ENERGY EFFICIENT CLUSTERING PROTOCOL FOR COLLECTING DATA IN WIRELESS SENSOR NETWORK

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ABSTRACT

Wireless Sensor Network (WSN) is used for collecting the information from the environment. WSN consists of a large number of Sensor Nodes (SN). Each Sensor Nodes in the network are connected by a wireless Channels. All the real time applications of Wireless Sensor Network (WSN) need energy. The nodes in the Wireless sensor networks are battery driven. There are some techniques such as clustering and data aggregation is used for energy efficiency. In the existing Energy Efficient Clustering to Enhanced Lifetime (EECPL) protocol, the reduction in the energy consumption is accomplished by performing data aggregation in the Cluster Members rather than Cluster Heads. Further, ring topology is adopted, in order to enable load balancing in the network. However, it is observed that the delay involved in data transmission is increased which makes it unsuitable for real-time application. In this paper, an Energy Efficient Clustering Protocol is proposed to reduce without compromising Network lifetime. The proposed protocol is compared with the existing EECPL protocol. The performance metrics considered for comparison are average end to end delay, the average energy consumption and network lifetime. NS2 simulation tool is used for the implementation. The proposed protocol outperforms the existing EECPL protocol.

Keywords: Energy Efficient Clustering to Enhanced Lifetime protocol, Cluster Head, Data aggregation, Cluster Member.

1. INTRODUCTION

Wireless Sensor Networks (WSN) are a collection of sensor nodes, each equipped with its own sensors, processor and radio transceiver [6]. Sensor nodes are characterized by limited power supplies, low bandwidth, small memory sizes and limited energy. The primary source of power supply in these nodes is the battery. These sensor nodes can sense and communicate the observed information about the environment to the neighboring nodes or Base Station (BS). The sensor nodes in the WSN will either be static or move within a single WSN. The sensed information are transmitted to the central node for processing. The processed data are sent to the sink node using multi hop communication. The data are remotely accessed by the user [4].

Clustering is a technique by which the sensor nodes are partitioned into groups called clusters. Clustering scheme reduces the communication overhead, reduces the interference among sensor nodes and decreases the overall energy consumption in the network. A Cluster Head (CH) is elected by a decision process. The function of the CH is to collect the data from all the cluster members, aggregate and transmit the information to the BS. CH also participates in the election process when there is a need for change of CH. The concept of cluster based routing is more attractive in WSN as it enables energy-efficient routing. In a hierarchical architecture, higher energy nodes (cluster heads) can be used to process and send the information while low energy nodes can be used to perform the sensing and transmitting the data to the neighbor [11]. Data gathering is defined as the process of gathering sensed data from
The proposed protocol contributes maximum lifespan of the network by reducing the energy consumption in each node and minimizing the overall network delay. It is achieved by an efficient aggregation mechanism which reduces the number of packet transmission. Also by adopting cluster based routing the energy consumption and delay are minimized.

The organization of this paper is as follows. Section- II presents the related work and explains the motivation of the proposed work. Section-III describes the design of the proposed scheme. Section-IV discusses the simulation environment and performance analysis of the proposed protocol. Finally, Section-V deals with the conclusion.

2. RELATED WORK

A number of clustering algorithms have been designed for providing efficient communication. Assistant Opportunistic Routing (As OR) algorithm [1] in which nodes are classified as frame nodes, assistant nodes and unselected nodes. The Source node chooses the assistant nodes. Assistant nodes in the route act as the best possible forwarding nodes. The unselected node does not become a part of the transmission. Frame nodes are selected from the predetermined routes for storing and forwarding the packets.

Average Velocity Based Routing (AVR) [10], in which each node calculates the velocity value for each of its neighbor nodes by considering the distance between the nodes per unit time.

Reliable Energy Efficient Protocol (REEP) [12] which aims at more reliable and energy efficient paths. The energy of each node is compared with the energy threshold value to check whether the node is ready to participate in the transmission process. This provides reliable transmission of data.

Chain Routing with Even Efficient Consumption (CREEC) [5], which aims to maximize fairness in the network. It is achieved by adopting two concepts, namely throwing data directly to the BS and forwarding through a nearby node. CREEC instructs nodes to spend an equal amount of throwing energy $E_{th}$ and forwarding energy $E_{fw}$. K-Hop Overlapping Clustering Algorithm (KOCA) [8] which overcomes the overlapping multi-hop clustering problem. It is achieved by connecting overlapping clusters based on specific degrees.

In the proposed Energy Efficient Clustering protocol to enhance lifetime (EECPL) [3] of wireless sensor network. Initially all nodes broadcast their energy and location information to the BS. The BS runs an algorithm and selects cluster head and cluster sender nodes along with node ID and broadcast this information to the network.

In the proposed Energy Efficient Clustering protocol is to minimize delay without compromising energy efficiency in the network. In the existing EECPL protocol, sensed data is circulated throughout the ring to reach the BS, which in turn increases the energy utilization in the network. Due to the involvement of all the nodes in the data transmission process, the energy consumption in the network is increased. Further increase in bandwidth utilization results due to the allocation of slots to the nodes that are not involved in sensing. The algorithm used for cluster sender election is adopted for Cluster Head rotation in the proposed protocol. This minimizes the overhead on memory utilization. In the existing EECPL protocol the cluster sender forwards data directly to the BS. In many real time applications the BS may not be reachable in a single hop. In the proposed protocol, multi-hop routing is adapted to forward data to the BS. This minimizes the routing overhead. This proposed protocol outperforms the existing EECPL protocol in terms of average end-to-end delay, the average energy consumption and network lifetime.

3. PROPOSED SCHEME

In a ring topology when the node is dead, the sensed information from the preceding nodes will
be lost. The network based on ring topology is highly dependent upon the connectivity between nodes. Star topology works with the central controller called Cluster Head (CH) which performs processing of sensed data. CH receives the data from the common nodes and passes the data to BS. The star topology based network works efficiently even the node is dead. The proposed Energy Efficient Clustering Protocol overcomes the limitations of the existing protocols. In the proposed protocol, CHs alone are involved during the aggregation process that reduces the energy utilization and processing time. The fused data from the CH node is transmitted to the Base station in a multi-hop manner which makes routing efficient. The computational complexity will not be increased even when the network becomes scalable.

3.1. Network Model

The network model consists of N number of nodes that are deployed in an M * M terrain. The nodes that are deployed in the terrain are categorized into Cluster Head (CH), Cluster Members (CM), Base station and Overlapping Nodes (OLN). The assumptions made in the design of the protocol are i) all nodes are randomly distributed in a desert environment with a unique ID.

i) Initially the energy of the nodes is considered equal, thus all nodes are homogeneous and have the same capabilities. ii) Nodes in the network are aware of its own location information.

3.2. Proposed protocol

The Clustering and the routing process in the proposed protocol is a function of parameters such as propagation time to reach the base station (T), residual energy (E) and Node degree (D) that are computed by

\[ F(R,C) = fn(T, E, D) \]

*Time to reach the base station (T):* It is defined as the time taken from the packet to reach the base station from the node.

*Residual Energy (E):* It specifies the remaining energy of a node.

*Node Degree (D):* It is defined as the total number of neighboring nodes of a single sensor node.

\[ D = \text{Size of (Neighbor Table)} \]

\[ E = \text{Total Energy} - \text{Energy Spent} \]

The proposed protocol consists of two phases such as Setup phase and the steady phase.

3.3. Setup Phase

In the setup phase initialization, cluster election and cluster formation are carried out using three modules, namely Initialization module, Cluster Head Election module and Cluster Formation module.

3.3.1 Initialization

After the nodes are deployed, an initialization packet is broadcasted by BS. Then the timer present in each node is switched on. The time field of the initial packet is set as 0 and is considered as an initial time of the packet. The nodes that are within the coverage of BS receive the broadcast packet from the BS. The time at which the packet received is updated in the timer. Each node in the network calculates the propagation time using the above equation.

\[ (T) = (T_c + T_n) + \sum_{i=1}^{n} (T_0 - T(n - i)) \]

Where,

- \( T_c \) Current time in the timer
- \( N \) Number of level

3.3.2 Cluster head election

In this phase, the Cluster Head (CH) nodes are elected based on three metrics namely the propagation time to reach BS, residual energy and node degree. After the completion of initialization phase, each node is aware of its propagation time to reach BS (T).

Each node initiates the neighbor discovery process by broadcasting the Route request (RTR) and wait for the Route reply message (RTR reply) from their neighbor nodes. In the RTR request packet the node encapsulates the information such as propagation time to reach BS (T), residual energy and location information. After the completion of neighbor is discovered, a neighbor table containing information about the neighbors is constructed. The selection of CH from node is executed based on three metrics namely the propagation time taken to reach BS, residual energy and node degree. The node that possesses a low propagation time taken to reach BS, maximum residual energy and a maximum node degree is selected as CH. The advantage of considering propagation time to reach a BS (T) rather than the hop count for making the routing decision is that minimizes latency, energy consumption and provides reliability. The residual energy in the node is considered as one of the parameters to ensure the
network lifetime. Finally, node degree takes into account for creating a dense cluster. Dynamically CH is rotated when the energy falls below the threshold value is shown in fig.1.

3.3.3 Cluster Formation Module

This module involves formation of clusters by selecting cluster members for each cluster. Once the node is determined as a CH, it will send an advertisement packet to their neighboring nodes. The node that receives advertisement packet from more than one CHs is called Overlapping Nodes (OLN). These nodes select their CH based on the distance parameter. After the decision is made, the common node informs the CH by sending a join request.

![Cluster Head Election Module](image)

**Fig. 1 Algorithm for Cluster Head Election**

3.3.4. Steady state phase

In this phase data forwarding is executed. The sensor nodes in the cluster sense the event about an environment. CH receives the sensed information from the cluster members. CH on receiving the sensed information, removes redundancy by an efficient data aggregation scheme. The fused data from the CH is routed to the BS through the next hop CH nodes. If the next hop CH nodes are not present within the range of the CH, then an overlapping node acts as a gateway through which the fused data is forwarded to the BS. The next hop CH is selected based on the function of the propagation time taken to reach BS, residual energy and node degree.

4. PERFORMANCE EVALUATION

This section discusses the simulation results obtained from analyzing the performance of the proposed Energy Efficient Clustering protocol and the existing EECPL protocol. The performance of the proposed system is studied with respect to various metrics such as average end to end delay, the average energy consumption and Network lifetime. It is found that the proposed system outperforms when compared with the existing EECPL protocol. The simulation experiment is carried out in NS 2 with 75 numbers of nodes. The nodes are deployed in a 100 * 100 terrain. Nodes are aware of their locations information and the location of their neighboring nodes. Each node in the scenario is categorized as a cluster member and CH. In cooperation with all the nodes, clusters are formed. A random error model is incorporated in the topology which randomly drops the packets during transmission. All the nodes in the network are considered as homogeneous since they have same transmission range. Among all the nodes in the network, one node is considered as a Base Station (BS). The simulation is carried out at three different intervals of time. The simulation settings for the experiments are given in the Table I.

4.1. Performance Analysis

This section defines the performance metrics that are evaluated during simulation process. After analyzing the performance metrics of both the existing EECPL and proposed System, a comparison is made and the efficient protocol is finalized.

4.1.1 Average End To End Delay

End to End delay in the network is defined as the time taken for the packet to reach from the source node to the destination node. End to End delay is calculated for various clusters by using the equation.

\[
D_{EECPL} = \sum_{i=1}^{n} D_s(i) + \sum_{i=1}^{n} [D_e(i) + D_{tr}(i)] + \sum_{i=1}^{n} D_{pt}(i)
\]

\[
D_{EECPE} = \sum_{i=1}^{n} [D_s(i) + D_{pt}(i)] + (h - l) [D_{pr} + D_q] + CH [D_{pr} + D_q + D_{pt}]
\]
Table 1. Simulation Parameters

<table>
<thead>
<tr>
<th>SIMULATION PARAMETER</th>
<th>VALUE</th>
</tr>
</thead>
<tbody>
<tr>
<td>Node count</td>
<td>75</td>
</tr>
<tr>
<td>Optimal cluster size</td>
<td>10</td>
</tr>
<tr>
<td>Number of clusters</td>
<td>10</td>
</tr>
<tr>
<td>Terrain dimension</td>
<td>100 * 100</td>
</tr>
<tr>
<td>Mobility Model</td>
<td>Random way point model</td>
</tr>
<tr>
<td>Speed of a node</td>
<td>1 m/s</td>
</tr>
<tr>
<td>Propagation Model</td>
<td>TwoRayGround</td>
</tr>
<tr>
<td>Transmission range</td>
<td>20 meters</td>
</tr>
<tr>
<td>Initial Energy</td>
<td>1 Joule</td>
</tr>
<tr>
<td>Transmission Energy</td>
<td>0.000045 Joule</td>
</tr>
<tr>
<td>Reception Energy</td>
<td>0.000024 Joule</td>
</tr>
<tr>
<td>Idle Energy</td>
<td>0.000001 Joule</td>
</tr>
<tr>
<td>Sensing Energy</td>
<td>0.000015 Joule</td>
</tr>
<tr>
<td>Processing Energy</td>
<td>0.000024 Joule</td>
</tr>
</tbody>
</table>

Where, \( m \)-number of Cluster Members, \( n \)-Number of nodes that perform sensing (\( n \leq m \)), \( h \)-Number of hops, \( D_s \)-Sensing delay, \( D_q \)- Queuing delay, \( D_{pr} \)- Processing delay, \( D_{pg} \)- Propagation delay, \( CH \)- Number of Cluster Head \( CH=1 \).

It is observed that as the number of cluster member is increased, the proposed protocol takes a constant delay, whereas the existing EECPL’s delay increases with the increased cluster members. Fig. 2, shows the comparison EECPL and proposed protocol for average end to end delay versus the cluster sizes.

### 4.1.2 Average Energy Consumption

The average energy consumed by a whole network is calculated using the formula:

\[
E_{	ext{SIM}} = \sum_{i=1}^{m} \left[ E_s(i) + E_{Tx}(i) \right] + CH \left[ E_{pr}(i) + n( E_{Rx} ) \right] + h \left[ E_{Tx}(i) + E_{Rx}(i) \right]
\]

Where, \( E_s \)- Energy spent during sensing, \( E_{Tx} \)-Energy spent during Transmission, \( E_{pr} \)-Energy spent during Processing, \( E_{Rx} \). The Fig. 3 depicts that when the number of cluster members is increased, the proposed System reduces the average energy consumed on compared against EECPL.

### 4.1.3 Network Lifetime

The overall network Lifetime is defined as the number of the rounds a node takes to live. In the proposed protocol, the lifetime of the network is extended as the number of rounds is increased when comparing with the existing EECPL protocol. The Fig. 4 shows the comparison of proposed protocol and EECPL for number of rounds versus number of cluster members.

V. CONCLUSIONS

In this paper, a new Energy Efficient Clustering protocol has been proposed to reduce the average energy consumed by the network and provide reliability by reducing the overall delay in the network. The performance of the proposed protocol is compared with the existing protocol. The performance metrics considered for
comparison are average energy consumption, average end to end delay and Network lifetime. On comparing with the existing protocol, the proposed protocol is found to be efficient in terms of average energy consumption, average end to end delay and Network lifetime. The proposed protocol provides reliability even when node failure is encountered in the network ie, when a node becomes faulty.

REFERENCES


