



## ENERGY EFFICIENT NODE DISJOINT MULTIPATH ROUTING TO IMPROVE WIRELESS SENSOR NETWORK LIFETIME

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### ABSTRACT

Some of the major challenges confronting wireless sensor networks are usually associated with scarcity of energy and resource limitations. In order to achieve efficient utilization of energy and increase the operational lifetime of the wireless sensor network while at the same time providing consistent packets delivery, energy efficient node disjoint multipath routing was recommended. In our method the node-disjoint multiple paths are discovered from the source node to the sink node. We make efficient utilization of the network paths by intelligently elect the most suitable paths for packet transmissions based on path cost calculation. The path cost calculation considers the number of hops, minimum energy node in the path and latency rate, As a result the best paths will select based on latest path cost. The structure of the control messages were shown in different categories. The fragmentation of data packets on node-disjoint multipath were also set-up through the network. Results through simulations investigated explains how EENDM accomplished better outcomes than DD and also N-1 multipath routing technique when compared with the benchmarks lifetime of network, control message overhead, consumption of energy node, Packet delivery ratio, and average packet delay.

**Keywords:** *Wireless Sensor Networks, Multipath Routing, Energy Efficient, Node Disjoint*

### 1. INTRODUCTION

A wireless sensor network (WSN) is a specific group of wireless Ad-Hoc networks in which hundreds or thousands of sensor nodes are collaborate together to monitor a remote site or to precisely measure a physical phenomenon from the environment. The sensor nodes constituting the network are battery-powered devices with limited energy, storage and computation capability [1]. The operations of routing in wireless sensor networks is indeed a complicated issue because it have unique features that largely varies from other types of networks such as MANET(mobile ad-hoc network), wired and wireless network. In view of these varying unique features, recent years have witnessed numerous routing procedures being developed and recommended [2, 3]. There are various schemes of routing that are categorized on what type of operation such as protocols that is normally based on negotiation, or protocol based on query, or protocol based on QoS and also protocol based on multipath. Some benefits of these

protocols includes, for instance, negotiation based protocols have the capability to eradicate redundant data, this process is done during the message exchange by including high level data descriptors. The routing protocol which begins the sink node initial the communication through the transmission of query data over the network are the query based protocols. In the case of protocol based on QoS, the sensor nodes are permitted to make a tradeoff comprising of the two factors namely consumption of energy and certain QoS metrics so that the before the sink node receive the data being transmitted [4]. The last protocol is multipath based routing, operates by not using only one path to send packet but instead several multiple paths, and the advantage of this approach is to increase reliability and robustness through enhance network performances. Most multipath routing protocols always attempts setting up numerous pair of multiple paths from source and destination for data transfer. And because of the protocol effectiveness, in recent years lot of research have been conducted on multipath routing [5, 6]. The rationale behind



the investigation of classical multipath routing are, firstly for load balancing; because traffics emanating from the source to destination are distributed over several pair of multiple node disjoint paths. Secondly the delivery of reliable data is guaranteed through multipath routing. These procedures through multipath allow for several duplicate packets to be transmitted besides various paths, so more robust to path failures. Wireless sensor network applied these types of operations for multipath routing. In multipath routing load balancing is very essential because of it has the ability to distribute the utilization of energy over several nodes leading to prolong network lifetime. Whenever the Duplicating data delivery are sent through multiple paths, the tracing of surveillance applications is immensely enhanced and is more precise at the expense of extra energy cost [6, 7].

## 2. RELEATED WORK

In wireless sensor networks routing is an essential technique for discovering multiple paths, so in the past years, apart from the numerous recommendations being made, it has also generated a lot of attention from researchers. Generally multipath routing covers a broader research area [2] so to fulfill the objective, the research highlighted on specific areas only which are related to our proposed scheme. Directed Diffusion (DD) is among the oldest multipath routing protocol recommended [8] because it is based on data-centric routing, which every communication must be for a named data. Most sensor nodes are normally application aware and maintained an interest cache. The advantage of this approach makes is to ensure that diffusion attains energy efficiency, and this is done by choosing the most suitable paths, caching and before being transmitted to the network, the data is processed. Though DD is a good routing protocol, there are some drawbacks such as interest broadcasting and path reinforcement that generates lot of energy consumption during control traffic and usage. In [9] Low Interference Energy Efficient Multipath Routing (LIEMRO) was essentially proposed to enhance the packet delivery ratio, lifetime, and latency throughout multiple interference-minimized node disjoint paths also it considers a load balancing algorithm in order to spread the source node traffic through multiple paths reliant on relative quality of each path. Some researchers have recommended a protocol known as N-to-1 multipath routing which has the ability to discover several node-disjoint paths through the sink and a

source node. The sink act as root, with the nodes being organizes to be a spanning tree structure [10]. To discover the multipath, the protocol operates through traversing the tree. The dissemination of traffic is implemented by the multiple paths which contribute to effective data transmission in terms of enhanced reliability and data security. The drawbacks of N-to-1 routing protocol that it does not take into consideration the node's energy level. Dissemination of traffic is another issue since the protocol is deprived of an efficient load balancing properties that can spread traffic effectively through utmost energy utilization. There have been several efficient multipath routing protocols in WSN having multiple sink nodes [11] that have been recommended by researchers. Whenever the protocol intends to communicate with the next hop, the cost function is used, representing the function of residual energy and hop count respectively. Once the protocol initialization is completed, only then the path construction phase begins. Then the source node unicast a route request message which will be received by all neighbors. On the other hand, multiple routes construction and maintenance are known to be costly in term of energy because it is usually associated with high control overhead. In recent times, AEMRP-LB- (An Adaptive Energy-aware Multi-path Routing Protocol with Load Balance for wireless sensor networks) has been recommending in [12]. AEMRP-LB highlight an idea called direction-angle to address the lack of broadcast and takes into account the tradeoff among the hop count and the residual energy to create multiple node- disjoint paths. The traffic load is balanced through the elected paths by employing a weighted traffic scheduling algorithm considering their transmitting capacity, and then AEMRP-LB employs the advantages of Multi-path Source Routing to report the acquired data as saving the storage resources and computing of the sensors. The authors in [13] designed Energy-Efficient Multi-Path Routing in Wireless Sensor Networks which is a reactive routing protocol. In the network, each node may serve as a source and a sink node in the same time. The route discovery mechanism provides the multiple paths among source and destination by using shared nodes in the search tree and query tree. The amount of control messages employed in the multiple route construction is consider high, because in order to construct query tree and search tree, query messages and search messages are to be broadcast in the network. These messages are sent from the source nodes and sink respectively. To achieve energy efficiency in routing protocols can be done normally through

decreasing the overheads associated with control traffic at the time of routes construction and path maintenance phases respectively and also the necessity to choose the most suitable routes with minimal energy usage by applying the best cost function. For the research, our recommendation entails attempts at reducing consumption of energy by way of disseminating and balancing the load over multipath paths. To construct the multiple paths, this is achieved by applying a procedure known as the cost function which is founded on several conditions namely number of hop, path with the least energy node and latency ratio. The following sections illustrate our recommendations more specifically.

### 3. DESECRATION OF EENDM SCHEME

In this section, we first define some assumptions. Then, we provide the details of EENDM. The EENDM is made of four phases such as, neighbour discovery process phase, multipath constructions phase, data disseminating and maintenance phase.

#### 3.1 Assumptions

Generally multipath network are grouped into two categories, disjoint and braided models. The model chosen in our method primarily placed emphasis on disjoint model. The figure 4.1 below explains a specific node-disjoint multipath routing model that is inclusive of a source node, a sink node, as well as several intermediate nodes. The assumption proposed was that, every sensory data being generated at the various source nodes are transmitted to a central point, that is, data processing centre. In the figure 1 below is a description of several node-disjoint paths that are not the common node or shows any link between the routes being discovered. Consequently, if there is any node or failures associated with that particular link in a pair of node-disjoint paths, only that route is influenced consisting of the failure node. Node-disjoint paths are more useful than partially disjoint and link-disjoint due to this class of path disjointedness delivers much greater aggregated network resources.

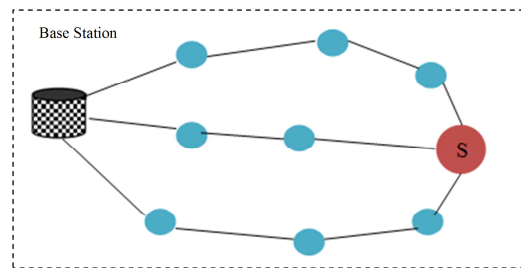


Figure 1: Network Model

In our proposed method, our assumptions were that  $N$  identical storage, process and communication abilities which are dispersed randomly across a specific area. Only a sink node own powerful resources to communicate with the sensor nodes or achieve any tasks. Every sensor node has a radio transmitter that comprises of constant transmission range of  $R$ , with the assumption that the network is dense and connected. For instance, when a random set of nodes is specified, data can be transmitted from a node to the next node through a multi-hop method. Due to the existence of multiple paths among a set of nodes, every node is allocated (ID) which is called a unique identifier. The nodes location unaware, that is, there is no GPS (Global Positioning System) equipped device. Another assumption proposed was, the sensor node and sink is immobile, which simply implies, support for mobility is non-existence and it possesses enough battery for providing sensing and transmission functions. Usually the battery has limited life span and cannot be replaced or re-energized. Moreover, the transmitter power of the sensor node is constant for data transmission and reception respectively. At every time period, a sensor node denotes  $n$ ,  $n \in 1, 2, \dots, N$ , which is capable to obtain the remaining energy level  $e_n$ , remaining description of the its power battery. As soon as incident happens or a stimulus is noticed, the neighbouring nodes initially broadcast the information and choose one of them to be the source node. The theory assumption implies a specific path comprising of  $L$  nodes and in that scenario  $L < N$  is denoted as a set of nodes which conveyed the generated data through the source node  $S$  to the intended destination, the sink node  $Y$ . The assumption proposed earlier on, describing the density of the network, there is still the probability of having multiple paths among the source node  $S$  and the sink node  $Y$ . For this reason, the likelihood of using multipath routing rather than single route, with the proposition that the multiple routes being utilized are disjoint. For instance, the route  $Z$ , which is made of  $L$  nodes, and as well as route  $B$ , comprising of  $R$  nodes, illustrates two

groups jointly uniquely different from each other excluding the source node S and the sink node Y respectively. To choose the best path for path construction phase, the path cost function is used once the REEQ reach to sink node. The path cost computation is highlight through the following equation:

$$P_c = E + H + D \quad (1)$$

With H representing the number of hops to the sink node y when select next hop; E representing the minimum energy node in the path and D is signifying end-to-end delay. Therefore the path cost function takes the minimum node energy in the path, the number of hop i.e. distance to sink and end-to-end delay from the sink into consideration. The selection benchmark used to choose the best path in our proposed node disjoint multipath method is the path cost function, with the notion of employing in our proposed method. In definition the path Z is comprise of L nodes consists (L-1) of links, the path cost  $P_Z$  denotes the calculation of specific link costs  $l_u (u+1)$  along with the path. This is illustrated below as:

$$P_Z = l_1 + l_2 + \dots + l_L (l+1) = \sum_{u=1}^{L-1} l_{u(u+1)} \quad (2)$$

### 3.2 Energy Model

At Figure 2 illustration below, represents consumption of energy fundamental features in wireless sensor networks that was recommended by (Estrin, 2002), and it was later acknowledged to be the regulatory ideologies for sensor networks in terms of energy consumption.

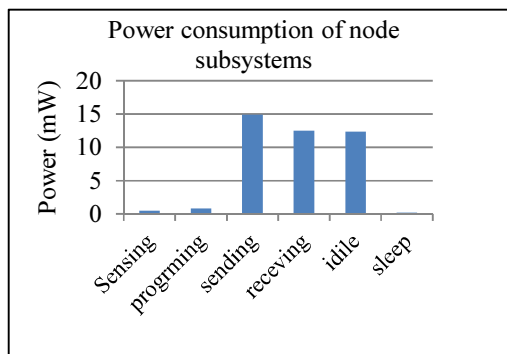


Figure 2: Energy Consumption Source

In figure 2 illustrations shows the elements consuming higher energy includes sending, receiving, and idling and the least amount of energy

consumptions are sensing, programming, and sleeping. For the research work sensing energy consumption, programming and also sleeping were not taken into consideration for subsequent studies. The consumption of idle energy is usually spent by the nodes in order to avert a collision, which is representing the MAC layer operations, and also to ensure the MAC layer energy consumption cannot have adverse influences on our energy studies in the network layer. Although one of the main purpose is to propose an energy efficient multipath method that is confined to the network layer and so we do not focus on idle energy consumption. Thus, the sending energy  $E_{TX} (k,d)$  and the receiving energy  $E_{RX} (k)$  was the central point of reference, therefore the overall consumption of energy is regarded to be the energy consumption of sending and receiving a packet multiplied by the total times transmission. For wireless networks, whenever nodes are positioned within the transmission range of nodes being transmitting, the prospect of receiving packets for free is higher even when the nodes are not part of it and not on duty. This occurrence is known to be the transmission properties of wireless sensor networks. Therefore, the computation of total energy consumption is

$$E_{MULT} = (E_{TX} (k, d) + N \times (E_{RX} (k)) \times NR \quad (3)$$

where N denotes the sum of nodes, NR signifies the transmission times in the network, k stands for the packet size, and d is the distance between two nodes. For the purpose of argument, the assumption envisages was that, every sensor nodes designated with the similar transmission radius. In order to transmit a “k-bit message” at a distance d, the energy dissipation is given by the equation as:

$$E_{TX} (k, d) = k \times E_{txElec} + k \times \epsilon_{amp} \times d^2 \quad (4)$$

where  $E_{txElec}$  signifies the energy for transmitting a single bit data,  $\epsilon_{amp}$  denotes the signal amplifier value. Besides, the energy consumption of receiving is

$$E_{RX} (k) = k \times E_{rxElec} \quad (5)$$

In equation (5),  $E_{rxElec}$  represents the energy consumption of receiving one bit data. For ease of use, it is assumed that energy consumption of transmitting a bit is similar to that of receiving one, as illustrated in Equation (6).

$$E_{rxElec} = E_{txElec} = E_{elec} \quad (6)$$

Starting from Equations (4), (5), and (6), after computations, the result of aggregate energy consumption is attained. The amplification factor for the transmit electronics is  $\epsilon_{amp} = 100$  pj/bit/m<sup>2</sup>



and the energy cost of operating transmitter and receiver electronics is  $E_{elec} = 50$  nJ/bit.

### 3.3 Neighbour Discovery Process Phase

mseque	mtype	sender ID	Node Type	Hop count	forward node ID	Forward Energylev
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mseque: message sequence  
 mtype: message type ( hello message)  
 sender ID: Sender's node id  
 node type: sink or source  
 hop count: hop distance of the message from its originator; source node hop count=0, then increases at each node.  
 forward node ID: upstream node that forward the message at last hop  
 Forward Energylev: Forwad node residual energy

Figure 3: The Format Of Hello Message

The HELLO beacon is part of exchanged messages among the sensor nodes during neighbour discovery process phase. At Figure 3 above demonstrates the various fields through the HELLO beacon. The message sequence in initial field's indicates a number created by the message originator. The number keeps on increased every time when create a new message. Together with the node ID, message received can be verified when needed. The form of field message signifies information which is known to be HELLO message and furthermore the sender ID field consists of the node ID of originating message. For ease of identification the field of node type indicates if the originating message is a source, a sink or a normal sensor node. The hop count present the message hop distance which relayed through the originating message. The forward node ID comprises the upstream node ID, which relayed the messages at last hop. (because it has the obligation for relaying messages in the previous node). The field of forward node energy level describes the node energy level of the node which transmits message at last hop. If the HELLO beacon reaches and the messages received are first time occurrences, every node creates its node neighbouring table such as the forward node energy level and forward node ID. Subsequently, the node validates if type of node is sink. When this happens, the sender ID is compared to the sink table of the node. Then a new entry is produced in the sink table when needed, along with the hop count refresh only if hop distance is lesser than the value recorder. Then finally, the HELLO beacon originating through the sink node is re-transmitted with the field's forward node ID, hop count and the forward node energy level updated. The algorithm 1 in the figure 5 produces more

elaborate stages in constructing the HELLO message in a sensor node. The selective flooding of HELLO messages coming from the sink assists every node to acknowledge the existence of the sink node and to compute the shortest hop distance to sink node. The completion of the neighbour discovery process phase means every node gets the sink table and also the neighboring node table. Each node will send the sink awareness message to its neighbours as shown in the figure 4.

mesque	mtype	Sender ID	Sink ID	Sink hop
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Figure 4: Sink Awareness Message

#### Algorithm 1 Algorithm to process the HELLO message

- 1: Set tabH: hash table of messages, tabN: table of neighbors, tabS: table of sinks
- 2: Input mseque: message sequence, SrcID: node sender ID, ST: sender node type, h: hop count, Fenergylev: forward energy Level, NID: upstream forward node ID
- 3: IF (mseque, SrcID) exists in tabH
- 4: RETURN
- 5: IF NID exists in tabN
- 6: update the entry (NID, Fenergylev) in tabN
- 7: ELSE
- 8: create new entry (NID, Fenergylev) in tabN
- 9: IF (ST == SINK)
- 10: IF (SrcID exists in tabS)
- 11: IF (h < tabS.SrcID.h)
- 12: tabS. SrcID.h = h
- 13: ELSE
- 14: create new entry (SrcID, h) in tabS
- 15: h = h + 1; NID = current node ID;
- 16: Fenergylev = current node energy level; Nhop= next hop
- 17: broadcast HELLO beacon to the neighbors
- 18: RETURN

Figure 5: Constructing The HELLO Message

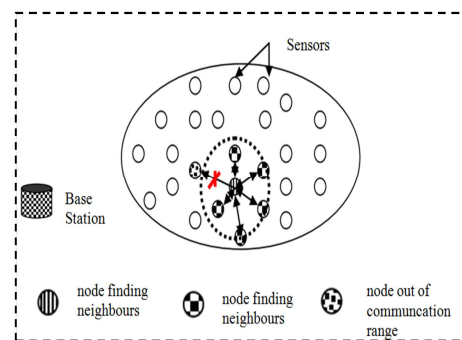


Figure 6: Neighbour Discovery Process

### 3.4 Multipath Construction Phase

The multipath construction phase is started once a pair of nodes senses the incident happens and the chosen source node starts to transmit gathered data to the sink node. As our intention is

to find out node disjoint multiple paths, the RREQ message will send to every node along with distinct route ID by source node. This is further illustrated in figure 8, however, RREQ message cannot all arrive at the destination sink node, and others might drop during the transmission to the intermediate nodes so as to avert paths having to share common nodes (in order to form the node disjoint nodes). The figure 7 below explains the structure of a RREQ message. The fields SrcID and SID specified the node ID of the source and also sink. The field of RID is the route id which is allocated by the source node in order to differentiate among the various routes that lead to the same sink. The remaining of the fields conveys the similar information as contained in control message that was presented.

mseq	mtype	SrcID	SID	RID	Hop count	Min Energy level	Forward node ID	Forward Energylev	TR	Delay
mseq: message sequence mtype: message type SrcID: Source ID SID: Sink ID RID: Route ID Hop count: hop distance of the message from its originator; source node hop count=0, then increases at each node. Min Energy level: minimum energy available for a node at path Forward node ID: upstream node that forward the message at last hop Forward Energylev: Forward node residual energy TR: time receive the message delay: end to end delay of the transmission packet										

Figure 7: The Format Of A RREQ Message

In order to send a message to a specific destination by the source node, the initial step is for the source node to examine its cache to see if there are any available routes to that destination. If none exist, a new route request is created. In order to select the next hop node, the node will choose a neighbour node that has minimum hop count to sink which was introduced in HELLO message. The selected node computes locally the Min energy level, TR and delay. Therefore as shown in the figure 7 the Min Energy level filed will be used later to evaluate the quality of the path. TR field indicating to the time of packet received and the field of Delay indicating to the delay of packet transmission thus the end-to-end delay can be calculated by using the information in RREQ message as the source node transmit RREQ message, and when the RREQ message from the source node is received by the intermediate N1, node N1 will store the time of this event on the field TR1 and forwards it to its best suitable next hop. Therefore when the RREQ message coming from N1 is received by the neighbour node N2, the node N2 will computes the

difference among the TR1 field and the current time TR2 which represents the measured delay of the link between N1 and N2 and it will stores in the delay field. By accumulating this time, the sink node can compute end-to-end delay for each of the available paths.

The feedback information received through the lower layer is then used in the EENDM method. The energy information will provides to network layer by MAC layer and each node have sufficient information concerning its energy availability, The intermediate node after obtaining the RREQ message then compares its available energy with the Min Energy level filed, there will no changes effected when the value in the field is smaller or is equivalent to the node available energy, otherwise, the node's available energy is positioned in the Min Energy level field of the RREQ message. In conclusion, hop count, delay, Min Energy level, forward node ID and forward node energy level is updated by the node before forwarding the RREQ message to the chosen neighbour. So when all RREQ messages received by the sink, the sink will estimate the number of available disjoint paths to the source and the minimum energy available on each of these paths.

There are two conditions for choosing the source of best path. In the first place, neighbouring node should not have elected for another route which connects similar pair of source and sink nodes. And lastly, the select of best path must be the lowest path cost within the entire paths as shown in the equation 7.

$$\text{Path Cost} = E + H + D \quad (7)$$

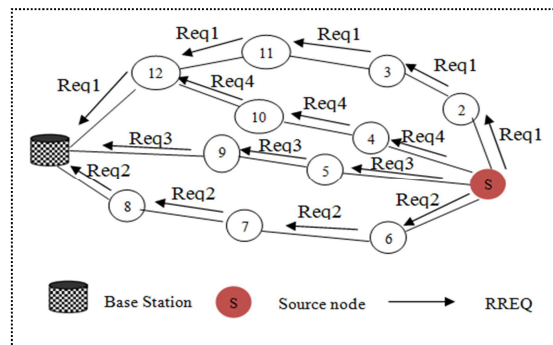


Figure 8: The RREQ Message

As demonstrated above in figure 8, the node 10 relays the message REQ4 to node 12. Therefore, when the node 12 receives another message i.e. REQ1 that come from node 11, the

node 12 will drop it since node 12 has been chosen previously by another route. Whenever a neighbour is chosen, the routing table is updated, and also the table of node neighbours is also updated concurrently. With this set up, future path search is achieved as the node can avoid to chosen a neighbour which have already been taken and used for the route that connects similar pair of source nodes and sink. The Algorithm 2 in the figure 9 elaborates the process of RREQ message through regular intermediate sensor node.

Algorithm 2 Algorithm to process the RREQ message by a regular intermediate node

- 1: Set tabN: table of neighbors, tabR: routing table, nodeS: neighboring node selected as the next hop, MinE: the min energy level
- 2: Input mseq: message sequence, srcID: source ID, skID: sink ID, rID: route ID, h: hop count, NID: forward node ID, Fenergylev: forward node energy, tr1: packet send time, tr2: packet receive time, d: delay
- 3: IF (srcID, skID) not exist in tabR
- 4: create new entry (srcID, skID) in tabR
- 5: ELSE
- 6: update tabR with (srcID, skID, rID)
- 7: nodeS = skID (the REQUEST message is forwarded to the sink node directly)
- 8: ELSE
- 9: WHILE (not reach the end of tabN)
- 10: elect the neighbor node x that has not been elected in the path among srcID and skID with minimum hop count to sink
- 11: E = energy available to the neighbor node x
- 12: IF (E <= MinE)
- 13: update min energy field,
- 14: h=h+1
- 15: delay=tr2-tr1
- 16: ELSE
- 17: keep the min energy (MinE) field not change
- 18: update the entry (hop count, MinE, tr1, tr2, d) in tabR
- 19: point to the next neighboring node in tabN
- 20: send RREQ message to another nodeS
- 21: repeat the steps from 10 to 20 until the RREQ reach to sink
- 22: return

Figure 9: RREQ Message Algorithm

In the case of the sink node, when the RREQ message which was received is treated in a different way. The sink node evaluates and measures the routes by considering the path cost presented in the equation 2. It then chooses three paths with minimum costs and unicasts the RREP message through the selected minimum cost paths. The sink node forwards the route reply messages to the source node as shown in figure 10. In Algorithm 3 in the figure 11, sink node highlights the pseudo-code of the RREP message and how it procedures are being carried out.

srcID	Hop count	Nhop	RID	SID	Min Energy level	delay
srcID: Source ID						
Hop count: distance to sink						
Nhop:next hop						
RID: Route ID						
SID: Sink ID						
FwdID: forward node						
Pcost: path cost						
Min Energy level: minimum energy available for a node at path						
delay: end to end delay of the transmission packet						

Figure 10: Route Reply Message

Algorithm 3 Algorithm to process the RREP message at sink node

- 1: Set tabR: routing table
- 2: Input seq: message sequence, srcID: source id, Nhop: next hop, rID: route ID, skID: sink ID, h: hop count, minenergy: min energy in path, d: delay
- 3: IF (RREQ messages) reaches sink node then
- 4: choose the three latest path cost
- 5: RREP with the three paths to source node with the fields (srcID, RID, h, Nhop, skID, minenergy, d)
- 7: RETURN

Figure 11: Route reply message algorithm

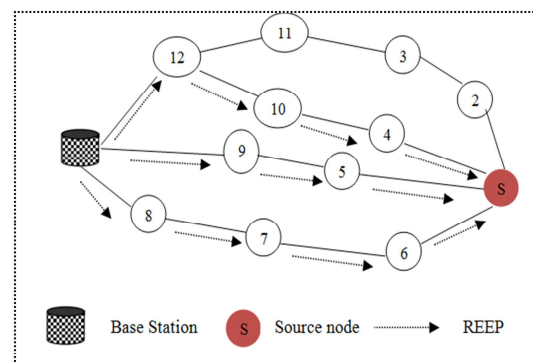


Figure 12: Multipath Selection Process

### 3.5 Data Disseminating Phase

SrcID	SID	Nhop	RID	Seq_Number	Data load
SrcID: source ID					
SID: Sink ID					
Nhop:next hop:the next hop					
RID: Route ID					
Seq_Number: the Sequence number of the Data packet each time it is sent out					
Data load: carry the data					

Figure 13: The Packet Format

When multiple paths have been determined, the source node starts to send data packets to every route by attaching the allocated rates. During the process, the event data and most of the control fields are transported by the data message. The packet format is shown in Figure 13 above contains the source ID, sink ID of the message, next hope, route ID and data load. The Source ID and Sink ID fields represent the packet source node and for the sink node. The data load field is useful for transporting data packets. Accordingly as soon as the path has been selected, the source S can balance its load to existing traffic

on the whole available route. At that moment the source node fragment the packet into k division of sub packets of equal size. Then it transmits the specific k sub packets with K (available) routes. Subsequently in the sink the whole K sub packets were received. At this time, the k sub packets combine together with the sink node and to get original data. We now turn our attention to the description of data splitting in illustration below as follows; assuming there packet having a size 15 data unit (kbit/s) which it transmits through the source to sink node. At the same time, several other nodes are also available among source and sink. As soon as discovery of 3 active routes from source to sink is established in order to transmit data, then the source node fragment the packet size of 15 data unit (kbit/s) into 3 sub packets and every sub packets is made of data comprising of 5 kbit data unit. By using the multiple paths, the data arrives safely to the sink node, therefore the 3 sub packets combine together and recover the full packet efficiently in the sink node. Therefore at figure 14, the source S utilizes multiple paths P1, P2 and P3. The node S transmitting to every routes having equivalent value of rate of data, that is,  $15/3 = 5$  Kbit of data to ensure load balance its current traffic across the whole available route.

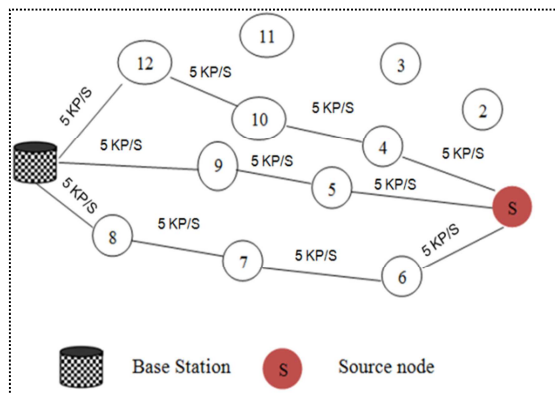


Figure 14: Packet Splitting

### 3.6 CONFIRMATION PACKET

In order to enable confirmation of the receiving the packets, NACK and ACK hybrid method were used. For this method, the sink node receive packet from the node, and the sender node wait awhile for a period of time, if there are both NACK message and the sequence number of the Data packet, then the source node retransmit the same packet again, else the next packet is transmitted. In the method, data is transmitted among the sequence packets which are to be

transmitted, if it is missing. Therefore the sink node in addition with sequence checking of packets received, will notify the sender with the NACK and the sequence number packet ID. for the latest packet can be used as an ACK message, since after transmitting the packets, no additional packets remains to be transmitted, so the packet sequence is compared, which is moreover used to create reliable ACK message. The benefit of using the hybrid method is because of lesser overhead cost, since there is no point in transmitting back and forth reply messages for every packet relayed to its neighbouring node and so consumption of energy is significantly reduced. Furthermore, it is worthy to take notice of how NACK and ACK messages notifies the sender whether confirm or not confirm from the of sink node.

### 3.7 Route Maintenance Phase

At this phase, every node keeps a neighbour table; that comprises of information about a neighbour nodes' energy level. Additionally, once the node fall under the threshold level, there is transmission of a message explaining its inability to participate in routing processes. Every node that is within radio range of failing node update its neighbour table through the deletion of the failing node and then the source begins a new route discovery processes in order to construct new path. The reason for this is to be certain the packet cannot be relayed to a node having inadequate energy, so that packet reach destination safely and not missing. Reliability of data transmission is guaranteed by this approach.

## 4. SIMULATION SETUP

Our method is implemented in ns-2 network simulator which is discrete event-driven and object oriented as the simulation platform. In our simulations, we consider a square region of area  $500\text{m} \times 500\text{m}$ , in which the wireless nodes are deployed randomly. There is one sink node which has no power constraints (sink node is deployed at the center of the area) and one source node in the network. We consider a variety of sensor networks of different sizes 50, 100, 150, 200 and 250. The simulation lasted for 500 sec. Each node has a fixed transmission range of 40 meters. The data packet size is 64 bytes. The rate of packet data transmission is 1 packet per second. We assign each node the same initial energy of 10 J at the beginning of each simulation in order to keep the simulation time within a reasonable time period.



The radio energy model proposed by [14] was used to calculate the energy consumed during transmission and reception of messages. We further introduce an Omni antenna (Antenna Type) to each node and adopt the IEEE 802.11 MAC layer protocol provided in the ns-2 with a bandwidth of 1.6 Mbps and the energy consumptions for transmission and reception are  $E_{elec} = 50$  nJ/bit. We split the data packet in 3 sub-packets and transmit the sub-packets through different paths simultaneously. The energy consumption of transmission and reception is computed according to formula (4) and (5).

Table 1: Parameter Values Used In Simulation For Proposed EENDM

Parameters	Value
Simulation dissemination	500m × 500m
Node placement Node	Random Distribution
Node numbers	50,100,150,200,250
Packet size	64 Bytes
Node initial energy	10 J
Transmission range	40 m
Traffic Type	CBR
Transmit Power	$E_{elec} = 50$ nJ/bit
Receiving Power	$E_{elec} = 50$ nJ/bit
Transmitter Amplifier ( $\epsilon_{amp}$ )	150 pJ/bit/ m <sup>2</sup>
Energy Threshold	0.3 J
MAC layer	IEEE 802.11 (CSMA/CA)
Simulation time	500s

## 5. RESULTS AND DISCUSSION

### 5.1 The Network Lifetime

The lifetime of the network is defined as the time at which the first node failure occurs, that is, the time at which some node's energy reserve is reduced to zero. The main point here is to determine the lifetime for numerous routing schemes. It can be seen that in the figure 15, the lifetime of the network depict a reducing returns anytime the size of the network start to grow bigger. When this trend is compared with some schemes, an increment of 23% 76% is witnessed by the network lifetime with EENDM which is significantly higher than DD and N-1 multipath routing respectively. Also assessing the graph, maximum network lifetime can be

attaining by EENDM. Moreover the lifetime of the network with EENDM worsen more slowly when compared with other routing schemes anytime there is increment in size of network.

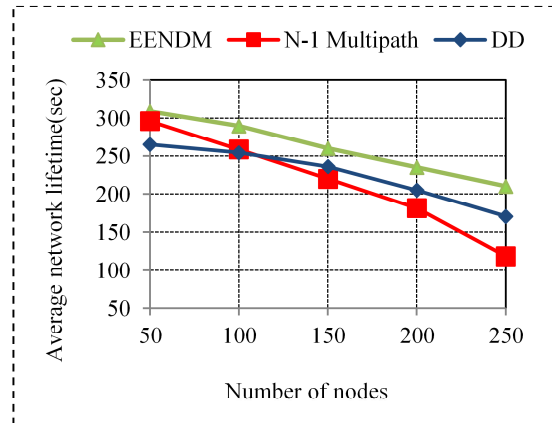


Figure 15: Average Node Lifetime

### 5.2 Average Energy Consumption

The average energy consumption is calculated across the entire topology. It measures the average difference between the initial level of energy and the final level of energy that is left in each node. Energy consumption of the node is the subsequent metric to be conducted. From the figures 16 illustrated below, EENDM energy consumption is much lesser when compared to other routing schemes. Moreover together with Directed Diffusion (DD) performances are much better in comparison with N-1 Multipath routing. EENDM keeps node energy consumption of node at reduced state through increment of network size normally occurs. To illustrate this further, the figure 16 below is an example of showing comparison of directed diffusion and N-1 Multipath routing, 13% and 34% respectively is the enhancement by using EENDM multipath routing anytime the nodes of 50 to 250 increases the size of the network. The energy efficiency of EENDM is more consistent as the results shows from the experiment conducted and the effect of increasing the size of the network shows smaller effects, and comparing it to other routing schemes their performances diminishes when the network size becomes bigger.

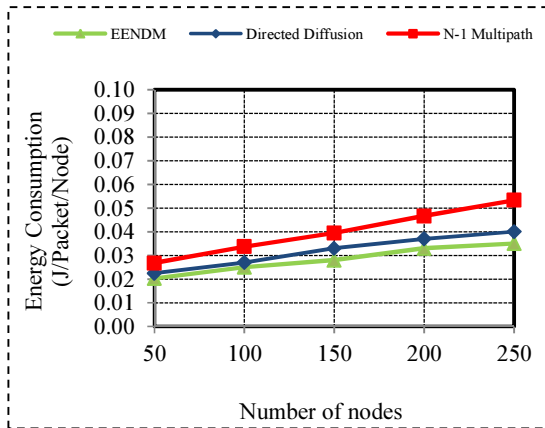


Figure 16: Average Energy Consumption

The initial energy level and the total number of data obtained through the sink were computed on the basis of energy consumption. When assessments of the methods were investigated, EENDM and directed diffusion outperform N-1 Multipath routing. In the case of directed diffusion, its overall performance is attributed to the ability to discover the shortest delays within the paths. Also directed diffusion schemes periodic transmit low rate exploratory through the source, which assist in diverting to other route if it occurs that the current path quality is diminishing to a certain level. In EENDM, using a combination of ACK, ACKN the most efficient way of decreasing consumption of energy. As every packet are not permitted to transmit a response packet when the hybrid scheme is being used moreover the routes being created based on the number of hops and the shorter routes being created, the packet transmission consumes minimum energy.

### 5.3 Average Control Packet

It is the ratio of the average amount of control message treated by the node and the amount of data packets received by the sinks. There are several routing schemes each having distinct technique and if a network is much bigger, it is necessary to needs a greater amount of exchange of control messages so as to be able to find and create more routes. This implies greater amount of energy is consumed and needed during the initial construction phase. Further when the network is a bigger one, it means it will take extensive time distance that separates the sink and the source nodes. There are many intermediate nodes which have to be navigated to enable a data packet to arrive at the destinations sink nodes. Control message overhead of several routing are illustrated in the Figure below, and to

get this value is through computation of two elements, that is, the ratio of the average amount of control message treated by the node and the amount of data packets received by the sinks. Here the control message overhead, portrays directed diffusion as having to expend greater amount of energy during transmission and receiving control messages when compared with another routing schemes, because it needs periodic interest broadcast and path reinforcement which consumes extra energy. In the Figure 17, 79% and 76% is enhancement of EENDM than DD and N-1 multipath routing respectively and showing the EENDM having smaller control message overhead.

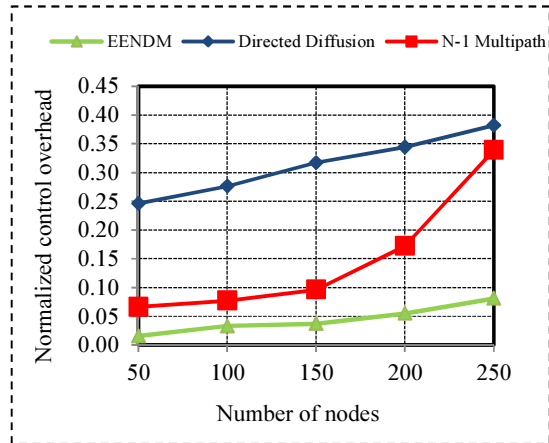


Figure 17: Ratio Of Control Message Overhead And Data Traffic Received

### 5.4 End-to-end Delay

It defines as the average time taken by a data packet to arrive at the destination. Only the data packets that successfully delivered to destinations that counted. The average packet delay is described in the Figure below 18, showing that in comparison with another schemes the EENDM having the shortest delay is a great benefit to the scheme. Through the use of the EENDM, as estimated the data packet is routed through several node-disjoint paths, so with this method, the network congestion and the transmission interferences possibilities are mostly avoided. In the Figure below, 22% and 30% enhancement of EENDM which it has shortest average delay than N-1 multipath and DD respectively.

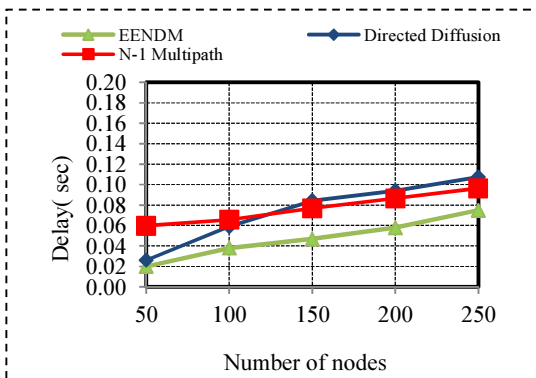


Figure 18: Average Delay

### 5.5 Packet Delivery Ratio

Packet Delivery Ratio is the ratio of the number of delivered data packets to the destination and the number of the sent packets by the source as shown in Equation below. This illustrates the level of delivered data to the destination.

$$PDR = \frac{\sum \text{Number of packet receive}}{\sum \text{Number of packet sent}}$$

The packet delivery ratio is described below in the Figure 19, it is simply the ratio of the number of delivered and transmitted data packet to the destination. It is usually portrays the state of data packets sent to the destination. From the Figure below 19, our proposed EENDM provides enhancement of nearly 32% when compared with directed diffusion, and another 17% when compared with N-1 Multipath. Through the use of dispersion method reliability is attained, implying EENDM performs much better by attaining the best delivery ratio in comparison with other schemes.

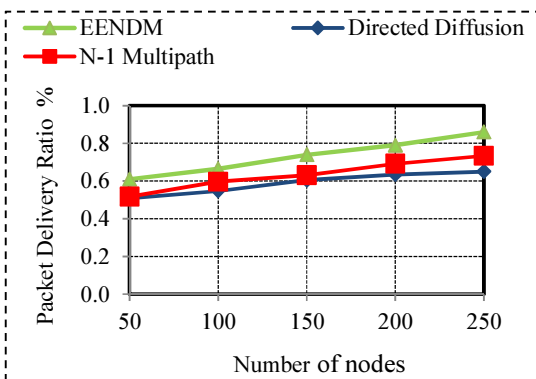


Figure 19: Average Packet Delivery Ratio

## 6. CONCLUSION

In this paper, we proposed an energy efficient node disjoint multipath routing for wireless sensor network in order to provide efficient energy utilization for sensor nodes and maximize the lifetime of the sensor network. These includes some phases such as neighbour discovery process phase, multipath construction phase, data disseminating phase, confirmation packet and route maintenance phase. We have illustrated the format of different control messages. The proposed EENDM endeavors to allocate the traffic to each path simultaneously. An innovative energy efficient node disjoint multipath routing (EENDM) was compared with some routing schemes such as N-1 multipath and directed diffusion, with the proposed EENDM performing better than the others schemes in network lifetime, Average Energy Consumption, Control Packet Overhead, Average Delay, Average Packet Delivery Ratio even when network size increases.

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