

# TRACKING COMMUNITY EVOLUTION IN SOCIAL NETWORKS

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## ABSTRACT

Recently, social network analysis is gaining on importance and bringing several challenges in the computer science discipline. Most social networks are dynamic and evolve gradually and the communities in these dynamic networks usually have changing members and could grow and shrink over time. The analysis of communities and their evolution is a relevant research domain that attracts researchers from a variety of fields; having suitable information and methods for dynamic analysis, one may challenge to forecast the future of the communities, and then conduct it appropriately in order to attain or modify this predicted future according to precise requirements. This capability would be a strong mechanism used by marketing, human resource managers, personnel recruitment, etc. In this paper, we are analyzing the changes in the dynamic network through tracking and examining the dynamic evolution of communities within a sequence of snapshots. We start by describing some basic dynamic features of social networks. Then, we propose a new technique called CED (Community Evolution Detection) which was developed in order to detect community evolution in the social network. The central elements of this technique are that it greatly depends on key nodes and QuantityInsertion metric. It also focuses on both efficiency and parameter free. We demonstrate the abilities and potential of our approach by testing it in real datasets and compare it with well-known algorithm with regard to complexity, accuracy and flexibility.

**Keywords:** *Community Evolution, Dynamic Network Analysis, Dynamic Social Network, Evolutionary Analysis, Community Dynamics*

## 1. INTRODUCTION

A social network is a social structure generally modeled as a graph where the nodes represent the social entities (e.g., people) and links describe social interactions (e.g., friendship, collaboration). Social network analysis has been an interesting subject in the field of data mining and has attracted many researchers from different communities such as sociology [1], epidemiology [2], recommendation systems [3], email communication [4], criminology [5] etc. One of the most important problems in network analysis is the identification of community structure, the division of network nodes into subgroups, within which nodes are densely connected while between which they are sparsely connected [6]. The analysis of communities may help find out the structural features of the networks and simplify applications as targeted marketing and advertising [7], and discovering influential individuals [8].

Early studies in analyzing social networks rely on the static properties by modeling the dynamic network as a static graph and discarding the temporal information. This static picture misses the opportunity to detect the evolutionary behavior of the network and the communities. The most existing real-life networks tend to change dynamically and evolve over time. New links may appear all the time due to the network growth or his change over time. So it is interesting to focus the analysis of social networks to the dynamics of these relations in order to better understand the evolution of the interactions between people. This analysis is done through tracking the progress of communities over time in a dynamic scenario.

Certainly, tracking the evolution of communities over time helps to comprehend the background and reasons ruling human comportment; such capability would be a powerful

tool to face many real-world difficulties that arise in marketing, personal recruitment, politics, public security domains, etc. For instance, in marketing, it can be associated with the analysis of possible effect during the announcement of a new product or services, e.g., why some inducements decrease user connections in web-based customer support services. In politics, it can encircle an observation of impacts of given political programs or individual politicians on some social communities and the analysis of influence evolution in time. Principally, it can be used to guide collective reactions to the course of election campaign or to the introduction of changes in the law. In public security affairs, the observation of the community evolution can ease the recognition of users or communities who spread or support unsafe or criminal ideas and compartment, e.g., terrorism.

The evolution of communities in dynamic social networks can be tracked by identifying critical events that characterize the changes in a community over time. In this paper, we present a simple but effective model for efficiently tracking and assessing the evolution and structure of communities over several time frames in a dynamic network, where the life-cycle of each community is characterized by a series of critical states. Based on the community states by matching communities found at consecutive time frames, we identify evolution chains that contain community states in the previous snapshots and its historical transitions. Different from other approaches, the method may combine information from either non-overlapping or overlapping communities and it is free from the selection of the underlying community detection algorithm.

In order to evaluate our approach, we have considered two mobile social network datasets Gowalla and Brightkite by performing experiments into several time frames. The experiment indicates that our method performs well on this data where it identifies events that are omitted by other methods. This gap of results may represent a potential predictor of future behavior.

This paper is organized as follows: In the next section, we provide a brief overview of some related and previous research in the area of dynamic community evolution. Section 3 defines the basic concepts used by our method. The problem formulation is presented in Section 4. The experimental study and results are given in Section 5. Section 6 presents a summary and future work.

## 2. RELATED WORK

There are many studies about community detection [9][6]. The traditional and much known graph clustering method consists on finding for a given graph, an optimal partitioning of a predefined number  $n$  of homogeneous communities. [11] [12]. The graph partitioning has important limitations that have conducted researchers to community detection problem.

Community detection methods are generally categorized into two main classes: static methods and dynamic methods. In both classes, there are methods that consider overlapping communities while others consider non-overlapping methods. The static methods may be categorized into two main classes: optimization based algorithms and heuristic based algorithm. The dynamic methods can be classified into four main categories: Successive static detections, simultaneous study of all stages of evolution, informed successive static detection and methods working on temporal networks. Lately, the temporal evolution of social networks has concerned many scientists. Optimization based algorithms resolves a community detection issue by converting it into an optimization problem and essaying to find an excellent solution with respect to an objective function already defined (The maximization of some quality index), such as various cut criteria implemented by spectral methods [13][14][15], the evaluation function introduced by the Kernighan-Lin algorithm [16], the network modularity used in numerous algorithms [17][18][19][20] and others [21]. On the other hand, heuristic algorithms do not clearly deal with optimization purposes, and they solve a community detection problem founded on assured natural assumptions or heuristic directions. For instance, the heuristic rule used in the maximum flow community (MFC) algorithm [22] is based on the assumption that “flows” through intercommunity links should be larger than those of intra-community links. Similarly, the heuristic rule employed by the GN algorithm [17] is that the “edge betweenness” of inter-community links should be larger than that of intra-community links. Others such as the Wu-Huberan algorithm [23], the HITS algorithm [24], the CPM [25], and the FEC [26] have adopted different assumptions.

In most popular real social sites (such as Facebook, Twitter and LinkedIn) the network

evolve deeply and observe a fast growth in terms of size and space over time, it is useful to consider the fact that connections may be transitory and some network characteristics may change at many time periods. Hence, it is significant to study network evolution and consider a set of snapshots in order to evaluate how the network evolves over time and accordingly discover changes in links between nodes.

Many researches have started working on detecting critical events that track the evolution of communities in dynamic social networks. MONIC framework [27] proposed a generalized evolution study approach to [28]. First, the communities are extracted at each snapshot by using any classical static community detection algorithm. Then, to study the evolution of communities at each snapshot, a many to many matching is applied in order to map communities of the snapshot  $C_i$  to communities  $C_{i-1}$  based on their maximum overlap and an overlap threshold. Also, the authors define numerous rules to handle other cases such as merging, splitting, birth and death of communities. [30] proposed a method that finds events by using Clique Percolation Method (CPM) community detection [29] on a graph made by the communities extracted at two successive time frames. Then, events related to the communities are specified according to the output of the community detection algorithm. [31] state critical events between extracted communities at two successive time frames which are implemented in the structure of bit operations. However, these events do not consider all of the states that can happen for a specific community. [32] defines a weighted bipartite matching to map communities and then described each community by a sequence of events. [33] proposed an event-based framework to consider all the moves from one state to another between communities at two successive time frames. In a later work [34], the event definition formula is enhanced to monitor the transitions of communities over the complete observation time, not only between two successive time frames.

After analyzing the methods presented in the above, we notice that they are three criteria that differentiate between them. The first criterion is the number of other time frames that is used to discover the events relating communities at a given timeframe; there are two possibilities: either using all previous time frames or consecutive time frames. The second criterion is the number of event categories which are continuing, shrinking,

growing, splitting, merging, death and birth. The last criterion is the way of matching communities which could be either one-to-one matching, many-to-many matching or other community detection method such as clique percolation method. Moreover, we note that the most challenge about tracking these dynamic networks is to provide a method that freely scales to networks containing millions of nodes and tens of thousands of communities and fit with overlapping and non-overlapping communities.

From the above considerations, our community evolution tracking method should include matching communities from consecutive snapshots during the identification of events; the matching should be one-to-one and include all categories of events. Moreover, our approach should not require any thresholds or parameters.

### 3. BASIC CONCEPTS

#### 3.1 Dynamic Social Network

A social network is often represented by a graph,  $G=(V, E)$ , where  $V$  is the set of nodes and  $E$  is the set of edges in the network. A dynamic network is a network in which  $V$  or  $E$  changes over time and demonstrated as a series of graphs  $\{G_1, G_2, \dots, G_n\}$ , where  $G_i=(V_i, E_i)$  represents the graph at snapshot  $i$ , which comprises  $V_i$  vertices and  $E_i$  interactions. The  $n_i$  communities detected at the  $i$ th snapshot are then denoted by  $C_i = \{C_i^1, C_i^2, \dots, C_i^{n_i}\}$ , where community  $C_i^p \in C_i$  is also a graph denoted by  $(V_i^p, E_i^p)$ .

An example of a mobile social network is illustrated in Figure 1. It contains four snapshots, and each snapshot is a distinct social network generated from data grouped in a specific time interval. In the simplest situation, one snapshot starts when the preceding snapshot ends.

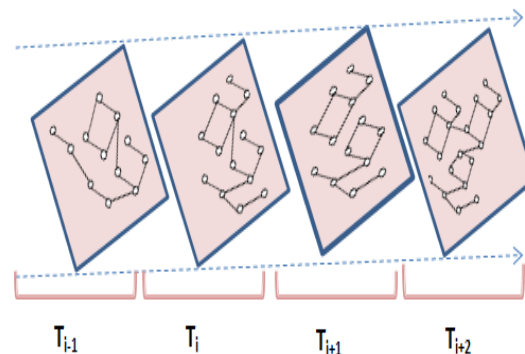


Figure 1: An example of dynamic social network containing four snapshots

### 3.2 Community operations (Community evolution)

When network evolves over time, different community operations may appear. The two main operations are growth and contraction, corresponding to the addition and removal of nodes from an existing community. Then, we observe the birth and death of communities: as the network evolves, new communities may emerge, and old communities may disappear. Finally, we can identify two operations that are a little more complex: fusion and division. During time, two communities may become similar. They are then merged into one. In a complementary way, a community can be divided into two new communities, smaller than the community from which they originated.

Community evolution is a succession of events following each other in the sequential snapshots within the social network. [30] and [31] have suggested some kinds of events but their lists were inadequate. Consequently, in this article, the possible list of events in social community evolution was prolonged. Seven independent classes of events have been recognized altering the state of a community or communities between two subsequent time frames (see Figure 2):

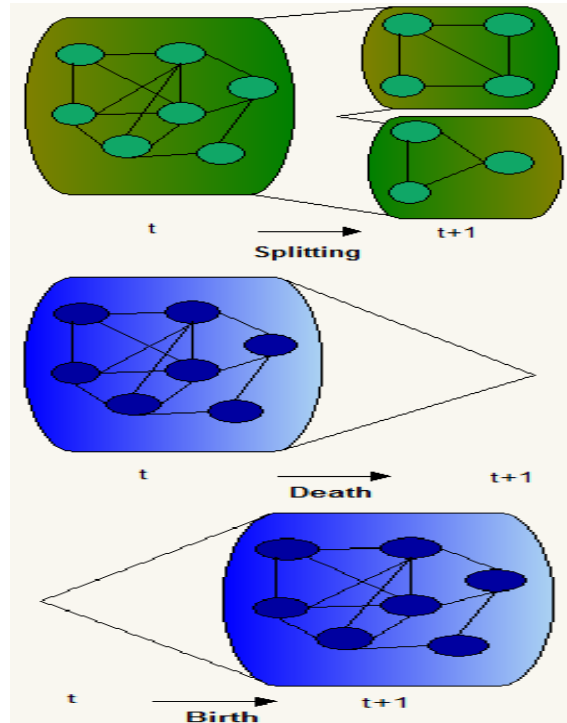
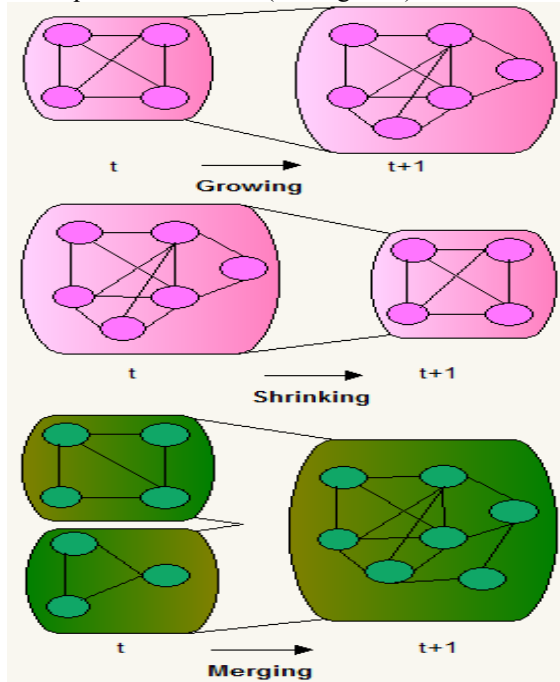


Figure 2: Seven community evolution events

#### Continuing

A community continues its presence, when two communities in the successive snapshots are the same or when two communities vary only by few nodes but their size keeps the same.

#### Shrinking

A community shrinks when some nodes have quiet the community, making its size reduced than in the preceding snapshot. A community may shrink slightly, i.e. by some nodes or significantly mislaying a greatest part of its participants.

#### Growing

(opposite to shrinking): A community becomes larger when some new members have become a part of the community, making its size greater than in the preceding snapshot. A community may evolve slightly as well as significantly, doubling or even tripling its size.

#### Splitting

A community divides into two or more communities in the next snapshot  $T_{i+1}$ , when some communities from snapshot  $T_{i+1}$  contain candidates of one community from the previous snapshot  $T_i$ . We may differentiate two kinds of splitting: (1) equal split happens when the involvement of all resulting communities in the splitting community is nearly similar and (2)

unequal split when one of the final communities has much greater involvement in the splitting community, which in turn for this greater community could be like to shrinking.

### Merging

(Opposite of splitting) A community is formed by merging some other communities when one community from snapshot  $T_{i-1}$  consists of two or more communities from the preceding snapshot  $T_i$ . We notice two types of merge (1) equal, when the involvement of all source snapshots in the merged, target community is almost the same, or (2) unequal, if one of the communities has much greater influence into the merged community.

### Death (dissolving)

Dissolving occurs when a community stops its life and does not happen in the next snapshot at all, i.e. its participants have disappeared or stopped communicating with each other and are dispersed among the rest of the communities.

### Birth (forming)

Creation of the new community (opposite to death) happens when a community, which was not present in the preceding snapshot  $T_i$ , appears in next snapshot  $T_{i+1}$ . When a community stays passive over numerous snapshots, such situation is considered as death of the first community and birth again of the second, new one.

## 4. PROBLEM STATEMENT

To study community evolution, one must first detect the communities by means of any clustering method in different particular periods. In this paper, we are using the community detection method used in our previous work [35] [41] in order to produce set of communities in each snapshot. Our community detection approach is divided into step 1 and step 2 as illustrated in Figure 3 which describes the three main steps required for the study of social community evolution. The first step consists on proposing an approach of clustering semantic information based on spatio-temporal data [41]. First, we divide the mobile social network into different time period snapshots. During each snapshot, we have used a density-based clustering algorithm (ST-DBSCAN) in order to identify groups according to spatiotemporal data which we interpret as equivalent to social perspective communities. However, ST-DBSCAN algorithm is not enough to characterize community structures since links

between actors are not taken into account by the clustering algorithm. Henceforth, we have applied well known random graph models in order to add links that interconnect individuals within a perspective community for finally representing the community structure. Those perspective communities are constructed based on temporary links created between a set of actors during a time window. Principally, we assume that individuals can have temporary ties that might disappear later.

The second step consists on proposing a community detection algorithm [35] by integrating the perspective communities from the step 1. It is about injecting the perspective communities from a mobile social network into an initial friendship network within a sequence of snapshots. In other words, during each snapshot, we built an augmented friendship social network using the semantic information extracted from perspective communities. This semantic information is integrated by changing the weight of friendship network links according to the perspective communities. Then, after the augmented friendship social network is built, a detection community algorithm is applied which results on communities that may be part of several networks in a given time period.

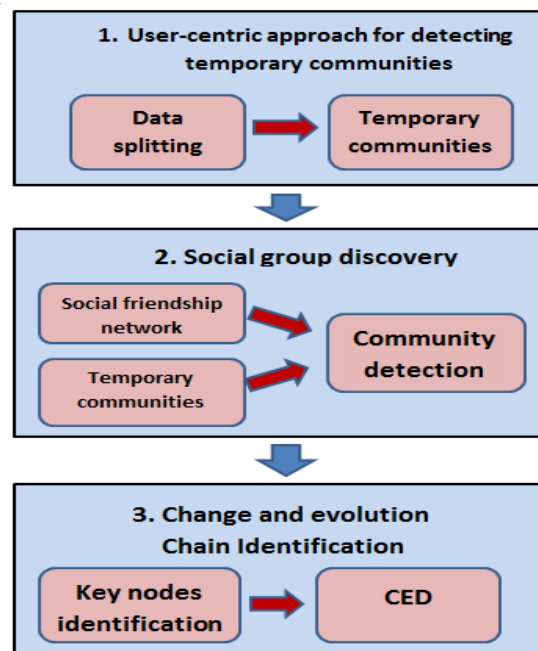


Figure 3: The three main steps for the study of social community evolution

The next step after extracting communities during each snapshot is to detect changes of social communities between two consecutive snapshots  $T$



**Algorithm 1** Algorithm KeyNodeDetection

**Input:** a community C with n vertices  
**Output:** the set of key nodes of C

Compute the social position of each node in C  
**if**  $SP(V_1) = SP(V_2) = \dots = SP(V_n)$  **then**  
    Return C  
**end if**  
 $key(V_1) = 0, k \in [1, n]$   
**for** every edge  $e \in Edge(C)$  **do**  
     $V_i, V_k$  are nodes connected with  $e$   
    **if**  $SP(V_k) < SP(V_i)$  **then**  
         $key(V_k) = key(V_k) - |SP(V_k) - SP(V_i)|$   
         $key(V_i) = key(V_i) + |SP(V_k) - SP(V_i)|$   
    **end if**  
    **if**  $SP(V_k) \geq SP(V_i)$  **then**  
         $key(V_k) = key(V_k) + |SP(V_k) - SP(V_i)|$   
         $key(V_i) = key(V_i) - |SP(V_k) - SP(V_i)|$   
    **end if**  
**end for**  
keyset = {}  
**for** every node  $V_i \in Vertex(C)$  **do**  
    **if**  $key(V_k) \geq 0$  **then**  
        input  $V_k$  into keyset;  
    **end if**  
**end for**  
return keyset

and T+1. Particularly, there exists a community in snapshot T and what about its state in the following time frame T + 1. Does it divide into a minor ones or fuse into a bigger one with another community? It is about detecting events such as growing, merging, death and so on. A new technique called CED (Community Evolution Detection) was developed in order to detect community evolution in the social network. The central elements of this technique are: it greatly depends on key nodes and QuantityInsertion metric. This metric allows evaluating the inclusion of one community in another. In other words, how many members from community  $C_i^{(t)}$  are in community  $C_j^{(t+1)}$ ? Consequently, QuantityInsertion  $QI(C_1, C_2)$  of community C1 in community C2 is computed as follows:

$$QI(C_i^{(t)}, C_j^{(t+1)}) = \frac{|C_i^{(t)} \cap C_j^{(t+1)}|}{|C_i^{(t)}|} \quad (1)$$

In the following section, the algorithm of key node detection is firstly introduced and then we present our core-based algorithm of tracking community evolution.

**4.1 Key Node Detection Algorithm**

As covered earlier, key nodes are significant in our evolution algorithm that is why their selection is of greatest importance. We believe that key nodes play a good stable quality element since the key nodes do not appear unexpectedly without any evidence in the past snapshots.

Since the structure of a community is excessively dynamic and changeable, it is very difficult to fix an experimental threshold to differentiate key nodes from regular ones. Contrasting to [36], our technique focuses on both efficiency and also parameter free. In order to find out community key members, several techniques have been suggesting quantifying the nodes' centrality measures such as degree, betweenness, paging rank and so on. Normally, the higher a node's centrality measure is, the more central it is in a community. In our method, a node  $N_i$  is given a key value  $SP(V_n)$  by computing its social position. For complete information about social position metric, how to compute and implement it refer to [37] [38] [39] [40].

In brief, for each vertex  $V_i$ , we compare its social position value with the one of its neighbor, if  $SP(V_i)$  is higher than the social position of  $SP(V_j)$ , then  $V_i$  is considered more essential than  $V_j$ , so  $V_i$ 's key value should be incremented by the difference of social position value of both nodes, on the other hand,  $V_j$ 's value is decremented by the same value. After going through all the edges, if  $V_i$ 's key value is positive, it is considered as a key node. If not, it is just a normal node. The pseudo-code of the algorithm is described in Algorithm1.

**4.2 Key-based Algorithm of Detecting Community Evolution**

The fact that employing community quantity insertion and centrality social position for identifying the changes within the community gives our algorithm a great gain over other techniques; it respects both the quantity and quality of community members. The quality is guaranteed by the detection of key members, while the quantity is reflected by the QuantityInsertion metric. Really, this method offers equilibrium between the communities that contain only little but more important members and communities with many of less core members. It is expected that only one event can happen for two communities ( $C_i^{(t)}, C_j^{(t+1)}$ ) in the successive snapshots; but, one community in snapshot t can take part in many events with several communities in t+1.

The process for the Community Evolution Detection Technique (CED) is described by the algorithm2.

*Algorithm 2 Community Evolution Detection*

**Input:**

**Output:**

KeyDet( $C_i^{(t)}$ )=KeyNodeDetection( $C_i^{(t)}$ )

**for** every community  $C_j^{(t+1)}$  in snapshot  $t + 1$  **do**

**if**  $QI(C_i^{(t)}, C_j^{(t+1)}) = QI(C_i^{(t)}, C_j^{(t)})$  **and**  $|C_i^{(t)}| = |C_j^{(t+1)}|$  **then**

Communities ‘continuing’;

**else if**  $QI(C_i^{(t)}, C_j^{(t+1)}) < QI(C_i^{(t+1)}, C_j^{(t)})$  **and**  $|C_i^{(t)}| > |C_j^{(t+1)}|$  **and**  $QI(C_i^{(t)}, C_j^{(t+1)}) = 1$  **and**

$KeyDet(C_i^{(t)}) \cap Node(C_j^{(t+1)}) \neq \emptyset$  **then** (there is only one matching event between  $C_j^{(t+1)}$  and all communities in the previous snapshot  $T_i$ )

Communities ‘shrinking’;

**else if**  $QI(C_i^{(t)}, C_j^{(t+1)}) > QI(C_i^{(t)}, C_j^{(t+1)})$  **and**  $|C_i^{(t)}| < |C_j^{(t+1)}|$  **and**  $KeyDet(C_i^{(t)}) \cap Node(C_j^{(t+1)}) = |KeyDet(C_i^{(t)})|$  **then**

Communities ‘growing’; (there is only one matching event between  $C_i^{(t)}$  and all communities in the next snapshot  $T_{i+1}$ )

**else if**  $QI(C_i^{(t)}, C_j^{(t+1)}) > QI(C_i^{(t)}, C_j^{(t+1)})$  **and**  $|C_i^{(t)}| > |C_j^{(t+1)}|$  **and**  $KeyDet(C_i^{(t)}) \cap Node(C_j^{(t+1)}) \neq \emptyset$  **then**

Communities ‘splitting’; (there is more than one matching event between  $C_j^{(t+1)}$  and all communities in the previous snapshot  $T_i$ )

**else if**  $QI(C_i^{(t)}, C_j^{(t+1)}) < QI(C_i^{(t)}, C_j^{(t+1)})$  **and**  $|C_i^{(t)}| < |C_j^{(t+1)}|$  **and**  $KeyDet(C_i^{(t)}) \cap Node(C_j^{(t+1)}) \neq \emptyset$  **then**

Communities ‘merging’; (there is more than one matching event between  $C_i^{(t)}$  and all communities in the next snapshot  $T_{i+1}$ )

**else if**  $QI(C_i^{(t)}, C_j^{(t+1)}) \neq QI(C_j^{(t+1)}, C_i^{(t)})$  **and**  $Node(C_i^{(t+1)}) \cap KeyDet(C_j^{(t)}) = \emptyset$  **and**

$KeyDet(C_i^{(t+1)}) \cap Node(C_j^{(t-m)}) = \emptyset$  **then**

Communities ‘Birth’;

**else if**  $QI(C_i^{(t)}, C_j^{(t+1)}) \neq QI(C_j^{(t+1)}, C_i^{(t)})$  **and**  $KeyDet(C_i^{(t)}) \cap KeyDet(C_j^{(t+1)}) = \emptyset$  **and**

$KeyDet(C_i^{(t-m)}) \cap KeyDet(C_j^{(t+1)}) = \emptyset$  **then** (for  $C_i^{(t)}$  in  $T_i$  and each communities  $C_j^{(t+1)}$  in  $T_{i+1}$ )

Communities ‘Death’;

## 5. EXPERIMENTAL STUDY

### 5.1 Experimental Datasets

We execute experiments to assess our algorithm on real social network dataset; we are using two real datasets: Gowalla and Brightkite. Gowalla is a location-based social network created in 2009: users are able to check-in at places through their mobile devices; Check-ins are shared with friends. The Gowalla dataset [32] is a 196,591 users' friendship network. The check-in data were collected from February 2009 to October 2010 and each user has 32.8 check-in records on average. Brightkite is a location-based social network created in 2007: users are able to check-in at places through their mobile devices; Brightkite users can establish mutual friendship links and they can push their check-ins to their Twitter and Facebook accounts. We study a dataset collected in September 2009 which includes the whole Brightkite user base at that time, with information about 54,190 users.

In the dataset, a check-in record is a tuple  $\langle \text{userid}, \text{check-in time}, \text{latitude}, \text{longitude}, \text{location id} \rangle$ . Here latitude and longitude denotes the latitude and longitude of the location where the user visited, and check-in time denotes the time stamp of the check-in activity. Each user in the dataset has a check-in list which contains a location sequence and a time-stamp sequence.

We are studying active users whose number of check-ins is greater than 50. The reason of choosing this number is to capture important characteristics of users' behaviors through check-in activities. We set the snapshots to be one month each for a period of one year.

### 5.2 Evaluation measures

On both these datasets, we compare our method CED (community evolution detection) with another event-based framework GED (The method for group evolution discovery).

#### 5.2.1 The number of identified events

A distribution of events in both Gowalla and Brightkite datasets extracted correspondingly by CED and GED during the 12 time frames is illustrated in both Figure 3 and Figure 4. We notice that in both Gowalla and Brightkite datasets, splitting and merging are the most frequent events. Brightkite has a meaningfully different characteristic, it holds much more events compared to Gowalla. The number of merging and splitting

events is higher than the other events for both datasets and in both methods: CED and GED.

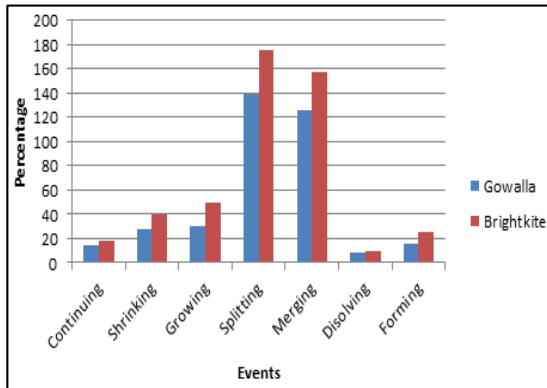


Figure 4: Distribution of the event types using CED

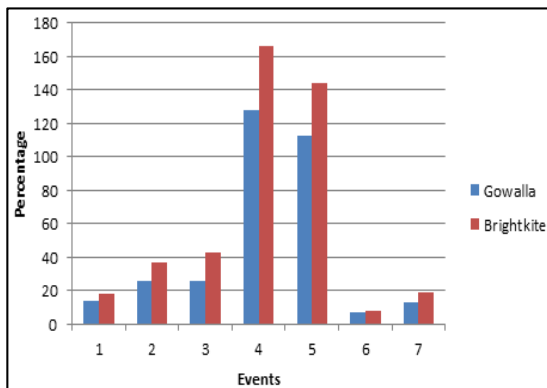


Figure 5: Distribution of the event types using GED

The Figures 5-11 represent the amounts of different types of event transitions recognized by both algorithms CED and GED in the corresponding time slots using Gowalla dataset.

**Continuing:** Figure 5 illustrates the number of transitions associated to communities without change (continuing). Our method discovered more events of this category.

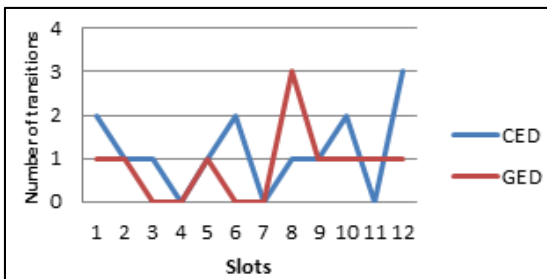


Figure 6: Distribution of continuing event

**Shrinking:** Figure 6 describes the number of transitions related to community shrinking. Our method discovered more events of this category.

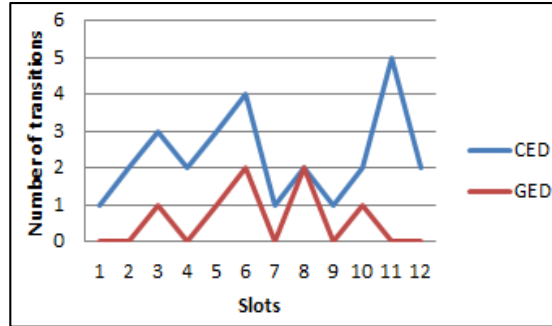


Figure 7: Distribution of shrinking event

**Growing:** Figure 7 presents the number of transitions corresponding to community growing. Our method discovered more events of this category.

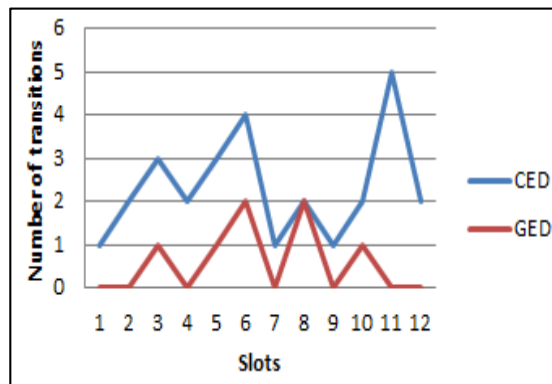


Figure 8: Distribution of growing event

**Splitting:** Figure 8 demonstrates number of transitions associated to community splitting.

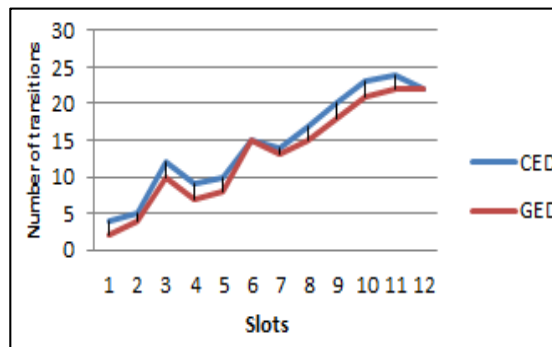


Figure 9: Distribution of splitting event



**Merging:** Figure 9 illustrates the number of transitions associated to community merging. Our method discovered more events of this category.

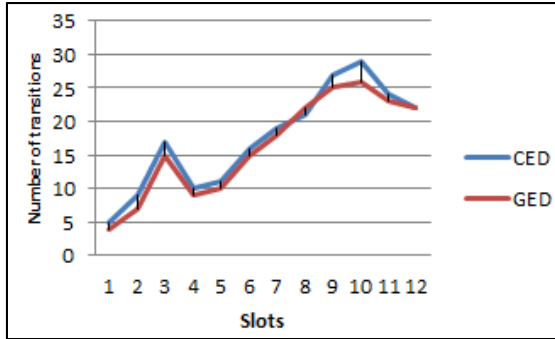


Figure 10: Distribution of merging event

**Dissolving:** Figure 10 shows the number of transitions associated to community dissolving. Our method discovered more events of this category.

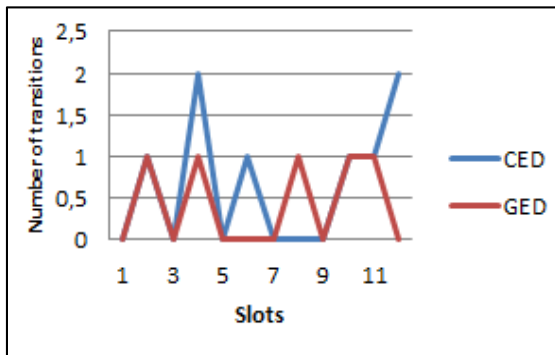


Figure 11: Distribution of dissolving event

**Forming:** Figure 11 presents the number of transitions associated to community merging. Our method discovered more events of this category.

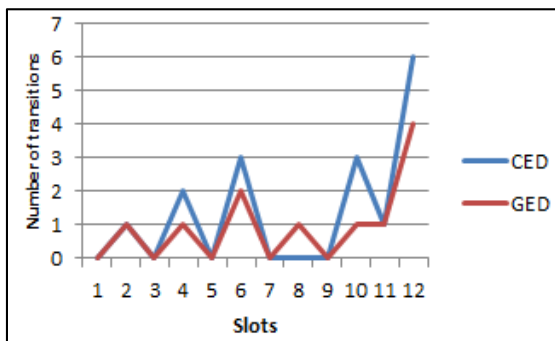


Figure 12: Distribution of forming event

### 5.2.2 Events discovered by our method CED and not discovered by GED

Table 1 illustrates the events that our method CED has identified and GED method has not. GED did not find those events because the approach is based on two parameters: alpha and beta (See [10] for complete description). The entire events not found by the GED method have both inclusions beneath 50%, which was reflected in the value for alpha and beta thresholds. To demonstrate this, the GED method was computed once more with thresholds equal to 10%. The result shows that only few events identified by our method were absent in the GED method.

Table 1: Events that CED has discovered (CEDF) and GED has not found (GEDNF) and Total no. of distinct events found by both methods (DE)

DataSet	Total no. of events found		No. of events CEDF		Total no. DE
	CED	GED	CED	GED	CED & GED
Gowalla	428	412	46	77	441
Brightkite	407	389	38	69	423

Using the event transitions extracted earlier between two consecutive snapshots, an evolution chain may be produced for each community  $C_i$  from  $T_n$ . Such chain contains all other previous communities from the preceding snapshots ( $T_{n-1}$ ,  $T_{n-2}$ ,  $T_{n-3}$ , etc.) the current community  $C_i$  comes from. Generally, it may occur that a community has been formed from two or more other communities—through merging. For instance, community  $C_{i+3}$  came into being from  $C_{i+1}$  and  $C_{i+2}$ . In such case, two separate evolution chains are being created for  $C_{i+3}$ , one with community  $C_{i+1}$  and one with  $C_{i+2}$ .

Table 2 shows the overall numbers of chains detected in each dataset, whereas the detailed statistics concerning occurrences of kinds of events in datasets are illustrated in Tables 3. From table 2, one can notice that the overall number of chains using Gowalla and Brightkite decreases while the length of chain increases. This behavior comes from the fact that our dataset contains less events that decrease the number of chains when we take into account longer chains, i.e., events such as forming, dissolving, continuing represent a small number.

Table 2: The number of evolution chains for particular chain length: CED

Chain Length	Gowalla	Brightkite
2	860	820
3	705	677
4	594	521
5	480	419
6	316	306
7	222	203
8	105	97
9	78	66
10	59	43

Table 3: The number of evolution chains for particular event type and particular chain length (CL) in Gowalla CED

CL	Containing	Shrinking	Growing	Splitting	Merging	Dissolving	Forming
2	150	249	217	96	136	4	8
3	98	190	202	88	129	3	8
4	86	163	193	72	103	2	5
5	72	123	184	68	95	2	3
6	64	94	176	61	84	1	3
7	55	87	168	54	72	1	1
8	47	71	154	46	69	1	0
9	36	62	140	38	62	0	0
10	32	56	131	32	54	0	0

### 5.2.3 Differences between our method CED and the method GED

Our method is faster on computing results rather than GED method and greatly depends on key nodes. Moreover, it is implemented with free parameters. However, the GED method depends heavily on two parameters  $\alpha$  and  $\beta$ . Those parameters need full control and impact the number of events obtained which proves the large gap in the attained results.

The above considerations approve that the CED method is better than GED method for both non-overlapping and overlapping community detection methods.

## 6. CONCLUSION

One of the challenging research problems in dynamic social networks is to extract communities and analyze their evolution over time. In this article, we overviewed different dynamic

community detection approaches. We then provide a method which monitors the changes in the dynamic network through tracking and examining the dynamic evolution of communities within a sequence of snapshots. In other words, we propose a model to capture all the possible events that may occur for communities. This approach will help comprehend the mechanisms leading the growth and changeability of social communities. The strengths of our community evolution discovery method are the following: it was designed to be parameter-free, conserves the low and adaptable computational complexity and is appropriate to determine fusion and division events. Simultaneously, it was designed to fit in both overlapping and disjoint communities. However, our challenge is to scale in large network. Our experiment is using a real-life datasets in order to analyze the soundness and feasibility of this technique. Our future work will be extending our present work by predicting the future changes of the communities based on the present and precedent events.

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