factor 'time', which is impossible to fabricate, to examine anomaly and tried to find practical ways for detection and prevention against virus and malware. We have performed learning process of the response and implementation time data using Neural Network Tool of MATLAB. Based on learning and test results, we would like to suggest IoT information security system based on artificial neural network. Figure 5 shows the flow chart for this study.

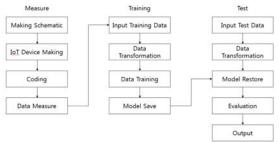


Figure 5: Research Flow Chart

We used Arduino Uno as IoT device for system implementation and additionally installed Wifi Shield to connect to the web. As shown on Figure 5, using Arduino Connection Schematic, we installed 7-segment on breadboard and connected with Arduino Uno for device operation.

Product Name	Quantity??
Arduino Uno R3 Board	1
Arduino Wifi Shield R3	1
Breadboard Standard Half+	1
Register 4700hm	2
7-segment 1-digit FND	1

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Breadboard Jumper Wire	12	web Ardı		
Tact Switch 12x12 mm	1	1.8.1		
USB Cable B-Type	1	1, w		

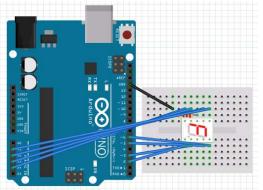


Figure 6: Arduino Connection Schematic

We used wifi shield to connect Arduino Uno to the Internet wirelessly. Through Arduino circuit diagram shown on Figure 6, we set 7segment on breadboard by using IoT devices and equipment on Table 1 and connected it to Arduino Uno as shown on Figure 7.



Figure 7: Arduino Device

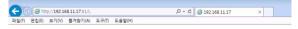
After obtaining device information from wireless router connected to Arduino Uno, we gradually increased the number of access and control to IoT devices from 1 device to 10 devices. Using simultaneous control of 10 devices and 7-segment, we tried number counting from 0 to 9.

In order to control Arduino Uno which was used for this study, we used ARDUINO program offered through the official Arduino website. This program enables connection with Arduino Uno and programming design. ARDUINO 1.8.1 version was used for this study.

As shown on the circuit diagram on Figure 1, we set 2, 3, 5, 6, A1, A2, A3, A4 as output pin of 7-segment and set wifi server as 81. In addition, we set serial as 9600, set ssid and password of wireless router and operated web server by connecting to wifi. By generating JavaScript by client.print, we set the number on 7-segment to count using a herf. Furthermore, through the generator of JavaScript, we measured the time to Milliseconds using Date Object. Through this process, by accessing to Arduino web server, we created a method for number counting of 7-segment and extraction of response and implementation time. Figure 8 shows the core method to measure response and implementation time, and Figure 9 shows the connection to Arduino web server.

void loop() {
#FiClient client = server.available();
<pre>ii (client) { String currentLing -:: If content connected) { if content connected) { if content c</pre>
client.print(" <scnipt_lnnlawe 'iyavscript'="" =="">'); client.print("vert(" = nep Bate()"; client.print("alert(" linish: "det.toUICString().split(" ')[4].split(':')[2]+"."+dt.getWilliseconds());"); client.print("SCSNIPT>);</scnipt_lnnlawe>
<pre>client.print("cituat size"10">dar>dar>dar); client.print("Dick neter#"/#"Out/sdar>"); client.print("dar>dar>dar>dar>dar>dar>dar>dar>dar>dar></pre>
else { currentLine = ""; }
} else if (c != '♥r') { urrentLine += c;
<pre>if (currentLine.eqs@thth(TET IAT)) { clent.print("SSTH(NUBUGE = 'use&cript'>"); client.print("SSTH(NUBUGE = 'use&cript'>"); client.print("var dt = new Date()'); client.print("var d</pre>
} if (currentLine.endsWith("GET /L")) { reset();
<pre>if (currentLine.ends@ith("GET /F")) { reset fail(); } }</pre>
totalTime = 0; client.sto(); Serial.orintln("client disonnected");

Figure 8: The Core Method to Measure Response and Implementation Time



Click COUNT

Click OFF

Click RESET

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Figure 9: Arduino Web Execution Screen

As Arduino Uno uses concurrency control, it processes data according to the time of input and control. As the number of devices controlling Arduino Uno increases, the response time also increases in turn. We measured 10 types of data from using 1 device to 10 devices, measured 200 times each type and extracted 2,000 response time in total. Furthermore, we used the same method to measure, learn and detect to figure out implementation time and deducted 2,000 data in total same as response time. In total, we extracted 4,000 data; 2,000 response time data and 2,000 implementation time data. Figure 10 shows the measurement process of response and implementation time.



Figure 10: Data Extraction Using Arduino Uno Count

4. EXPERIMENTAL CLASSIFICATION RESULTS AND ANLYSIS

In this study, we built the artificial neural network using Neural Network Toolbox of MATLAB R2017a. The structure of artificial neural network model in this study used ten evaluation factors; input layers of ten nodes from one device to ten devices. For extracting learning data of the artificial neural network, we used ten nodes as evaluation factors and generated data 200 times according to response and implementation time, 2,000 data per each time and 4,000 data in total. Among the learning data, we sorted 200 data in one pair and generated 10 pairs of data according to response time and 10 pairs of data according to implementation time.

Table 2 and Table 3 show extracted data for response and implementation time.

Tuble 2. Turi of Kesponse Time Dala Tuble									
1	2	3	4	5	6	7	8	9	10
0. 93 6	6. 31 2	12. 64	19. 146	26. 224	31. 73	37. 987	44. 325	46. 256	57. 293
1. 27 6	7. 10 9	12. 826	19. 17	25. 422	31. 739	37. 954	44. 818	50. 557	57. 115
1. 45 5	6. 27 8	12. 831	18. 85	25. 402	31. 642	38. 072	44. 34	47. 076	52. 637
0. 87 5	6. 29 2	12. 623	19. 06	25. 429	31. 729	37. 994	44. 463	46. 216	57. 042
1. 41 6	6. 29 1	12. 722	18. 996	25. 423	31. 643	39. 646	44. 329	51. 164	57. 036
1. 41 4	6. 52 9	12. 829	19. 63	25. 541	31. 608	37. 624	44. 456	46. 102	56. 625
1. 52 7	6. 17 8	12. 722	19. 159	25. 227	31. 928	38. 084	44. 489	46. 193	57. 253
0. 94	6. 41 8	12. 718	18. 751	25. 794	31. 642	37. 99	44. 535	46. 235	56. 433
1. 35 8	6. 41 2	12. 724	19. 107	25. 437	31. 738	37. 989	43. 639	50. 59	57. 433
1. 39	6. 42	12. 724	19. 021	25. 906	37. 873	37. 997	44. 528	46. 146	57. 44

Table 2: Part of Response Time Data Table

Table 3: Part of Implementation	Time Data Table
---------------------------------	-----------------

1	2	3	4	5	6	7	8	9	10
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
284	58	88	16	468	732	036	344	628	9
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
296	58	868	14	444	74	024	364	612	932
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
296	592	872	164	456	708	008	324	616	916
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
284	592	864	152	492	744	024	352	628	88
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
284	592	848	16	456	756	004	308	612	872
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
288	592	864	16	472	756	052	308	58	928
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02

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288	592	884	164	432	736	032	332	604	916
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
284	588	86	164	452	744	028	332	592	86
0.00	0.00	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
296	588	872	164	436	744	056	332	596	94
0.00	000	0.00	0.01	0.01	0.01	0.02	0.02	0.02	0.02
3	584	868	164	44	764	044	292	62	904

We used logsig function as activation function between input and hidden layers and lastly used 10 nodes which represent the number of nodes for optimized learning. Figure 11 shows the node and layer structure used for learning.

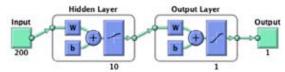


Figure 11: Node and Layer Structure for Actual Data Analysis

We sorted the output layers into 10 nodes from 0 (the best) to 9 (the poorest) and applied backpropagation algorithm as a learning method.

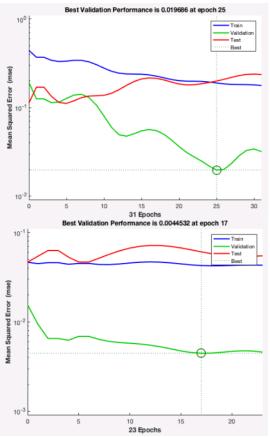


Figure 12: Learning Process Graphs According to Response and Implementation Time

Figure 12 represents the learning process to find the optimized artificial neural network through the program using Neural Network Tool of MATLAB and it shows gradual convergence of output errors. In addition, the experiment results of learning and test data according to response time are as follows; 1Device 0.8264, 2Devices 1.1488, 3Devices 1.16685, 4Devices 2.4455, 5Devices 3.5776, 6Devices 4.7787, 7Devices 6.0763, 8Devices 7.2209, 9Devices 7.7097, 10Devices 8.435. The experiment results of learning and test data according to implementation time are as follows; 1Device 0.33987, 2Devices 0.87541, 3Devices 2.0051, 4Dvices 3.2756, 5Devices 4.0608, 6Devices 4.7047, 7Devices 6.1007, 8Devices 7.4578, 9Devices 8.2585, 10Devices 8.6098. Figure 12 shows learning results based on output layers set from 0 (the best) to 9 (the poorest), not on response and implementation time. By setting critical values of response and implementation time recall rate, the anomaly of IoT can be detected.

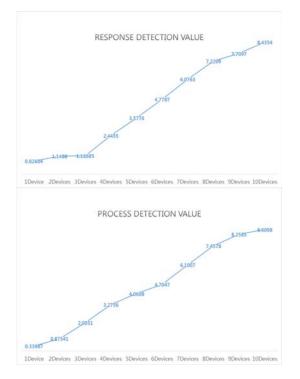


Figure 13: Detection Rate of Learning Method

Considering several limitations of IoT such as low specification and power, this study suggested learning response and implementation time of IoT devices and performed tests based on the learning results. Based on the learning results, we used random test data in order to verify and

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utilize learning results. This study implemented the measurement standard of critical values from 0 (the best) to 9 (the poorest). Based on the critical values, it is expected that setting critical values based on various devices, situations and fields will help to flexibly detect various anomaly when IoT is in use.

5. CONCLUSION

In this paper, we suggested the way to detect anomaly of IoT system by applying artificial neural network theory. Nowadays, IT industry uses IoT concept in the products. Therefore, IoT is widely used in variety of service sectors. However, malicious users may access IoT system using deceptive ways to steal private and service information, which may cause problems on IoT system. As IoT system communicates with various devices, there may be more possibilities of malfunction and non function compared to a single device. System development and software evolution have diversified system intruders, and the combination of existing security technology and models with IoT system security is still insufficient.

In this study, we performed research based on accumulated data using basic artificial neural network algorithm. If we use definite inputs, we could only have fixed learning results. Therefore, if we use unexpected inputs in the study hereafter, we need to study unexpected situation as we may have different conclusions compared to existing learning results and. Furthermore, the security of IoT components in physical environment also needs to be considered. Secure authentication of physical access is required to prevent potential physical damages. In addition, it is necessary to continuously identify various potential threats and find appropriate solutions in terms of cyber security.

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