

# REAL-TIME RELIABILITY PREDICTION FOR THE MINE LOGISTICS TRANSPORTATION SYSTEM BASED ON MULTI-PERFORMANCE PARAMETERS DEGENERATION

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## ABSTRACT

The real-time reliability prediction problem of the mine logistics transportation system by applying multi-performance parameter degeneration method was studied. According to monitoring data, by analyzing performance degradation cases and correlation among some performance parameters of the studied system, this paper establishes a new reliability model about time-varying performance degeneration, analyzed in detail this model by the practical example, and gets some practical conclusions. Presented detailed methods and steps can offer the reference for real-time reliability prediction researches of the mine logistics transportation system.

**Keywords:** *Reliability, Real Time Systems, Mine, Transportation, Logistics, Parameter Degeneration*

## 1. INTRODUCTION

With the development of mining industry in our country, the mine bulk logistics transportation system which plays an important role in its developed process also obtained the considerable development and progress. At present, the researches of the mine bulk logistics transportation system mainly focus on logistics distribution and transportation path optimization of the system, and etc, but the reliability research of mine bulk logistics transportation is lack of study. Even if it is researched, the overwhelming majority only carries on the analysis by using the traditional reliability method and only considers the reliability effect of the system operating parameters without considering the effect of the degeneration of system components and equipment performance. The reliability refers to the ability of finishing stipulated function in stipulated conditions and time. The system reliability can be defined as the probability of the successful operation according to the design requirements under the condition of given time interval and environment. Successful operation should not only guarantee that system can work correctly and meet the functional requirements, but also guarantee that the performance of the certain service level.

## 2. THE DETAILED ANALYSIS OF SOME RELATED REFERENCES

Until now, there have been many references studying reliability prediction, reliability estimation or real-time reliability, and many concepts about it have been set up. In [1], a prognostic methodology is applied in this paper to assess its prediction reliability for several degradation scenarios typical of gas turbine performance deterioration. The methodology makes use of the Monte Carlo statistical method<sup>[1]</sup>. In [2], Infinite Impulse Response Locally Recurrent Neural Networks are employed for forecasting failures and predicting the reliability of engineered components and systems<sup>[2]</sup>. In [3], in view of the problem that it is difficult to determine the difference degree of reliability levels between the evaluation object and similar products when using a similar comparison method to predict the reliability level of NC machine tools, a reliability prediction method introducing interval analytic hierarchy process was presented<sup>[3]</sup>. In [4], the problem of choosing the most suitable values for the support vector machines (SVMs) parameters is solved by particle swarm optimization (PSO), a probabilistic approach based on an analogy with the collective motion of biological organisms;

SVM in liaison with PSO is then applied to tackle reliability prediction problems based on time series data of engineered components [4]. The reference [5] proposes an enhanced parenting process, which consists of rigorous mathematical formulations and provides statistical inference on the failure rate of the new product [5]. The reference [6] describes the project to improve the reliability of remotely operated Water Hydraulic Manipulator (WHMAN) utilizing probabilistic methods, this work was done on an FMECA (Failure Methods, Effects and Criticality Analysis) performed on the WHMAN prior to starting this project. Furthermore, additional considerations regarding maintenance regime derived from the results of this project are presented [6]. The reference [7] introduces a probabilistic framework for fatigue life reliability analysis that addresses uncertainties that appear in the mechanical properties, service loads in terms of response-time history signal of a Belgian pave were replicated on a multi-axial spindle-coupled road simulator, a fatigue life probabilistic model of a stub axle was developed using Monte Carlo simulation where the stress range intercept and slope of the fatigue life curve were selected as random variables [7]. In [8], an enhanced Probabilistic Neural Network (PNN) algorithm is proposed where the Gaussian at each labeled point are not assumed to be spherical. Each of the Gaussians has a 'full' covariance matrix instead of simply assuming the Gaussian with a 'spherical' covariance matrix [8]. In [9], a neural network-based model for forecasting reliability was developed; a genetic algorithm was applied for selecting neural network parameters like learning rate ( $\eta$ ) and momentum ( $\mu$ ), the input variables of the neural network model were selected by maximizing the mean entropy value [9]. In [10], the formal statement of the problem of constructing a real-time computing system that has a minimum number of processors is presented, a method for its solution using an iterative scheduling algorithm based on the method of simulated annealing is proposed, and an experimental study of the proposed algorithm is conducted [10]. In [11], a new method was proposed to evaluate reliability and predict lifetime using accelerated degradation data for high-reliability and long-life products, a general modeling approach based on time series for degradation path was analyzed [11].

By detailed analyzing these references, we find that the special studies aiming to real-time reliability prediction for the mine logistics transportation system are scarce. The basic idea of some related references is that the reliability of the

new equipment is stable. However, the aging, wear or tear of the equipment will occur when it has been used for a long time, so the reliability of equipment and systems will gradually decline. Therefore, the real-time assessment and prediction of reliability is very important. In addition, as the time lengthening, the performance of the system continues to degenerate, this process is not only one of the performance parameters of the degradation, but there is more than one performance to occur degradation. In this article, we analyze the performance parameters degradation of the mine bulk logistics transportation system. According to the degradation process of the equipment and system, we analyze the reliability of the system to establish the reliability model based on multi-parameter degradation.

### 3. ESTABLISHING THE NEW RELIABILITY MODEL ABOUT PARAMETER DEGENERATION

The degraded phenomenon due to intrinsic properties is called as performance degradation. At present the research about system reliability method based on the performance degradation often assumes that the system has single parameter degradation. In fact, there are often many performance parameters occurring degradation.

It is assumed that  $y_i(t)$  ( $i = 1, 2, \dots, n$ ) are  $n$  monitored performance parameters in a mine transportation system,  $y(t)$  is the detected performance time-varying function. For studying the system reliability based on multiple performance parameter degradation, firstly we should distinguish whether these performance parameters are independent of each other or not. If they are, so we can look the system as a series system, its reliability  $R(t)$  is

$$\begin{aligned} R(t) &= P\{y_1(t) \leq D_1, y_2(t) \leq D_2, \dots, y_n(t) \leq D_n\} \\ &= P\{y_1(t) \leq D_1\}P\{y_2(t) \leq D_2\} \cdots P\{y_n(t) \leq D_n\} \end{aligned} \quad (1)$$

Where  $y_i(t)$  ( $i = 1, 2, \dots, n$ ) are the detected performance time-varying functions;  $D_i$  ( $i = 1, 2, \dots, n$ ) are the failure threshold of the performance parameters; If these degraded performance parameters are associated with each other, the system reliability is

$$R(t) = P\{y_1(t) \leq D_1\}P\{y_2(t) \leq D_2\} \cdots P\{y_n(t) \leq D_n\}$$

$$= \int_0^{D_n} \cdots \int_0^{D_2} \int_0^{D_1} f(y_1(t), y_2(t), \dots, y_n(t)) dy_n(t) \cdots dy_1(t) \quad (2)$$

The following matrix is used to judge whether the performance parameters are related or not.

$$\begin{bmatrix} \text{var}(y_1(t)) & \text{cov}(y_1(t), y_2(t)) & \cdots & \text{cov}(y_1(t), y_n(t)) \\ \text{cov}(y_2(t), y_1(t)) & \text{var}(y_2(t)) & \cdots & \text{cov}(y_2(t), y_n(t)) \\ \vdots & \vdots & \cdots & \vdots \\ \text{cov}(y_n(t), y_1(t)) & \text{cov}(y_n(t), y_2(t)) & \cdots & \text{var}(y_n(t)) \end{bmatrix} \quad (3)$$

Where  $\text{cov}(y_i(t), y_j(t))$  is the covariance of the time-varying function, If  $\text{cov}(y_i(t), y_j(t)) = 0$ , then the  $i$  performance parameter and the  $j$  performance parameter are not related, else they are related.

In general case, we hypothesizes that the  $n$  degradation parameters obeys normal distribution.

Table 1 The Factual Observation Data Of Three Monitored Performance Parameters

<b>T/ Cycle number</b>	200	400	600	800	11600	11800	12000
<b>Speed (meters/ hour)</b>	104	92	90	92	46.3	42	39
<b>Carriage ability (T/ Square meter)</b>	1.2	1.1	1	0.8	0.82	0.8	0.75
<b>Unit price (Yuan/Kg)</b>	0.22	0.22	0.22	0.21	0.25	0.22	0.21

In order to look for the distribution regularity of above parameters, firstly, we find out the maximum and the minimum value in actual statistical data, divide data into some equal width intervals, and then calculate the frequency number and frequency of data falling into each interval. Take the transportation capacity as an example for distribution analysis, shown as table 2.

Table 2 The Calculated Frequency Number And Frequency In Each Interval

Class limits	Frequency number $f_i$	Frequency $f_i / n$
0.7—0.75	3	0.05
0.75—0.8	4	0.0667
0.8—0.85	7	0.1167
0.85—0.9	9	0.15
0.9—0.95	14	0.2333
0.95—1.0	9	0.15
1.0—1.05	5	0.0167
1.05—1.1	4	0.0667
1.1—1.15	3	0.05
1.15—1.2	2	0.0333

The joint probability density function can be expressed as

$$f(x) = (2\pi)^{-\frac{n}{2}} |\Sigma|^{-\frac{1}{2}} \exp\left[-\frac{1}{2}(X - \mu)^T \Sigma^{-1} (X - \mu)\right] \quad (4)$$

The system reliability can be shown as

$$R(t) = P\{y_1(t) \leq D_1\}P\{y_2(t) \leq D_2\} \cdots P\{y_n(t) \leq D_n\}$$

$$= \int_0^{D_n} \cdots \int_0^{D_2} \int_0^{D_1} f(y_1(t), y_2(t), \dots, y_n(t)) dy_1(t) dy_2(t) \cdots dy_n(t) \quad (5)$$

#### 4. CASE STUDY

This paper chooses the belt conveyor system in a real open pit mine as the research object; we selected three monitored performance parameters including speed, carriage ability, and unit price to be used to predict the real-time reliability, shown as the following table 1.

Then, we can use Excel to draw the histogram distribution diagram. The function of the normal distribution histogram can be assumed as  $N(\mu, \sigma^2)$  from the histogram, Then the probability density function is

$$f(x; \mu, \sigma) = \frac{1}{\sqrt{2\pi}\sigma} e^{-\frac{(x-\mu)^2}{2\sigma^2}} \quad (6)$$

The Likelihood function is

$$L(x_1, x_2, \dots, x_n; \mu, \sigma) = \left(\frac{1}{\sqrt{2\pi}\sigma}\right)^n e^{-\sum (x_i - \mu)^2 / 2\sigma^2} \quad (7)$$

The Logarithmic function is

$$\ln L = \frac{-n}{2} \ln 2\pi - n \ln \sigma - \frac{\sum (x_i - \mu)^2}{2\sigma^2} \quad (8)$$

The Likelihood equations are

$$\frac{\partial \ln L}{\partial \mu} = 0 \quad \frac{\sum (x_i - \mu)}{\sigma^2} = 0 \quad (9)$$

$$\frac{\partial \ln L}{\partial \sigma} = 0 \quad -\frac{n}{\sigma} + \frac{\sum (x_i - \mu)^2}{\sigma^3} = 0 \quad (10)$$

$$\hat{\mu} = \sum x_i / n = \bar{x} \quad \hat{\sigma} = \sqrt{\sum (x_i - \bar{x})^2 / n}$$

$$\mu = 0.92, \quad \sigma = 0.11 \quad (11)$$

Then the performance parameters follow a normal distribution:  $N(0.92, 0.11^2)$ .

Similarly, the distribution of the other parameters is respectively the Normal Distribution  $N(78, 22^2)$ ,  $N(0.22, 0.01^2)$ .

We can obtain the covariance matrix of three performance parameters by the MATLAB software, and also obtain the function curve of performance reliability of this mine transportation system by formula (5) shown as Figure.1.

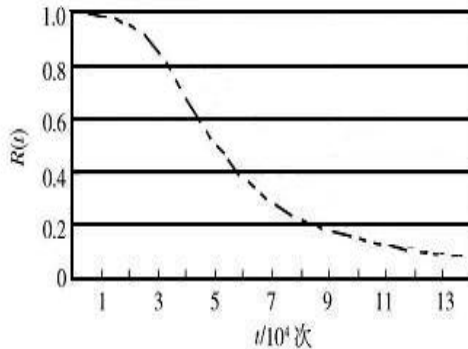


Figure.1 The Function Curve Of Performance Reliability Of The Real Mine Transportation Systems

## 5. CONCLUSIONS

(1) According to detailed process and method presented in this paper, by the Figure 1 and MATLAB software, we can predict the real-time reliability degree is 0.98 when the operation cycle number is 9200; its value is 0.97 when the operation cycle number is 10800.

(2) It is shown from the data that with the increase of cycle number, its real-time reliability will decrease according to the certain rule. Therefore, we can flexibly adjust the bulk transportation plan to avoid affecting the normal production work. Presented detailed methods and steps can offer the reference for real-time reliability prediction researches of the mine logistics transportation system.

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