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PERFORMANCE ANALYSIS OF SLEACH, LEACH AND DSDV PROTOCOLS FOR WIRELESS SENSOR NETWORKS (WSN)

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ABSTRACT

Wireless Sensor Networks (WSN) is an emerging technology for attraction of researchers with its research challenges and various application domains. It consists of small nodes with sensing, computation, and wireless communications capabilities. The limited energy resource is one of the main challenges facing the security in such networks. An attempt has been made to compare the performance of three protocols DSDV, LEACH and SLEACH. The purpose of this paper is to create a simulation of these protocols using NS2. Comparison is made based on packet delivery fraction, average end-to-end delay, throughput, average jitter and packet loss. This paper presents all scenarios for simulation and then we analyzed the results.

Keywords: Wireless Sensor Network, Hierarchical Routing, DSDV, LEACH, SLEACH

1. INTRODUCTION

Wireless sensor network is a popular area for research nowadays, due to vast potential usage of sensor networks in different areas. Typically, wireless sensor networks contain hundreds or thousands of these sensor nodes that are generally identical. These sensor nodes have the ability to communicate either among each other or directly to a base station (BS).

The sensor network is highly distributed and the nodes are lightweight. Intuitively, a greater number of sensors will enable sensing over a larger area [1].

This paper have been made to provide a systematic comparative analysis of three popular routing protocols: LEACH, SLEACH and DSDV.

The objective of our analytical simulation is to understand the various approaches proposed by researchers to overcome routing inefficiency in WSN. Also, compare a secured hierarchical protocol with other protocols namely its behavior using these criteria. There are quite a number of routing protocols that are excellent in term of efficiency. However, the security requirements of these protocols changed the situation and a more detailed research is currently underway to develop secure routing protocols. To address these concerns, we compared secure LEACH (SLEACH) to LEACH and DSDV protocols. SLEACH is

meant to protect outsider attacks that is why it is performed much better than LEACH and DSDV of all metrics.

The remainder of this paper is structured as follows: Sections 3 and 4 give an overview and description of routing protocols that is analyzed. Section 5 presents a brief description of the simulation parameters. The simulation results and comparative analysis of the above said routing protocols are discussed in section 6. Finally, section 7 concludes with the comparisons of the overall performance of these protocols.

2. RELATED WORK

Most of the research literature involves comparing AODV, DSR and DSDV [2-6]. Very little work exists in literature that discusses LEACH, SLEACH and DSDV.

In [7], there is comparison of various routing protocol in wireless sensor network, the authors have observed that AODV gives the better performance for both MANETs and WSNs with respect to packet delivery ratio, routing overhead, throughput put and average delay by varying number of nodes. However, LEACH is better for Average End to End Delay, less packet loss but not in case of Packet delivery ratio.

In [8], comparison of DSDV, AODV and DSR protocols has been performed by using NS2 simulator. DSR is better in comparison of AODV

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and DSDV du to a smaller amount of routing overhead when node have high mobility, counting the metrics throughput, average end-to-end delay and packet delivery ratio.

In [9], author give a comparison of routing protocols, where AODV, DSDV and DSR are compared. The author observed that AODV perform well when area in large. In the other hand, DSR is good for the condition when there is balanced traffic and mobility and movement of nodes is less then DSDV will be preferable.

In [10], the author compares AODV, DSR, TORA protocols by using OPNET Modeler. From the study of simulation is clear that TORA is better than AODV and DSR when the number of nodes increased in a network but it cannot be necessarily that TORA will perform well, the performance may depending by varying the network.

In [11], comparison of AODV, TORA, LEACH protocols has been performed with the metrics-Average End-to-End Delay, Packet Delivery fraction, packet loss. LEACH is better for Average End to End Delay, less packet loss but not in case of Packet delivery ratio.

3. ROUTING PROTOCOLS IN WIRELESS SENSOR NETWORK

Wireless Sensor Networks can be divided into Table-Driven and On-Demand Routing protocol where Table Driven protocols are proactive and maintain a routing table, On-Demand are active and do not maintain a routing table and cluster based routing.

The main aim of cluster based routing is to efficiently maintain the energy usage of sensor nodes by involving them in multi-hop communication within a particular cluster. Cluster formation is generally based on the energy reserve of sensors and sensors proximity to the Cluster Head (CHs). Clustering plays an important role for energy saving in WSNs. With clustering in WSNs, energy consumption, lifetime of the network and scalability can be improved [12].

In cluster based WSNs, sensor nodes are arranged into number of clusters. Every sensor cluster is managed by a CH during the network operation such as data transmission. LEACH (Low Energy Adaptive Clustering Hierarchy) is a cluster based routing protocol for WSNs. But LEACH routing protocol is lack of security. 4. DESCRIPTION OF ROUTING PROTOCOLS: DSDV, LEACH AND SLEACH

LEACH is based on a hierarchical clustering structure model and energy efficient cluster-based routing protocols for sensor networks. In this routing protocol, nodes self-organize themselves into several local clusters, each of which has one node serving as the cluster-head. In order to prolong the overall lifetime of the sensor networks, LEACH changes cluster heads periodically. LEACH has two main steps: the set-up phase and the steady-state phase. In the set-up phase, there are two parts, the cluster-head electing part and the cluster constructing part [13].

The advantages of LEACH include the following [14]:

- Any node that served as a CH in certain round cannot be selected as the CH again, so each node can equally share the load imposed upon CHs to some extent.
- Utilizing a TDMA schedule prevents CHs from unnecessary collisions.
- Cluster members can open or close communication interfaces incompliance with their allocated time slots to avoid excessive energy dissipation.

DSDV is a table driven routing scheme for ad hoc mobile networks based on the Bellman-ford algorithm. The improvement made to the Bellman-Ford algorithm includes freedom from loops in routing table by using sequence numbers [15]. Each node acts as a router where a routing table is maintained and periodic routing updates are exchange, even if the routes are not needed. A sequence number is associated with each route or path to the destination to prevent routing loops. Routing updates are exchanged even if the network is idle which uses up battery and network bandwidth. Thus, it is not preferable for highly dynamic networks.

SLEACH protocol is the first attempt to build a secure version of the well-known LEACH protocol. It is prevents sinkhole, selective forwarding and HELLO flooding attacks. SLEACH prevents an intruder node to send falsified data messages. However, it doesn't guarantee confidentiality and availability. This algorithm works with homogeneous WSNs in which all nodes have the same characteristics, i.e., initial energy, and processing power. This algorithm makes use of cryptography as the security mechanism by using symmetric-key methods. It can protect the network

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from outsider attack but it decreased the network efficiency and performance [16].

5. EXPERIMENTAL RESULTS

4.1 Simulation Tools

Network Simulator (Version 2), widely known as NS2, is simply an event driven simulation tool that has proved useful in studying the dynamic nature of communication networks. It was developed at the University of California at Berkeley and extended at Carnegie Mellon University, CMU, to simulate wireless networks [17]. The simulator is written in C++, accompanying an OTCL script language based on Tcl/Tk. The researcher defines the network components such as nodes, links, protocols and traffic using the OTCL script. NS-2 uses OTCL as the interface to the user (Figure 1). This script is then used with NS, the simulator, to conduct the desired simulation, and as a result outputs traces at different selective layers. The output data within the trace output files is then filtered and extracted using statistical analysis software like excel/access program. The extracted relevant data is then used to evaluate performance by manipulating various metrics such as delays, throughput, overheads etc [18].



Figure 1: Simulation Overview

4.2 Simulation Environment

A simulation experiment was performed by using NS2 simulator to study the performance of three protocols mentioned LEACH, SLEACH and DSDV [19]. Simulation experiment was performed twice by taking 30, 60, 90, 120, 150, 180 nodes in first

scenario and 50, 100, 150, 200, 300 nodes in second scenario to study the performance of three protocols. Simulation time will be 100 sec for first scenario and 200 sec for second scenario. The following tables are the configurations set as per the assumed simulation context:

Table 1: Simulation parameters for scenario 1

Parameters	Value	
Simulator	NS-2 (version 2.35)	
Channel type	Channel/Wireless channel	
Radio-propagation	Propagation/TwoRayGround	
model		
Network interface	Phy/WirelessPhy	
type		
МАС Туре	Mac /802.11	
Interface queue	Queue/DropTail\PriQueue	
Туре		
Link Layer Type	LL	
Antenna model	Antenna/OmniAntenna	
Packet size	512 MB	
Number of nodes	30, 60, 90, 120, 150, 180	
Traffic type	TCP, CBR	
Simulation Time	100 sec, 200 sec	
Routing Protocols	DSDV, LEACH, SLEACH	
Nominal bit rate	2 Mb/s	
Node speed	20m/s - 15m/s	
Transmission rate	4 packets/sec	
Area of simulation	1000m * 300m	
Queue Length	50	

 Table 2: Simulation parameters for scenario 2

Parameters	Value	
Simulator	NS-2 (version 2.35)	
Channel type	Channel/Wireless channel	
Radio-propagation	Propagation/TwoRayGround	
model		
Network interface	Phy/WirelessPhy	
type		
MAC Type	Mac /802.11	
Interface queue	Queue/DropTail\PriQueue	
Туре	_	
Link Layer Type	LL	
Antenna model	Antenna/OmniAntenna	
Packet size	512 MB	
Number of nodes	50, 100, 150, 200, 250, 300	
Traffic type	TCP, CBR	
Simulation Time	100 sec, 200 sec	
Routing Protocols	DSDV, LEACH, SLEACH	
Nominal bit rate	2 Mb/s	
Node speed	20m/s - 15m/s	
Transmission rate	4 packets/sec	
Area of simulation	1000m * 300m	
Queue Length	50	

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4.3 Performance Metrics

The performance of the proposed protocol is evaluated using the ns-2 simulator. A set of performance metrics are used for comparing the protocol of this work, each of these metrics parameters can be described briefly as follows:

Packet delivery fraction (PDF) [20]: is the fraction of all the received data packets successfully at the destinations over the number of data packets sent by the CBR sources.

Average end-to-end delay: There are possible delays caused by buffering during route discovery queuing at the interface queue, latency. retransmission delays at the MAC, and propagation and transfer times [21, 22]. The average end-to-end delay is an average end-to-end delay of data packets. It also caused by queuing for transmission at the node and buffering data for detouring. Once the time difference between every packet sent and received was recorded, dividing the total time difference over the total number of total packets received gave the average end-to-end delay for the received packets. The performance is better when packet end-to-end delay is low. It is calculated as follows:

$\frac{\sum_{1}^{n} (Packet_Sent_Time - Packet_Recv_Time)}{\sum_{1}^{n} Total_Packets_Recv}$

Packet loss: It is the difference between the total numbers of packets send by source and received by sink. A packet is dropped in two cases: the buffer is full when packet needs to be buffered and the time that the packet has been buffered exceeds the limit [23].

Throughput: The throughput metric measures how well the network can constantly provide data to the sink [24]. It can be defined as how many data packets received by receiver with in data transmission time or successful data transmission performed within a time period. In any network, throughput is average rate of successfully data packet delivered from source node to destination node. Throughput is represented in bits/bytes per second. In any network, higher throughput is most essential factor. The throughput is calculated as follows:

Received_Packet_size Time_To_Send

Average Jitter: is the variation in the time between packets arriving, caused by network congestion, timing drift, or route changes [25]. More formally in a particular stream of packet, S_i is the time when

packet \mathbf{i} was send from the sender, $\mathbf{R}_{\mathbf{i}}$ is the time which received by the receiver, the jitter of packet I is given by:

$$J_i = |(R_{i+1} - R_i) - (S_{i+1} - S_i)|$$

It should be less for a routing protocol to perform better.

4.4 Performance evaluation

This section presents our simulations results. In order to compare the performance of DSDV, LEACH and SLEACH in terms of average jitter and throughput we carried out simulations for different scenarios.



Figure 2: Throughput

From the figure 2, it is quite clear that SLEACH perform much better than LEACH and DSDV as it delivers data packets at higher average rate in comparison to LEACH and DSDV.

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Figure 3: Average Jitter

From the figure 3, according to our simulation results, DSDV has less jitter than SLEACH and LEACH. SLEACH and LEACH performed the worst in case of average jitter.

6. RESULTS AND DISCUSSION

In this section, the performance of SLEACH, LEACH and DSDV have been compared based on three performance metrics: Packet delivery fraction (PDF), average end-to-end delay and packet loss.

The purpose of the study was to investigate the behaviors of SLEACH, LEACH and DSDV for these metrics.



Figure 4: Average end-to-end delay for SLEACH, LEACH and DSDV (Scenario 1)



Figure 5: Average end-to-end delay for SLEACH, LEACH and DSDV (Scenario 2)

From figures 4 and 5, we observe that average end-to-end delay is less for SLEACH as compared to LEACH and DSDV.

Figure 4 shows that LEACH and DSDV average delay is almost equal than SLEACH because they have higher average delay than SLEACH. The performance of SLEACH is uniform.

From figure 5, we observe that the average delay for LEACH becomes very high and increases when the number of nodes increases except for 100 and 200 nodes. Besides, when the network size increases, the DSDV's average delay increases also, specially, when the numbers of nodes are between 100 and 250, but it decreases further up to 250 while it remains uniform for SLEACH.





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Figure 7: Packet delivery fraction for SLEACH, LEACH and DSDV (Scenario 2

From figures 6 and 7, when looking at the packet delivery fraction (PDF), it can easily be seen that SLEACH perform much better than LEACH and DSDV.

Based on figure 6, it is clear that the PDF for the three protocols decrease or increase according to number of nodes, because at network size from 30 to 60, it decreases for SLEACH and LEACH, in the other side, it increases for DSDV. Besides, it increases for SLEACH and DSDV while it decreases for LEACH when the numbers of nodes are between 150 to 180.

From figure 7, it is observed that in low network size, SLEACH gives higher PDF; while PDF is minimum for DSDV. When the numbers of nodes are between 150 and 220, the PDF almost remains constant for SLEACH while it decreases for LEACH and DSDV. Now when the numbers of nodes are increased further up to 270, the PDF increases for SLEACH and LEACH while it decreases for DSDV.



Figure 8: Packet loss for SLEACH, LEACH and DSDV (Scenario 1)



Figure 9: Packet loss for SLEACH, LEACH and DSDV (Scenario 2)

From figures 8 and 9, the packet loss is increases at some points and decreases at other points.

It is observed from the figure 8 that in low network size, DSDV gives highest packet loss; while it is minimum for SLEACH and LEACH. In high network size, the packet for LEACH and SLEACH increase again while it decreases for DSDV.

Based on figure 9, the packet loss becomes very low for LEACH and SLEACH, however, it increases when the network size increase, and it

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decreases for the three protocols when the number of nodes are between 200 and 300.

7. CONCLUSION

Sensor node has a limited amount of battery in sensor network. So, it is important to have the maximum lifetime of network through energy effective routing. That is why, designing and selecting an appropriate secure routing protocol for the network is a tough task. Because of this reason, SLEACH protocol selected. It gives better result than normal LEACH protocol.

In this paper, we focused on the three routing protocols LEACH, SLEACH and DSDV. These protocols have been evaluated on NS2 simulator by using five performance metrics such as packet delivery fraction, average end-to-end delay, throughput, average jitter and packet loss.

Each protocol gives variant performance in different scenario so no one protocol can be chosen best for all type of network. As per the simulation result based on Average jitter, Throughput; SLEACH gives highest throughput but it performed the worst in case of average jitter. Best performance is shown by DSDV as average jitter, because DSDV is a proactive protocol i.e. all routing information are already stored in table. Overall, when comparing the routing throughput for each protocols, SLEACH has the best performance and DSDV has lowest throughput.

From the performance evaluation, it can be concluded that in low network size; LEACH gives highest average end-to-end delay but it gives poor performance for PDF and packet loss.

As it can be seen, SLEACH is uniform in height network in size in terms of average end-to-end delay but it gives best for PDF and packet loss. Overall, SLEACH performs much better if we take as terms PDF and packet loss. As it has least packet loss throughout.

In case of high network size; DSDV gives the highest average end-to-end delay but it gives poor performance for packet loss and PDF.

As a result of our studies, we concluded that the secure hierarchical routing protocol SLEACH indicate a better performance in terms of throughput. Besides, SLEACH performs much better PDF and packet loss with increasing number of mobile nodes. However, SLEACH outperforms LEACH and DSDV in terms of all the five metrics because it is quite efficient, and preserves the structure of the original LEACH, including its ability to carry out data fusion.

In future work, we plan to design a suitable secure routing protocol for WSNs that gives stable performance under different network conditions.

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