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APPLICATION OF CLASSIFICATION ALGORITHMS IN DATA MINING FOR HOTSPOTS OCCURRENCE PREDICTION IN RIAU PROVINCE INDONESIA

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ABSTRACT

High fire occurrence in Riau Province, Indonesia has been going on in the recent years with large areas occurring in the peat soil. In this paper a data mining technique namely classification was applied on forest fire data to develop classification models for hotspots occurrence in Riau Province. The models provide characteristics of areas where active fires occurred. We studied physical data including land cover, road, river, city centers, industrial timber plantation, logging concession, peatland depth and peatland types to classify 2693 target objects. Target objects are true alarm data namely hotspots distribution in 2008 and false alarm data which are randomly generated within the areas at least 1 km away from any true alarm data. We applied three classification algorithms that are available in the data mining toolkit Weka 3.6.2: J48 module as Java implementation of C4.5 algorithm, SimpleCart and NaïveBayes. The result shows that the classifier generated from the J48 has highest accuracy i.e. 69.59 % compared to two other algorithms. Our results based on the J48 classifier show that hotspots are predicted to take place in areas that (1) are non logging concession areas, (2) are plantation and dryland forest, and (3) have peatland type: Very deep Hemists/Saprists (>400 cm). Additionally, hotspot occurrence probability is higher in areas located 10 km from roads, 3 km from rivers and within 5 km to 20 km of city centers where the areas are accessible to humans.

Keywords: Data Mining, Classification Method, Forest Fires, Hotspot, Indonesia

1. INTRODUCTION

Forest fires both in Kalimantan and Sumatra, Indonesia seem to be yearly disaster especially in dry season. It is considered as a regional and global problem because its impacts could be felt by people not only in Indonesia but also in many parts of Southeast Asia including Singapore and Malaysia. Riau is one of provinces in Sumatra that has high deforestation because of forest fires especially in dry season. Uryu et al. (2008) in [1] state that Riau has high deforestation in recent years and the majority of the deforestation has occurred on peat soil. This province has lost more than 65% of forest (about 4 million hectares (ha)) in the last 25 years in which forest cover decreased from 78% in 1982 to 27% in 2007 [1]. A study conducted by [2] found that there is a clear relation between fires and deforestation and degradation [2]. According to [1] more than 72,000 active fires (hotspots) were recorded in Riau by NOAA AVHRR and MODIS satellite sensors in the period 1997-2007. The total emission in Riau was estimated about 3.66 gigatons (Gt) CO₂ between 1990 and 2007 resulted from deforestation, forest degradation and decomposition and burning of peat [1]. Especially in peatland, fires produce not only CO₂ emissions but also smoke haze problems. Peatland fires in Riau Province have resulted in smoke haze problems that also felt in neighboring countries including Brunei, Singapore and Malaysia, and as far as Thailand, Vietnam and Philippines. Herawati et al (2006) in [3] state that smoke haze problems from peatland fires influence the city traffic, sea transportation and flights, human health and other economical lost [3]. In order to minimize the incidence of forest

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fires, many	works	have been	conduct	ed in	Data	Source
developing	forest f	ire risks	models	using	Spread and coordinates	Ministry of
geographical	informat	tion system	s (GISs)) and	of hotspots 2008	Environment.

Study on fires risk may involve large spatial data including physical data, climate data, and social economic data. The data are stored in spatial databases as one of the component in GISs. Spatial databases store large number of spatial features and their relationships for further manipulation and analysis to help users in decision making process. In order to extract interesting and useful but implicit spatial patterns from large spatial databases, data mining techniques continue applied in many areas including in forest fires risk modeling.

Data mining tasks including association rules mining, classification and prediction, as well as cluster analysis have been successfully utilized in analyzing spatial data related to forest fires [10-14]. In this paper, a data mining technique namely classification is applied on forest fires data to develop classification models for hotspots occurrence in Riau Province Indonesia. The spatial data used include land cover, road, river, city centers, logging concession, industrial timber plantation, type and depth of peatland. The classification models provide characteristics of areas where active fires occurred and it can be used to predict the hotspot occurences in a new area.

2. MATERIAL AND METHODS

1) Forest fires data

remote sensing [4-9].

The study area is the Riau Province in Sumatera Island Indonesia (Figure (1)). The total area of Riau Province is approximately 8,915,015.09 Ha (89,150 Km²) consisting of land and water areas. Spatial data are detailed in Table 1. We assigned the datum WGS84 as the spatial reference system to all spatial objects.



Figure 1. Riau province, Indonesia (Source for Riau Province map: BPS (Statistics-Indonesia)) Table 1. Spatial data

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Data	Source
Spread and coordinates	Ministry of
of hotspots 2008	Environment,
_	Indonesia
Physical data: land	National Land
cover, road, river, city	Agency (BPN) Riau
centers, Industrial	province, Indonesia
Timber Plantation,	
Logging Concession	
Administrative border	BPS (Statistics-
for village, subdistrict,	Indonesia)
district and province	
Peatland: peatland depth,	Wetland Indonesia
peatland types	

For mining purposes using classification algorithms, a dataset should contain some explanatory attributes and one target attribute. Therefore we conducted two main tasks in constructing a forest fires dataset: 1) creating the target attribute and populating its value from the target objects, and 2) creating explanatory attributes from neighbor objects related to the target objects. In our study, target objects are true and false alarm data (Figure (2)). True alarm data (positive examples) are hotspots that spread in Riau Province in 2008. Number of hotspots in peatland and nonpeatland areas in 2008 is 3,092. False alarm data (negative examples) were randomly generated and they are located within the areas at least 1 km away from any true alarm data. For this purpose we created 1 km buffers from positive examples and extract all randomly generated points outside the buffer to be negative examples. Explanatory objects are physical data including land cover, roads, rivers, city centers, industrial timber plantation (ITP), and logging concession, peatland type, and peatland depth that will classify the target objects into false or true alarm.



Figure 2. False and true alarm data

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2) Data preprocessing

Preprocessing steps were performed to relate the explanatory objects to target objects by applying topological and metric operations. Topological relations used are Inside. Meet. and Overlap. Metric-relations i.e distance is calculated from target objects to explanatory objects such as river, road and city centers. Distance between two objects are calculated in decimal degree because all maps are referenced using WGS84. We converted decimal degree unit to meters to prepare a final dataset. Preprocessing steps for spatial objects are explained in the following subsections. All steps were performed using open source software: Quantum GIS 1.0.2 (http://qgis.org/) for spatial data analysis and visualization, PostgreSOL 8.4 as the system database management (http://www.postgresql.org/), and PostGIS 1.4 for spatial data analysis (http://postgis.refractions.net/).

a) Distance target objects to nearest road, river and city centers

We defined relations between target objects and spatial objects: roads, rivers and city centers by calculating distance from target objects to nearest roads, rivers, and city centers. For this purpose, the PostGIS operation ST_Distance was applied to compute distance from each target to all rivers, road networks and city centers then identify its minimum value as distance from a target to nearest objects. Figure (3) and Figure (4) show a river network and a road network respectively overlaid with target objects. Distance between target objects (false alarm and true alarm) and river segments were calculated by running the following query statement:

SELECT target.gid AS target_ID, river.gid AS river_ID, target.class, ST_Distance(target.the_geom, river.the_geom) AS dist_target_river FROM river, target;



Figure 3. Rivers and some target objects



Figure 4. Roads and some target objects

b) Land cover, logging concession, industrial timber plantation

There are 13 types of land cover: natural forest, dryland forest, mix garden, mangrove, plantation, settlement, swamp, paddy field, shrubs, bare land, unirrigated agricultural field, water body, and embankment. We determined types of land cover for the areas where the target objects are located. For this purpose we applied the topological operation ST_Within in PostGIS to identify target objects *inside* an area and its type of land cover. The following query statement was used to identify target objects inside all land cover types.

SELECT target.gid, target.the_geom, target.class, land_cover.landcovertype FROM target, land_cover WHERE ST_Within(target.the_geom, land_cover.the_geom) ORDER BY target.gid;

In order to relate target objects with logging concession and industrial timber plantation (ITP) represented in polygons we defined whether the objects are located in the polygons or not. The topological operation ST_Within in PostGIS was used to identify target objects *inside* logging concession and ITP.

c) Peatland

The total area of peatland in Riau Province is about 40,191.97 km² or about 45% of the total area of Riau Province. There are two important characteristics of peatland considered in this work: peatland types and peatland depth. Figure (5) and Figure (6) display peatland types and peatland depth layers respectively, as well as some targets overlaid with these two layers. The label in peatland type for example "Hemists/Saprists (60/40), Moderate" is described as follows: Hemists and Saprists are peatland types, the value 60 and 40 respectively represent 60% of Hemists and 40% of Saprists covering the area. Moderate is a category for peatland depth. The topological operation

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ST_Within in PostGIS was applied to identify target objects *inside* peatland.

3. RESULT AND DISCUSSION

Classifiers were developed from a dataset containing physical data and target data. Number of target objects after preprocessing steps is 2693 (1373 true alarm (hotspot) and 1320 false alarm. Fields in the dataset are as follows

- 1. Distance from target data to nearest road in km (min_dist_to_road)
- 2. Distance from target data to nearest river in km (min_dist_to_river)
- Distance from target data to nearest city center in km (min_dist_to_city)
- 4. Land cover type for the area where target data are located (landcovertype)
- 5. Logging concession in the area where target data are located (in_logging_conc)
- 6. Industrial Timber Plantation in the area where target data are located (in_itp)
- 7. Peatland types (legend)
- 8. Peatland depth
- Target attribute containing true and false alarm (class). True alarm data are hotspot in 2008 for all areas in Riau Province. False alarm data are randomly generated outside 1 km buffer for true alarm data

The dataset are divided into the training set for developing the classification models and the testing set to calculate the accuracy of the models.

There are several methods that can be applied to construct classification models such as decision tree and neural network. The decision tree methods include ID3 [15] developed by J. Ross Quinlan during the late 1970s and early 1980s, C4.5 [16] as a successor of ID3, and CART (Classification and Regression Tree) [16] proposed by L. Breiman et.al in 1984 that generates binary decision trees. Other method is Bayesian Classification. The simple Bayesian classifier namely Naïve Bayesian Classifier learns from training data the conditional probability of each attribute A_i given the class label C [17]. Moreover, classification is conducted by applying Bayes rule to compute the probability of C given the particular instance of $A_1, ..., A_n$, and then predicting the class with the highest posterior probability [17].



Figure 5. Target layer overlaid with peatland type layer



Figure 6. Target layer overlaid with peatland depth layer.

We applied two decision tree algorithms that are available in the data mining toolkit Weka 3.6.2: the J48 module as Java implementation of C4.5 algorithm and SimpleCart. For comparison, we

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also run the algorithm NaïveBayes in Weka 3.6.2 to develop a classifier on datasets. Weka is a collection of machine learning algorithms for data mining tasks. It is the open source software issued under the GNU General Public License that contains tools for data pre-processing, classification, regression, clustering, association rules. and visualization (http://www.cs.waikato.ac.nz/ml/weka/). 10-folds cross validation was used to calculate accuracy of the classifiers. Table 2 represents accuracy of classifiers for forest fire data in peatland areas.

Table 2 Accuracy of classifiers

Algorithm	Accuracy
J48	69.5878 %
SimpleCart	66.84 %
NaiveBayes	62.8667 %

Below are some rules generated from the C4.5 decision tree:

- 1. IF in_logging_conc = no AND landcovertype = Plantation AND min_dist_to_city <= 20.3706 km AND legend = Saprists/Hemists(60/40),Very_deep AND depth = D2 (Moderate 100-200 cm) THEN Hotspot Occurrence = T (56.0/19.0)
- 2. IF in_logging_conc = no AND landcovertype = Plantation AND min_dist_to_city > 20.3706 km AND legend = Saprists/Hemists(60/40),Very_deep THEN Hotspot Occurrence = T (127.0/9.0)
- 3. IF in_logging_conc = no AND landcovertype = Shrubs THEN Hotspot Occurrence = T (111.0/27.0)
- 4. IF in_logging_conc = yes AND min_dist_to_road > 5.212 km AND landcovertype = Dryland_forest THEN Hotspot Occurrence = F (140.0/13.0)

The numbers in parentheses at the end of each rule represent the number of examples associated to this rule whereas the number of misclassified examples are given after a / slash /.

The main result of this work is a decision tree generated by the J48 module in WEKA 3.6.2. It consists of 241 leaf nodes with the first test attribute is logging concession. The next test attribute for the area in logging concession is minimum distance to nearest road (Figure (7)). If the distance between a particular area to the nearest road is less than or equal to 5.212 km then 23 hotspots are predicted occur in that area (see leaf 1 in Figure (7)). Otherwise the tree will evaluate the land cover types, distance the area to nearest city center and road in order to decide the potential of hotspot occurrence. Other attributes namely peatland types and peatland depth are not required to classify the objects in logging concession areas to the target classes.

n logging conc = yes
min dist to road <= 5.212: T (23.0/8.0) - leaf 1
min dist to road > 5.212
landcovertype = Plantation
min dist to city <= 24.5647: F (22.0/1.0)
min dist to city > 24.5647: T (2.0)
<pre>landcovertype = Bare land</pre>
min dist to river <= 3.2219: F (4.0)
<pre> min dist to river > 3.2219: T (2.0)</pre>
<pre>landcovertype = Mix garden: F (0.0)</pre>
<pre> landcovertype = Dryland forest: F (140.0/13.0)</pre>
<pre> landcovertype = Unirrigated agricultural field: F (0.0)</pre>
landcovertype = Shrubs
min dist to road <= 19.111: F (2.0)
min dist to road > 19.111: T (4.0)
<pre>landcovertype = Swamp: F (2.0)</pre>
<pre>landcovertype = Paddy field: T (2.0)</pre>
<pre>landcovertype = Mangrove: T (2.0/1.0)</pre>
<pre> landcovertype = Natural forest: F (0.0)</pre>
<pre>landcovertype = Settlement: F (0.0)</pre>
<pre>landcovertype = Water body: F (1.0)</pre>

Figure 7. Subtree associated with the root node 'logging concession' with the value 'yes'.

The next test attribute for the root with the value non-logging concession is land cover type (Figure (8)). The tree predicts 659 hotspots occurred in the plantation and 197 hotspots taking place in Dryland forest (Table 3). After testing the land cover type, other explanatory attributes will be evaluated to create rules for classifying the hotspots occurrence. These attributes include distance the area to nearest city center, peatland types, distance the area to nearest river, peatland depth, Industrial Timber Plantation, and distance the area to nearest road. From the J48 classifier, we summary that hotspots are mostly predicted taking place in (1) non logging concession areas, (2) plantation and dryland forest, (3) areas with peatland type of very deep Hemists/Saprists (> 400 cm).



Figure 8. Subtree associated with the root node 'logging concession' with the value 'no'.

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Table 3 Number of actual and predicted hotspotsgrouped by land cover types

Land Cover Type	Number of actual hotspot	Number of predicted hotspot
Bare land	127	158
Dryland forest	230	197
Embankment	0	0
Mangrove	2	1
Mix garden	65	69
Natural forest	15	16
Paddy field	67	61
Plantation	651	659
Settlement	2	2
Shrubs	91	115
Swamp	33	30
Unirrigated		
agricultural field	90	98
Water body	0	0
Total	1373	1406

Most of forest fires cases in Indonesia are caused by human factors. Human activities may trigger fire ignitions. Some factors such as proximity to road networks, proximity to rivers, and proximity to settlement areas are related with human ignitions [8]. Roads represent areas of higher fire risk because of the influence of human activities [18]. Additionally, roads are potential routes for hiking or camping areas [19]. The consideration of the proximity to rivers is also important because of its influence in humidity and vegetation type [18]. Our results based on the J48 classifier showed that hotspot occurrence probability is higher in the area located 10 km from roads, 3 km from rivers and within 5 km to 20 km of city centers where peatlands are accessible to humans (Table 4 and Table 5).

 Table 4 Number of predicted hotspots grouped by distance to nearest road and river

Distance to nearest road (km)	Number of Predicted Hotspot (%)	Distance to nearest river (km)	Number of Predicted Hotspot (%)
5	39.12	1	24.32
10	28.09	2	21.62
15	12.87	3	17.78
20	6.33	4	13.58
25	3.27	5	8.61
30	2.56	6	6.12
35	3.06	7	3.91
40	2.42	8	2.13
[45, 60)	2.28	[9, 12)	1.92
Total	100	Total	100

 Table 5 Number of predicted hotspots grouped by distance to nearest city center

Distance to	Number of
nearest city	Predicted
center (km)	Hotspot (%)
5	15.36
10	30.73
15	19.99
20	19.06
25	10.95
30	3.56
35	0.07
40	0.28
Total	100

4. SUMMARY AND FUTURE WORK

In this study, classification models for hotspots occurrence in Riau Province Indonesia have been developed. The dataset contains explanatory attributes and the target attribute consisting of hotspots in 2008 as true alarm data and false alarm data which are randomly generated within the areas at least 1 km away from any true alarm data. We applied three classification algorithms, that are available in Weka 3.6.2, on peatland fires data to construct the classifiers. The model with the highest accuracy of 69.5878 % is generated by the J48 algorithm. Our results based on the J48 classifier show that hotspots are predicted taking place in (1) non logging concession areas, (2) plantation and dryland forest, (3) areas with peatland type of very deep Hemists/Saprists (> 400 cm). Furthermore, hotspots are predicted occurred in areas located 10 km from roads, 3 km from rivers and within 5 km to 20 km of city centers where peatlands are accessible to humans. The classification model can be used to predict the hotspots occurrence in the new location.

Additional data preprocessing steps can be performed to improve accuracy of the model. The steps include identifying outliers and smoothing out noisy data, attribute transformation and discretization, as well as attribute selection. Furthermore, our next study will include socioeconomic and weather data that influence peatland fires. Another direction of research is applying spatial data mining techniques to the data so that relation between objects of interest and its neighbors can be involved.

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