



SMART TRANSMISSION POWER ADJUSTMENT ROUTING BASED ON CONNECTIVITY AND COVERAGE IN MOBILE ADHOC NETWORKS

BHARATHIRAJA.R¹, S.KARTHIK² and V.P. ARUNACHALAM³

¹Research Scholar, Lead Engineer, Department of Quality Assurance FICO,

Bangalore - 560 017, Karnataka, India.

E-mail: ¹bharathirajaphd@gmail.com

²Dean cum Professor and Joint Supervisor, Department of Computer Science Engineering

SNS College of Technology, Sathy Main Road, Coimbatore-641035

³Principal and Research Supervisor, SNS College of Technology, Coimbatore-641035.

ABSTRACT

The network connectivity of Mobile Ad hoc Networks (MANETs) is a multifaceted problem due to the uncertainty of the network topology. Since, wireless links have significantly limited capacity, they are affected by several errors that results in degradation of the received signal and consequently lead to the problem of coverage and connectivity. In this paper, we propose to develop a smart transmission power adjustment routing technique based on connectivity and coverage for MANETs. Initially traffic factor is calculated for each node which is based on the input and output capacity at each node and data generation rate. Then the path which has minimum transmission power and traffic factor is selected for transmission. The proposed technique also provides transmission of data to the node which is outside the coverage area. From the simulation results, we show that the proposed routing technique provides optimal power control in MANET by attaining good throughput and reduced energy consumption.

Keywords: *Mobile Ad hoc Networks (MANETs), Quality of Service (QoS), Energy Consumption.*

1. INTRODUCTION

1.1 Mobile Ad hoc Networks (MANET)

Mobile ad hoc networks (MANETs) are made up of mobile devices that use wireless transmission for communication. They can be set up anywhere and at any time because they require neither infrastructure nor central administration. The goal of MANET architecture is to provide communication facilities between end users without any centralized infrastructure. Mobile Ad-Hoc Network (MANET) is a mobile ad hoc network technology that can change locations, adaptive and configure itself on the move using Wi-Fi connection or any other medium to connect to various networks, while some are restricted to local area and others connected to internet. The main principle of MANET is that it can connect to available network nearby through which can connect to internet or to further more network to acquire internet. If A node needs to connect to B node and if the destination node is in the local area

within the range then connection is established to the neighboring network itself without passing on to internet. This enables network topology within the available neighboring network thus reducing congestion in server or internet. [1, 2, 3]

1.2 Applications of MANET

MANETs are useful in tactical applications such as emergency rescue or exploration missions. In addition, it is useful in commercial applications such as conferences, individual museum visits, freely city tours, peer-to-peer applications, e-gaming, etc. [5]

1.3 Quality of Service (QoS) in MANET

Quality of Service (QoS) is the qualitatively or quantitatively defined performance agreement between the service provider and user applications based on the connection requirements. The QoS requirements of a connection are a set of constraints such as bandwidth (available bandwidth) constraint, delay constraint, jitter constraint, loss ratio



constraint, and so on [6]. The actual form of QoS and the QoS parameter to be considered depends upon the specific requirements of an application. [7] [8].

1.4 Connectivity in MANET

MANETs are self-organisable, infrastructure less, wireless, peer-peer, multi hop networks. They adopt distributed control in providing connectivity from the source to the destination. Therefore the mobile units themselves need to take the responsibility of discovering its nearest neighbors who are ready to route data packets to the destination. Co-operation among all the mobile nodes is very essential in such cases. Typical applications of these networks are outdoor events such as conferences, concerts and festivals, places with no network infrastructure, outdoor emergencies and natural disasters and military operations. [9]

1.5 Coverage in MANET

MANET enables wireless communications between participating mobile nodes without the assistance of any base station. The two nodes which are not in each other transmission range calls for a supporting intermediate node that relays the message and sets up communication. Further the broadcast operation plays an important role in the MANETs by the way of radio transmission. The challenges may be tackled by selecting an ideal error free fully coverage environment with high transmission delivery ratio, forwarding node. [10]

1.6 Issues of Coverage and Connectivity

Connectivity with mobility is in great demand and the following describes the issues related to coverage and connectivity. The network connectivity of Mobile Ad hoc Networks (MANETs) is a multifaceted problem due to the uncertainty of the network topology. [11]

Nowadays, there is a huge increase of handled devices. Laptops, mobile phones and PDAs take an important place in the everyday life. Hence, the challenge is now to make all these devices communicate together in order to build a network. [12]

Since, wireless links have a significantly lower capacity than the wired ones; they are affected by several error sources that result in degradation of the received signal and consequently lead to the problem of coverage and connectivity [12]. The process of maintaining coverage and connectivity incurs more energy. [9]

1.7 Problem and Proposed Work

There are many different paths to transmit the data packet from source to destination. Many works have been done for finding the shortest path, enhancing the power-level, dividing the coverage area into sectors, adding some more hardware to have a probability of more paths, scaling the power level to overcome noise interference level. But no work has been done to choose an alternative path which is not the shortest path still; it has a probability of transmitting the data in better energy level so far. Choosing an alternative path which is nearly equal to the shortest path having a comparative lower traffic intensity and a lower probability of collision of data packets will lead the data-packet transmission to a rapid and safe manner.

In this paper, we propose to develop a routing protocol using smart transmission power adjustment technique based on connectivity and coverage for MANETs.

2. RELATED WORK

Jishan Mehedi and Mrinal Kanti Naskar [13] has proposed a fuzzy-based distributed algorithm to maintain connected MANET considering freeway mobility model. According to the algorithm, each node will control itself in a way that it can maintain its connectivity with other nodes. In this approach each node is enabled with a Global Positioning System (GPS) receiver. Through GPS each and every node is getting its position and velocity. After getting the information all the nodes in a network transmit their position and velocity information periodically. Obtaining information from all other nodes, each node will decide its own velocity to maintain connectivity. Moreover, faults to a particular node have also been considered in this algorithm.

S.Smys and G.Josemin Bala [14] have introduced a connection balanced routing technique in mobile ad-hoc networks (MANETs). Their technique utilized the virtual backbone (VB) update messages. VB architecture is familiarly used to alleviate broadcast storm problem in wireless networks. To overcome the connection overhead problem, they have proposed a localized algorithm to support reducing the number of connection and maintain these connections by nearby VB nodes or identify the new VB for maintain the k-connections.

Zhu Han et al [15] have introduced a method of how to utilize UAVs to improve the network

connectivity of a MANET. In this method four types of connectivity are defined: global message, worst case, network bisection, and k-connectivity. The method is formulated for the deployment and movement problems for the UAV and developed adaptive algorithms to provide a simple solution as well as good performance. By providing a theoretical analysis for a simple two-node one-UAV case, they demonstrated that the addition of the UAV provided an improvement in global message connectivity of 240%. By this method, the network bisection and k-connectivity are also improved by the addition of a UAV to the network.

Saleem Sheik Aalam and Dr.T.Arull Doss Albert Victorie [16] have proposed CP-AOMDV, Coverage Prediction Adaptive Routing in multi-path on Demand Mobile Ad Hoc Networks. CP-AOMDV tries to prevent link failures by estimating the routes using prediction of the coverage area. The key factor in CP-AOMDV design was to calculate the probabilistic coverage area at each node. In CP-AOMDV the routing overhead was reduced compared with AOMDV routing protocol. In CP-AOMDV, all the intermediate nodes always update the coverage information through the coverage prediction message.

3 PROPOSED SCHEME

3.1 Overview

In this paper, we propose to develop a routing protocol using smart transmission power adjustment technique based on connectivity and coverage for MANETs. Initially traffic intensity is calculated for each node. For calculation of traffic intensity we take the factors input and output capacity, buffer power at each node and data generation signal. Each node within a certain range has the capability of transmitting the data to a maximum distance. Each node should take their decision in choosing the data transition path. So every node maintains a database which is tracking the activities of different paths so that it is easy to take the routing decision at different times.

3.2 Calculation of Traffic Factor (TF)

For calculation of traffic factor at every node at different time intervals, we use this formula

$$\text{Traffic Factor (TF)}(t) = \frac{op}{ip + dg} \quad (1)$$

Where op=output capacity

Ip= number of input packets at a time t,

dg= data generation rate(kbps) required at time t,

Traffic Factor is calculated for regular time interval. The interval should be in milliseconds. The traffic factors are changed into a new level which is identical with the optimal power level. After modification we can add up the optimum power value and traffic factor to have the final result.

3.3 Estimation of Output Capacity

To find the available o/p capacity we consider two factors: available bandwidth and bandwidth required to pass one signal. Different type of signal requires different bandwidth. But in our method, we assume that all signals are identical.

$$OP = BW_{\text{avail}} / BW_{\text{req}} \quad (2)$$

where OP = output capacity

BW_{avail} =available bandwidth

BW_{req} = bandwidth required for one signal

So output capacity is directly proportional to available bandwidth.

3.4 Effect of Traffic Factor on Inter Symbol Interference (ISI)



Figure 1. Shows ISI At Different Power Factor Levels

According to the equation-1 the traffic factor is inversely proportional to the summation of i/p and data generation rate. So the pressure on the output increases when the pressure of the transmitting signal increases. The above figure clears that, when the number of signal increases in a channel of certain bandwidth, the ISI is increasing.

3.5 Determination of Optimum Path

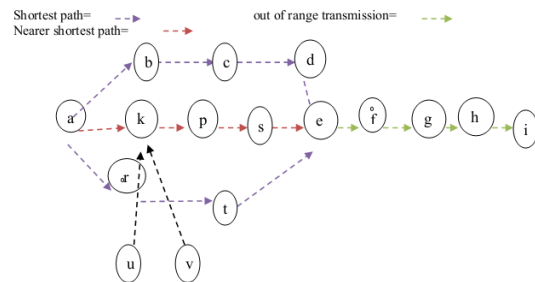


Figure 2 Showing The Connectivity Of Nodes

Consider figure 2. In this case we can consider node 'a' wants to transmit its data packet to a different node. Node 'a' can transmit the data node only to the 4th node that is 'e' because it can have the maximum power range to that level only.



Let us assume that the shortest path is a-k-p-s-e. Since the data packets of nodes ‘u’ and ‘v’ also pass through the intermediate node ‘k’, the inter symbol interference (ISI) is high at node k.

But there are two other paths to reach at point ‘e’, namely, a-b-c-d-e and a-r-t-e. Although these paths are not shortest; due to less traffic it can use a higher data generation rate in a lower power level to transmit the data. The ISI can be measured from the traffic factor since it is directly proportional to the ISI. Hence optimum path can be selected based on the traffic factor and power level.

Node ‘a’ cannot transfer data packets to node ‘h’, directly since it is out of coverage. It has to transmit the data through the end point, which is node ‘e’.

Here ‘e’ has to forward the data. When ‘a’ wants to send the data to ‘h’, it generates a data packet keeping a flag field whose value is set to 1. The flag field indicates the data is modifiable at the end points. Since ‘e’ is the end point for ‘a’, ‘a’ sends the data to ‘e’ keeping the flag 1. ‘e’ finds that ‘h’ is reachable from it. Hence ‘e’ forwards the data to ‘h’ and sets the flag 0.

To choose the path the node uses the formula
$$\min \{ \max \{ \text{required transmission power} + \text{traffic factors} \} \}$$
 of different paths (3)

3.6 Tables Maintained At Each Node

The maintained data table at each node is given as follow

Table 1. Table Maintained At Nodes For Packet Sent From ‘A’ To ‘E’

Node ID	Maximum data generation according to existing power calculation	Summation of traffic factors till next node	Data generation rate + TF (where TF is converted in to identical of data generation)	Selected path
b				
k				
r				

Data packet structure

Table 2. Data Packet Structure Flows In The Network

sender	data	flag
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The figure3 shows the data packet is carrying a sender id data and flag to indicate permission.

The data packet send from a to e is given below. Here the flag is one.

Table 3. Data Packet From A To E

A’s id	data	Flag=1
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The data packet send from e to h is given below. Here the flag is 0.

Table 4. Data Packet Flow From E To H

A’s id	data	Flag=0
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3.7 Algorithm

Phase-1 (Transmission within coverage range)

1. Get the available bandwidth at each time interval T_i
2. Calculate the output capacity (OP) of the node.
3. Get the numbers of data packets (IP) trying to pass through a node N_j at time T_i
4. Calculate the data packet generation rate (data generation rate= no of data packet/unit time) at time T_i

5. Calculate the traffic factor of node N_j using (2).
6. Obtain the traffic factors of the next nodes through which the sender can transmit the data to the destination.
7. Update its data table of by N_j getting traffic factor and maximum power range to the different nodes.
8. Find the appropriate path which is the minimum of summation of identical traffic factor and minimum of the summation of maximum powers required to transmit the data packets and conform it for the data transmission.
9. Generate the data packet in decided power level and transmit it through chosen path.
10. Transmit the traffic factor to other nodes. So that other nodes can also choose their data transmission paths.

Phase-2 (Transmission out of coverage range)

1. Transmit the message to the node which is the maximum distance to which the sender can transmit the message in the above given procedure.
2. Keep the flag value at 1 so it is indicating that end node can modify it.
3. After getting the message, the end node regenerates the message by checking the required node is available or not.

4. If the node is available, set the flag 0 and keep all other field as same it was and send to the required node. It is also following the phase one procedure.
5. If it can not find the node availability in its range, then follow the step-1 of phase 2'.

Transmit Power	0.660 w
Receiving Power	0.395 w
Idle Power	0.035 w
Initial Energy	10.3 J
Transmission Range	150,200,250 and 300 m
CBR rate	100,150,200 and 250kb

3.8 Advantages

A smart algorithm is designed to detect the path according to the transmission power and traffic interference which has the following advantages:

- No need to increase the power to a greater amount although the ISI increase at single node.
- Collision is decreased to a lower possibility without impact of the base station.
- As high speed processors are available, computations will not be an overhead.
- It has been specially focused decreasing the collision with an alternative path. So the traffic and average generating power is decreased.
- Dynamic selection of path leads more paths to available.
- We get a better connectivity and coverage.

4. SIMULATION RESULTS

4.1 Simulation Parameters

We evaluate our Smart Transmission Power Adjustment (STPA) technique through Network simulator (NS-2) [18]. We use a square region of 500 x 500 sqm, in which nodes are placed using a uniform distribution. The number of nodes is varied as 50,100,150 and 200. We assign the power levels of the nodes such that the transmission range of the nodes varies from 250 meters to 400meters. We have modified the standard 802.11 CSMA MAC protocol to include the adaptive power control technique. The simulated traffic is Constant Bit Rate (CBR). We assumed that nodes have global knowledge of the network topology for adjusting their transmission power and no control packets and related overhead were included.

The following table summarizes the simulation parameters used

Table 5. Simulation Settings

No. of Nodes	50 and 200.
Area Size	500 X 500
Mac	Modified 802.11
Simulation Time	25 sec
Traffic Source	CBR
Packet Size	500

4.2 Performance Metrics

We compare the performance of our proposed STPA method with “Power Control in Wireless Ad Hoc Networks for Energy Efficient Routing with Capacity Maximization” (PCEER) protocol [17]. We evaluate mainly the performance according to the following metrics:

Packet Delivery Ratio: It is the total number of packets received by the receiver during the transmission.

Average end-to-end delay: The end-to-end-delay is averaged over all surviving data packets from the sources to the destinations.

Average Energy Consumption: The average energy consumed by the nodes in receiving and sending the packets.

A. Based on Transmission Range

In our initial experiment we vary the transmission range as 250,300,350 and 400m for 50 nodes with traffic rate of 100kb.

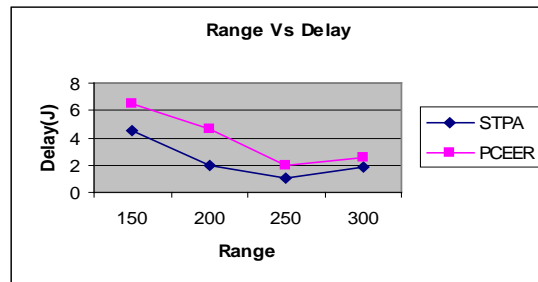


Figure 3: Range Vs Delay

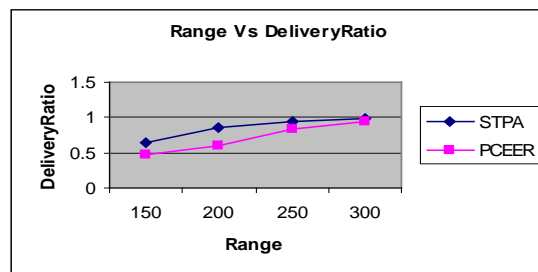


Figure 4: Range Vs Delivery Ratio

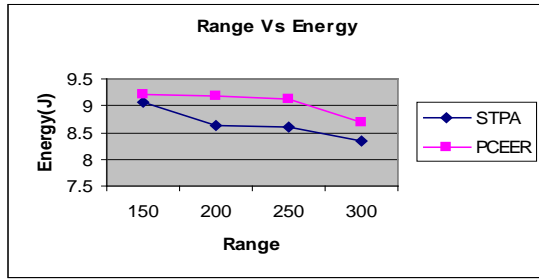


Figure 5: Range Vs Energy

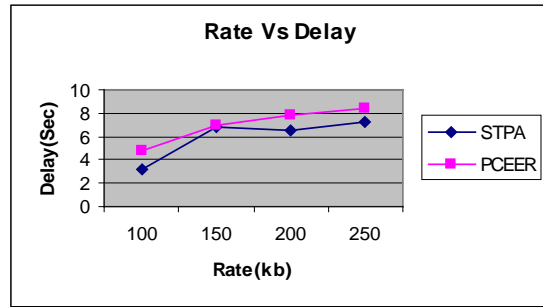


Figure 7: Rate Vs Delay

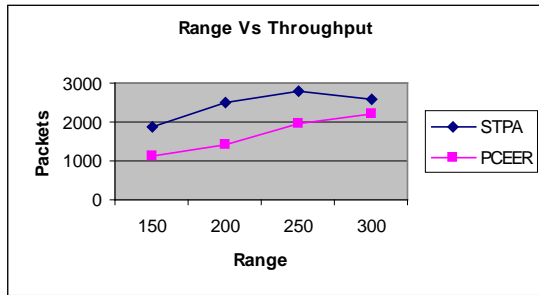


Figure 6: Range Vs Throughput

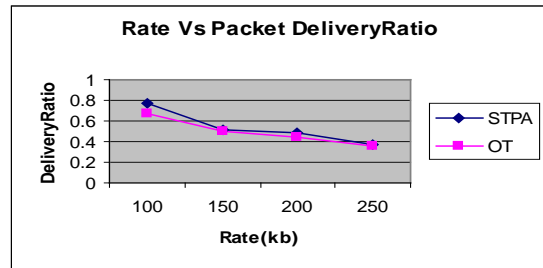


Figure 8: Rate Vs Delivery Ratio

Figure 3 show the average end-to-end delay occurred for both STPA and PCEER approaches when the transmission range is increased. As we can see from the figure, the delay is less for STPA, when compared to PCEER.

Figure 4 show the Packet Delivery ratio occurred for both STPA and PCEER approaches when the transmission range is increased. As we can see from the figure, the delivery ratio is high for STPA, when compared to PCEER.

Figure 5 show the Energy consumption for both STPA and PCEER approaches when the transmission range is increased. As we can see from the figure, the energy consumption is low for STPA, when compared to PCEER.

Figure 6 show the Throughput for both STPA and PCEER approaches when the transmission range is increased. As we can see from the figure, the throughput is more for STPA, when compared to PCEER.

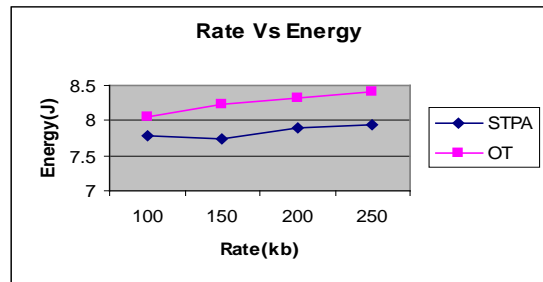


Figure 9: Rate Vs Energy

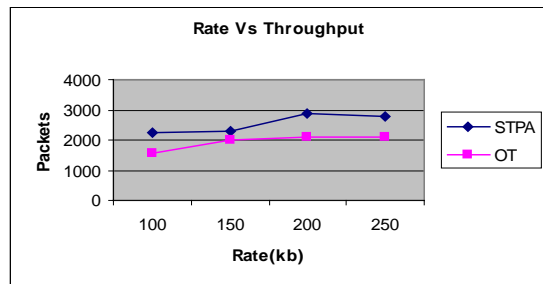


Figure 10: Rate Vs Throughput

B. Based on Traffic Rate

In our second experiment we vary the traffic rate as 100,150,200 and 250kb for 200 nodes with transmission range 250m.

Figure 7 show the average end-to-end delay occurred for both STPA and PCEER approaches when the rate is increased. As we can see from the figure, the delay is less for STPA, when compared to PCEER.

Figure 8 show the Packet Delivery ratio occurred for both STPA and PCEER approaches when the rate is increased. As we can see from the figure, the



delivery ratio is high for STPA, when compared to PCEER.

Figure 9 show the Energy consumption for both APCT and PCEER approaches when the rate is increased. As we can see from the figure, the energy consumption is low for STPA, when compared to PCEER.

Figure 10 show the Throughput for both STPA and PCEER approaches when the rate is increased. As we can see from the figure, the throughput is more for STPA, when compared to PCEER.

6. CONCLUSION

In this paper, we have proposed to develop a smart transmission power adjustment routing technique based on connectivity and coverage for MANETs. Traffic factor is calculated for each node which is based on the factors input and output capacity at each node and data generation rate. Each node contains data tables to store the traffic factor values of its neighbor nodes. During data transmission the nodes with minimum transmission power and traffic factor is selected for forwarding the data. If the destination is not reachable or outside the coverage range it selects an end node for further transmission. From the simulation results, we have shown that the proposed routing technique provides optimal power control in MANET by attaining good throughput and reduced energy consumption.

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