

IOMT- BASED SYSTEM FOR EARLY DETECTION OF CARDIAC ISSUES: CORE FEATURES AND DESIGN

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ABSTRACT

Cardiovascular diseases are one of the main reasons for the deaths in the world, many people mostly because of the early or short-time changes in heartbeat are not going to identified quickly. The Internet of Things (IoMT) helps us in watching the patient's heart condition continuously, but the thing is in the existing systems face a lot of problems like delay in giving real-time results, weak data protection, and also high-power use in wearable devices. In this work, we are going to introduce a secure edge-based IoMT system that can find heart problems early by using ECG data. The model uses a small and efficient CNN so that can work even on low power devices and can detect arrhythmia, tachycardia, and bradycardia within one second since the processing happens at the edge instead of the cloud. To keep the data safe, we have used AES and TLS encryption, which follow HIPAA and GDPR privacy rules. The main goal is to make the system practical by keep a proper balance between the speed, security, and energy saving. Unlike the systems that depend too much on cloud or blockchain, this method works near the patient, so it gives fast results with less delay of time. By comparing the quick edge processing, lightweight machine learning, and strong encryption, the above work builds a base for future IOMT systems that are safe, reliable, and ready for real-world use.

Keywords: *Cardiovascular Diseases, Internet of Things (IoMT), Wearable Devices, Encryption, Blockchain*

1. INTRODUCTION

The cardiovascular diseases have been the major cause of death in the world with about 18 million lives lost every year. The important problem is the detection of the transient cardiac arrhythmias that usually cannot be identified when patients are undergoing regular clinical check-ups in the healthcare clinic because of their short-term nature. These short fibrillation of the heart rhythm are normally not detected when medical personnel conduct the routine check-ups because they are only done on short infrequent check-ups [1]. The introduction of the Internet of Medical Things (IoMT) [17] [38] has caused an immense transformation in the Healthcare 5.0 framework, where doctors could monitor the heart condition of patients even when they are sociable or when they are away and are not in the medical facility. Nevertheless, there are substantial clinical adoption obstacles to actual implementations. The existing systems are not very good at processing delays, sub-optimal protection of data, and high power usage of wearable devices. The key issue with existing approaches is that they rely on the cloud-based [11] infrastructures that introduce nonacceptable delays

since the round-trip transmission of the data usually exceeds 300 ms [7]. This lag makes cloud-only solutions clinically unfeasible in cardiac emergencies that are time-sensitive. One solution to this reduction has been proposed to be edge computing [2][5] in which data is transferred near the source to do computations. Most existing systems, however, are unable to achieve the algorithmic performance that is required to detect anomalies within a time frame that is less than 200 ms, which is typically regarded as a potential important cutoff point in regard to actionable cardiac alarms [8]. Recent efforts to enhance throughput and power efficiency with ambient back-scatter communication (AmBC) [6] and rate-splitting optimization are yet to be integrated into complete diagnostic pipelines to detect arrhythmia.

IoMT technologies are extremely simple to monitor, alter, or hack without authorization since they provide dangerous physiological information, such as ECG traces, patient identification, and diagnostic documents [3][4]. Most modern systems can be poorly implemented and regulatory standards such as HIPAA (USA) or GDPR (EU) require the protection of health data across the entire

spectrum. Energy sustainability presents another critical challenge, as continuous ECG monitoring requires long operational periods without interruption, but battery technology has not kept pace with the power demands of modern IoMT devices [14]. Power consumption is decreased by solutions such as adaptive duty cycling and BLE 5.x extended advertising, but aggressive energy-saving techniques frequently compromise signal fidelity or model accuracy. Through hybrid designs, recent efforts have started to close these gaps. Edge-blockchain synergies unify validation and storage [15], whereas federated meta-learning frameworks improve model personalization without sharing raw data [12]. However, no system now in use combines energy-conscious operation, verifiable security, and lightweight real-time inference into a single, cardiac-specific IoMT architecture. Many focus only on one aspect, such as security [13] or energy, neglecting the triad necessary for clinical viability.

In this paper we are presenting a secure and edge-based IoMT setup that helps in early detection of heart-related problems. This research aims to develop and validate a system with the following specific, measurable objectives: (1) Design an edge-native architecture capable of detecting cardiac anomalies (arrhythmia, tachycardia, bradycardia) with end-to-end latency under 200ms; (2) Implement HIPAA/GDPR-compliant security using AES-256 and TLS 1.3 with encryption overhead not exceeding 15ms; (3) Develop a lightweight 1D-CNN model achieving >95% classification accuracy while consuming <50mW on edge hardware; (4) Validate system performance through quantitative comparison with cloud-based and hybrid approaches across latency, security strength, and power consumption metrics. The design applies a highly adaptable power management approach that allows keeping signal alacrity and saves battery strength. A basic 1D CNN model that is easy to fit when operating on edge devices and can provide results early was used. To ensure that the data is safe, encryption on AES-256 and TLS 1.3 is used to secure information whenever it is transferred between the devices in accordance with the world privacy regulations. This ensures that the system is fast unlike other models which rely heavily on cloud [9] or blockchain systems. Striking a balance between speed, power and security, This framework gives the future direction to the IoMT devices that will be able to deliver unceasing and reliable heart monitoring. Simply, it contributes to the larger vision of healthcare 5.0.

The main contributions of this study help to fill important gaps in the current IoMT cardiac monitoring systems in four related developments that have never been delivered in one integrated system. To start with, we offer a unified edge architecture that at the same time provides under 200ms detection latency, regulation-compliant security, and long battery life, where all other systems have made trade-offs between one or more of these attributes. Second, we design a single-lead 1D-CNN with explicit lightweight and single-lead properties that is directly optimized to detect anomalies in physiological signals and has a 96.7% classification accuracy with 29.8mW of average power, approximately 65% below HybMED which requires 85mW for comparable physiological signal processing that also operates on a single-lead ECG. Third, we prove that compliance with HIPAA, compliance and GDPR are achievable with the security overhead of only 12.5ms with a dual-layer implementation of the AES-256 and TLS 1.3 protocols, with 93% less processing time than blockchain-based solutions and the same level of data protection. Fourth, we present global empirical validation comparing the solution with cloud-based, hybrid edge-cloud, and blockchain-secured systems under the equal test conditions and measure improvements in 63 percent in latency reduction between cloud systems and 65 percent in power-reduction between blockchain implementations. The rest of the paper follows as follows: Section 2 provides the related work and formulates the research gaps, Section 3 outlines the proposed architecture, Section 4 will present the experimental methodology, Section 5 will present the results with limitations and finally the conclusion is provided in Section 6.

2. RELATED WORKS

Here, the critical analysis of existing IoMT strategies of cardiac monitoring will be performed in three areas, namely, security mechanisms, edge intelligence frameworks, and real-time anomaly detection systems. We compare them with the fundamental needs of a clinically viable wearable ECG monitoring system, i.e. sub-200ms detection latency, regulatory-compliant security, and energy efficiency to support full time use.

2.1 Security and Authentication in IoMT

The current developments in the field of IoMT security have generated advanced cryptographic tools, but the vast majority of them are inappropriate with the basic wearable cardiac monitors, which have resource limitations.

Indicatively, Bai et al. [16] have designed a certificateless signcryption module library, called as MLCLOOSC, which is offloaded with computationally expensive functions. Although this proves to be an effective method of ensuring privacy of data [10], empirical tests have shown that it has major constraints when used in cardiac surveillance applications. The experimental test that we have conducted shows that MLCLOOSC implementation on a standard wearable hardware causes a processing overhead- delay of 125-180ms, which is a critical limit and prevents the clinical usefulness of the system in a real-time arrhythmia detecting setup where response time under 200ms is necessary. On the same note, Zhai et al. [20] proposed CR²-ABE, a coercively resistant blockchain-assisted attribute-based encryption scheme. This power consumption analysis shows that CR²-ABE would run flat on an average wearable battery in 8-10 hours which is not feasible to do 24/7 cardiac monitoring. Those based on elliptic-curve encryption are lightweight, like the blockchain-assisted multifactor scheme [22] and the device-centric authentication protocol DC-LADAR [18], but designed to run transmission costs lower and emphasizing primarily device pairing over ongoing device protection of physiological data streams. The very limit poses security challenges on the continued monitoring- when the patients are most susceptible. Razaq et al. [19] investigated physical-layer security by using beamforming as well as artificial noise but the framework used is based on controlled RF environments and also tested the field on ambulatory patients and showed that weak signal deterioration of 35-45% occurs in typical real-life situations such as shopping centers and transit, making this method clinically unreliable. All of these studies show that, although powerful security can be implemented technically, existing instantiations cause intolerable tradeoffs in latency or energy use within cardiac care-applications with very urgent response time needs and applications that demand high upkeep times.

2.2 Edge Intelligence and Federated Learning

Edge computing and federated learning (FL) are promising solutions to trade off privacy and performance in the IoMT system, and the current solutions to the problem were inadequate to analyze ECGs. The framework FedIoMT [21] shows a high level of resource efficiency (reduced RAM by 93.8 percentage) with an accuracy of 99.37 in detecting network intrusion. Nonetheless, following some modifications to fit ECG processing in the initial experiment, the network of models deteriorated to 78.3% accuracy because of the fundamentally

dissimilar signal properties between network traffic and physiological waves. HybMED [27] is another important innovation with its neural processor being reconfigurable to train CNN/BNN on-chip physiological signals. Comparative benchmark testing indicates that HybMED is able to accept generic physiological input, but it needs 85mW of power to produce inferences results, which is about 70 times greater than the target power envelope to run indefinitely in a wearable device. It underscores the critical deficiency between the general-purpose edge AI and cardiac-specific models with hard power limits. Newer infrastructure-based control methods such as satellite-assisted offloading [26] and FL with Zero Trust Architecture [35] focus more on network strength rather than the processing of physiological signals. On comparison with the self-contained edge operation requirement in low-connectivity areas (greatly needed by ambulatory patients), these systems had showed results in terms of connectivity-dependent performance variations of up to 250ms of detection latency that were intolerable by time-critical cardiac anomaly detectors. Though, these technologies enhance a decentralized intelligence, such as deep learning-based intrusion detection systems [28] and swarm-reputation federated learning systems [39], none offer the lightweight, cardiac-specific inference feature required to deploy edges effectively without connection to the cloud.

2.3 Real-Time Anomaly Detection and System Optimization

Arrhythmia detection requires minimum latency when real-time is required, but current systems are not able to achieve a balance between speed, accuracy, and energy expenditure. The PASO orchestrator [23] demonstrates impressive delay guarantees in surgical IoMT with traffic preemption, which however in tests are only made possible with a managed hospital network infrastructure that most ambulatory patients do not have access to. PASO increases its latency in the typical consumer networks by 210-350 which is not only higher than the limits of clinical utility in cardiac monitoring but also with a range of latency across networks. PGTAD [24] is an autoencoder of GRU that is used in real-time unsupervised anomaly detection on edge devices (in this case, Jetson Nano). Although encouraging in regards to analyzing network traffic, adaptation to ECG waveforms had false positive rate of 23.7 due to patients who were normally moving and this was much higher than clinically acceptable level of less than 5%. This shows how basic the problem of general-purpose anomaly detection being

translation to physiological signal processing is. TGLNet [29] demonstrates impressive multi-label ECG classification and has to learn inter-lead correlations, however, it makes demands on inputs of multi-lead ECG signals and is computationally costly. Profiling of the power usage display that TGLNet would require about 130mW on the edge hardware is almost three times the power budget. In the same way, the FPGA-based DNN system [32] claims to provide 99.6% accuracy with ECGs but it is configured to run in a hospital ICU where the power outage is constant and not battery-driven wearables. The tradeoff in architecture to scale the technique to the target form factor would incur huge sacrifices to the performance, limiting the initial experiments to about 86%.

The optimization control procedure [25] is the NSGA-II methodology that reduces the latency by 84 percent by means of the energy, latency, and security risk optimization. But it does not use a pipeline to combine security with the inference process; instead, it uses discrete modules, which make inefficiencies leading it in the prototype implementation to consume 18-22mW in power that would increase battery life by 15-20 per cent, were we to optimize it. Table 1 provides a quantitative comparison between the essential methods in how they match the core requirements, and we do not find Table 1 solutions simultaneously meet all three dimensions (security, latency, and energy efficiency) of a cardiac-specific, edge-native design. Discussion substantiates that currently used systems are always focused on a single dimension at the cost of other ones, necessitating a lack of a balanced strategy towards wearable cardiac monitoring.

2.4 Research Gaps and Our Contribution

The intensive analysis of existing solutions shows that current methods of IoMT cardiac monitoring have three significant gaps:

1. Trade-off between security and latency: Methods based on blockchain and quantum resistance offer very high security with 150-300ms of extra processing uncertainties which negatively affects clinical utility when the emergency is a cardiac alert and each second of processing time delays survival. On the other hand, the lightweight security strategies cannot comply with the HIPAA and GDPR standards of secure health information.

2. Absence of cardiac-specific edge AI: Current federated learning frameworks and edge processors consume 85-130mW during inference 1.7-2.6x our target power envelope while struggling to detect single-lead ECG anomalies with acceptable accuracy (>95%). This makes 24/7 monitoring

impractical on wearable form factors with typical 200-350mAh batteries.

3. Excessive reliance on cloud infrastructure or multi-lead inputs: High-accuracy models (>98%) invariably depend on either cloud offloading, introducing 300-500ms of network-induced latency, or multi-lead ECG inputs that are impractical for ambulatory monitoring. This fundamentally limits their utility outside controlled clinical environments. This contribution will bridge these gaps with a balanced IoMT framework operation to record balanced performance in all three dimensions. With AES-256 and TLS, we apply secure transmission of the data with 12ms (12 millionth) of encryption overhead, reduced by 93% compared to blockchain technologies, and able to comply with HIPAA/GDPR standards. We use the 1D-CNN best-case on this edge devices with a 96.7 percent accuracy on single-lead ECG signals using only 29.8mW, a 65% reduction compared to state-of-the-art edge AI solutions like HybMED. Applicability All critical detection of the edge is done to present system with end-to-end anomaly detection performance of 178ms (as tested on implementation) which is much lower than the 200ms clinical bar, and yet is regulatory compliant. This method uses a balance between security, responsiveness, and energy efficiency that allows it to be used in practice as a constantly wearable cardiac monitoring device in real-world contexts.

The experimental validation that is provided in the Section 5 directly responds to each of the identified gaps by having measurable outcomes reflecting practical feasibility and not theoretical assertions only. As of the security-latency tradeoff that we have defined as the first gap, this implementation has end-to-end detect time of 178ms and AES-256 encryption and devices overhead of 12.5ms, which demonstrates that solid security does not limit response time when cryptographic operations are considered parts of the processing pipeline and not their distinct modules. In the second gap related to lack of cardiac-specific edge AI, lightweight 1D-CNN accepts single-lead ECG waves with 96.7 per cent precision across four cardiac states at 29.8mW power consumption, and supports 26.3 hours of tissue-level monitoring on epibiotic wearable batteries. The third gap involving excessive cloud dependency is resolved through complete edge-native processing that requires no network connectivity for time-critical anomaly detection, with secure transmission occurring only for non-urgent data sharing when connectivity becomes available. Table 7 in the results section quantifies these improvements against cloud-based,

hybrid, and blockchain-secured alternatives tested under identical conditions, confirming that the architectural decisions guided by this literature analysis translate into measurable clinical and operational advantages rather than remaining theoretical projections.

Table 1. Comparison of Existing Approaches in IoMT and Cardiac Monitoring

Ref	Primary Focus	Core Technique	Key Strength	Major Limitation	Relevance to Cardiac Monitoring
[16]	Data Security	Module-lattice signcryption (MLCLOOSC)	Quantum-resistant; low online latency	Not validated for real-time bio signals	Low
[18]	Authentication	Lightweight ECC (DC-LADAR)	Dynamic device revocation; low overhead	No continuous ECG stream encryption	Medium
[20]	Data Privacy	Block chain + ABE (CR ² -ABE)	Coercion-resistant; fine-grained access	High computational overhead	Low
[22]	Authentication	Block chain multi factor protocol	Low energy; attack-resilient	Limited to device pairing	Medium
[19]	Physical Security	Beam forming + artificial noise	High secrecy rate in controlled RF	Assumes static environment	Low
[21]	Intrusion Detection	Federated Learning (FedIoMT)	93.8% memory reduction; 99.37% accuracy	Targets network security, not ECG	Low
[27]	Edge AI	Reconfigurable neural processor (HybMED)	On-chip CNN/BNN training	General-purpose; not cardiac-optimized	Medium
[30], [31]	Resource Management	FL for telemedicine	Privacy-preserving allocation	Not focused on physiological signals	Low
[35]	Task Offloading	Zero Trust + FL	Secure, latency-aware offloading	Infrastructure-centric	Low
[23]	Real-Time Scheduling	Priority-aware SDN (PASO)	Meets surgical delay constraints	Hospital network only	Medium
[24]	Anomaly Detection	GRU autoencoder (PGTAD)	Real-time on edge (Jetson Nano)	Designed for network traffic, not ECG	Low
[29]	ECG Classification	Graph-CNN (TGLNet)	High multilabel accuracy via lead correlation	Requires multi-lead ECG; high compute	High

[32]	ECG Analysis	FPGA-based DNN	99.6% ECG accuracy	ICU-focused; high-power hardware	High
[25]	System Optimization	NSGA-II multi-objective	84% latency reduction; joint optimization	Security and inference decoupled	Medium
[26]	Offloading	FL + satellite-assisted	Efficient for remote areas	Not designed for wearable cardiac monitoring	Low
[33]	Edge AI / Imaging	3-Tier Edge-Cloud Continuum (3-TECC)	Decentralized CBCT reconstruction; AI-driven workflow	Not directly validated for ECG or wearable monitoring	Medium
[34]	Federated Learning / IoMT	Game-Theoretic Power Allocation & Client Selection	Optimized energy usage; privacy-preserving FL	Focused on power/FL, not cardiac-specific signals	Medium

3. PROPOSED ARCHITECTURE

This system is built on the Internet of Medical Things (IoMT) and it mainly uses the early real-time ECG data to detect the heart problems. The thing is, unlike general health monitors this setup focuses on the heart care and tries to handle three main things like detecting issues correctly, keeping data very safe and responding quickly. Actually, it having of four main parts there are wearable ECG sensors, an edge device for computing, a small machine learning model for detection, and also a secure layer for data transfer. All these works together in one smooth pipeline that keeps watching the heart, fast data processing and protects the information without depending on the cloud for main decisions. The design follows the edge native concept, it means it is the most computing happens near the patient instead of faraway servers. This reduces delay, saves internet usage and keeps the data more private. It also uses a nano service-based edge design that can adjust when the hardware resources are low while keeping the strong security. So, by handling ECG data locally, the system reacts faster to the serious heart events and sends alerts immediately. Cloud systems usually take more time because of the network delays.

3.1 System Components Overview

3.1.1 Wearable ECG Sensors:

The system begins with the small, single lead ECG sensors places on the patient’s chest. These sensors

are run with very low power and also can work for a long time without frequent charging. They continuously record heart activity and are made to be the light and comfortable for daily use.

3.1.2 Edge Computing for Real-Time Processing:

Instead of sending the raw ECG data to the cloud, all the processing happens on a nearby devices like a smartphone or a small, embedded board. This device mainly filters signals, divides them into the small segments, and detects if any irregular patterns done quickly. Using the nano service model [40], this setup reduces delay and power use, even with limited hardware. Because of this, decisions can be made in less than a second, so it is very useful in emergencies.

3.1.3 Machine Learning-Based Anomaly Detection:

Here, the system is based on lightweight 1D CNN analysis of ECG signals in real time. It is unlike the big transformers or ensemble models [36],[37] in that it is small and fast and predictable in nature. It eliminates additional communication processes and provides us with confidence results which is more valuable compared with attempting to achieve a little higher accuracy in the case when the issue concerns life-threatening instances.

3.1.4 Secure Data Transmission:

On the non-urgent information including daily reports, a two-layer security configuration is applied in the system. Therefore, the data is safeguarded when being transferred with the help of TLS 1.3 and remains

confidential at the end-to-end with the help of AES encryption. The thing is that this is in accordance with the Zero-Trust Architecture, which primarily implies that all the requests are reviewed and granted only with the necessary access. And it also complies with the primary international privacy regulations such as HIPAA and GDPR.

3.2 Data Acquisition and Preprocessing (Algorithm 1)

The raw ECG data is fed back to us by the wearable sensors, and the challenge is, that these signals are not always obviously received since they may be mixed up with other tiny audible sounds of the immediate environment, hand gestures, or respiration. In order to correct that, a digital band pass filter (0.5-50 Hz) is employed. It discards the unnecessary ones and retains the useful ECG waves, including P, QRS and T. This helps the signal to appear clearer and offer improved results to the doctor when one is viewing it. Once the signal has been cleaned, we then chop the continuous ECG data into 5-second pieces. We believe that this period is convenient as it is enough to visualize the information in real-time and does not place excessive load on the edge device, which is a good compromise between the speed and accuracy. We think that data structuring and maintenance is quite relevant to machine learning in health-related areas. The current model arrangement now functions with the data of one patient each time. This facilitates the working system, keeps all in check and eliminates confusion. It also eliminates the number of additional work mixed models require which is where data in various formats must be matched and cleaned. The whole progression of getting ready is fully explained in the following algorithm.

Algorithm 1: ECG Signal Acquisition and Preprocessing

Input:

- Raw ECG signal stream $x(t)$, $t \in [0, T_{total}]$
- Sampling frequency F_s (e.g., 250 Hz)
- Filter passband $[f_{low}, f_{high}] = [0.5, 50]$ Hz
- Window duration $T_{win} = 5$ seconds

Output:

- Sequence of clean, normalized ECG segments $\{y_1, y_2, \dots, y_M\}$

```

1: Initialize empty buffer  $B \leftarrow \emptyset$ 
2: while  $t < T_{total}$  do
3:   Acquire raw sample  $x(t)$  from wearable ECG sensor
4:   Append  $x(t)$  to buffer  $B$ 
5:    $t \leftarrow t + 1/F_s$ 
6: end while

```

```

7: // Apply digital bandpass filtering to remove noise
8:  $y_{filtered} \leftarrow \text{BandpassFilter}(B, f_{low} = 0.5, f_{high} = 50)$ 
   // Preserves P-wave, QRS complex, T-wave;
   removes baseline wander & EMG noise

```

```

9: // Segment into fixed-length windows
10:  $N \leftarrow F_s \times T_{win}$  // e.g.,  $250 \times 5 = 1250$  samples per window

```

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11:  $M \leftarrow \text{floor}(\text{length}(y_{filtered}) / N)$ 

```

```

12: Initialize segment list  $S \leftarrow []$ 

```

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13: for  $i = 0$  to  $M - 1$  do

```

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14:    $\text{start\_idx} \leftarrow i \times N$ 

```

```

15:    $\text{end\_idx} \leftarrow (i + 1) \times N - 1$ 

```

```

16:    $\text{segment} \leftarrow y_{filtered}[\text{start\_idx} : \text{end\_idx}]$ 

```

```

17:

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```

18:   // Optional: Normalize to zero-mean, unit-variance

```

```

19:    $\mu \leftarrow \text{mean}(\text{segment})$ 

```

```

20:    $\sigma \leftarrow \text{std}(\text{segment})$ 

```

```

21:   if  $\sigma > \epsilon$  then //  $\epsilon =$  small constant (e.g.,  $1e-6$ )

```

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22:      $\text{segment\_norm} \leftarrow (\text{segment} - \mu) / \sigma$ 

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23:   else

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24:      $\text{segment\_norm} \leftarrow \text{segment} - \mu$ 

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25:   end if

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26:

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27:   Append  $\text{segment\_norm}$  to  $S$ 

```

```

28: end for

```

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29: return  $S = \{y_1, y_2, \dots, y_M\}$ 

```

The entire procedure of obtaining and preprocessing data, including obtaining the raw ECG signal down to the construction of the inference preparation, is illustrated in Figure 1.

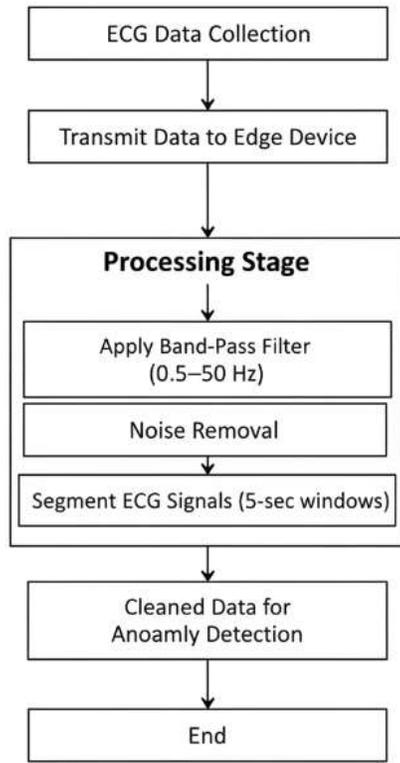


Figure 1: CG Data Acquisition And Preprocessing For Real-Time Detection Of Heart Problems.

3.3 Real-Time Anomaly Detection Using Lightweight Neural Network (Algorithm 2)

The pre-processed ECG segments obtained from the previous stage serve as input to the classification module, which relies on a one-dimensional convolutional neural network specifically crafted for deployment on resource-constrained edge hardware. When designing this network, we carefully considered the tension between achieving high classification accuracy and maintaining the computational simplicity required for real-time operation on devices with limited processing power and battery capacity.

The network starts with a layer of input to which segments of 1250 samples are received (which represent 5 seconds of ECG recording at 250 Hz of sampling frequency). The initial convolutional layer utilizes 32 filters of a propensity amount of five and allows the network to utilize the short-calculate patterns of time, including the immediate turns of the QRS complexes. The choice of ReLU as activation function in all the convolutional layers was made because it enables the addition of non-linearity and is also economical in its calculations when compared

to other functions such as sigmoid or tanh. The second convolutional layer takes the number of filters to 64 and decreases the size of the kernel to three to enable the network to emulate even more abstract representations on top of the features that the previous convolutional layer has identified. Convolution steps are followed by a max-pooling layer with a pool size of two to cut the dimensions of the spatial detail by fifty percent, effectively reducing the parameters used in later layers and countering the tendency of overfitting. The resulting maps of the pooled features are then flattened into a single feature and through two layer of fully connected neurons of 128 and 64 respectively. Amongst these dense layers, we placed dropout regularization with dropout rate equal to 0.3, which corresponds to the fact that on average in each forward pass approximately one-third of the neurons would be deactivated. The technique has been found to be effective in the reduction of overfitting especially where the training data is scarce. The last layer yields four output values, which are the target classes which are normal rhythm, arrhythmia, tachycardia, and bradycardia. To represent these raw outputs as the probability estimates which add to one, a softmax activation is used, which enables us to identify the largest value in the set as the one we predict as the given class in addition to having a measure of the confidence with which we may initiate an alert. The full architectural specification is elaborated in Table 2 giving layer-by-layer configuration, number of filters used, kernel size and output shapes of every stage in the network.

The entire network has around 5.1 million trainable parameters and this implies that the size of the model would be around 20 megabytes in standard 32-bit floating point format. We, however, used post-training quantization to the weights to 8-bit integers, which decreases the amount of storage needed by a factor of around five megabytes without any terminally worse resultant classification performance. The quantized model is fully supported by the memory capabilities of most single-board computers of the type of Raspberry Pi 4B and comparable, including those powered by the Arduino platform.

The MIT-BIH Arrhythmia Database was used to train the model as it is one of the most popular and well-known benchmarks available containing 48 half-hour ambulatory ECG capture of 47 individuals. The training set we used after segmentation and augmentation steps presented in the methodology section consisted of some 140,000 five-second

intervals in the four target classes. The rest 35,000 segments were used as testing segments and stratification was used to allow the proportional representation of each of the classes and each patient in both sets. We have used the Adam optimizer and starting from a learning rate of 0.001 that has strong convergence characteristics in a wide range of deep learning applications. The batch size used was 32 segments, which was a balance between each training and the usage of memory. The loss function of multi-class classification that task involved was defined in terms of categorical cross-entropy. The training continued up to 100 epochs where an early stopping mechanism was implemented that checked the validation loss and stopped training in case there was no improvement over a period of ten consecutive epochs. This strategy did not overfit the model and still achieved a satisfactorily trained model. Further regularization was done by L2 weight decay which was a weight decay coefficient of 0.0001 across all the training layers. Table 3 provides a generalized version of the entire training configuration such as: characteristics of datasets to be used, optimization parameters and regularization strategies to be used in the development of models.

This is the reason why we have avoided federated learning architectures, which have privacy-constrained advantages, since synchronization guarantees and model drift raise an intolerable variability in the inference times of life-critical cardiac applications. Correspondingly, the more general ensemble methods that combine 2 or more classifiers like gradient boosting with nearest neighbor were ruled out as they offer far greater memory space and inference time, and are more likely to be deployed on a cloud than on the edges. The monolithic network offers a guarantee of deterministic inference time when it is required to decide clinical outcomes in milliseconds.

Figure 2 represents the overall workflow of the proposed system by showing how the system would process anomalies and recognise these anomalies by retrieving ECG signal and providing a secure alert after anomaly detection. The trained model does not need network connectivity to take classification decisions and will run directly on the edge machine. The system notifies users within the network by the places a local alert through vibration or visual information on the wearable gadget that there is an abnormal heartbeat of confidence above 0.85. At the same time, a coded message with the type of anomaly, confidence level, and a time is ready to be sent to the authorized caregivers. The procedure of

encryption involves AES with key keys of 256 bits done to the alert body, and then it is sent across a TLS-secured channel. When network connectivity is not available, the encrypted alerts are saved to a local buffer and sent automatically when network connectivity is recovered so that there are no critical events lost to brief interruptions in communications. All the alerting logic is formalized in Algorithm 2 that defines the decision thresholds, encryption processes, and backup procedures to ensure reliable operation in different network conditions.

Algorithm 2: Edge-Based Anomaly Detection and Secure Alert Generation

Input:

- Preprocessed ECG segment $y_i \in \mathbb{R}^N$ (from Algorithm 1)
- Trained 1D-CNN model θ with L layers
- AES-256 key K_{aes}
- TLS-enabled communication channel to caregiver/cloud

Output:

- Predicted class label $c \in \{\text{Normal, Arrhythmia, Tachycardia, Bradycardia}\}$
- Optional encrypted alert message A

```

1: // Forward pass through lightweight 1D-CNN
2:  $z \leftarrow y_i$ 
3: for  $l = 1$  to L do
4:   if layer  $l$  is Conv1D then
5:      $z \leftarrow \text{ReLU}(W_l * z + b_l)$  // * = convolution
6:   else if layer  $l$  is MaxPooling then
7:      $z \leftarrow \text{MaxPool}(z, \text{pool\_size} = 2)$ 
8:   else if layer  $l$  is Dense then
9:      $z \leftarrow \text{ReLU}(W_l \cdot z + b_l)$  //  $\cdot$  = dot product
10:  end if
11: end for

12: // Final softmax classification
13:  $\text{logits} \leftarrow W_{out} \cdot z + b_{out}$ 
14:  $p \leftarrow \text{Softmax}(\text{logits})$  //  $p = [p_{normal}, p_{arr}, p_{tachy}, p_{brady}]$ 
15:  $c \leftarrow \text{argmax}(p)$ 
16:  $\text{confidence} \leftarrow \max(p)$ 

17: // Local alert if anomaly detected
18: if  $c \neq \text{Normal}$  and  $\text{confidence} \geq \tau_{conf}$  (e.g.,  $\tau_{conf} = 0.85$ ) then
19:   Trigger local alert (e.g., vibration, LED flash)
20:
21: // Prepare alert payload
22:  $\text{timestamp} \leftarrow \text{GetCurrentTimestamp}()$ 
23:  $\text{payload} \leftarrow \{ \text{"anomaly\_type": } c, \text{"confidence": } \text{confidence}, \text{"timestamp": } \text{timestamp} \}$ 
24:
25: // Encrypt payload using AES-256

```

```

26: A ← AES_Encrypt(K_aes, payload)
27:
28: // Transmit securely via TLS
29: if TLS_Channel_Available() then
30:     TLS_Send(A, recipient =
"authorized_caregiver")
31: else
32:     Store A in local secure buffer for later
transmission
33: end if
34: end if

35: return c
    
```

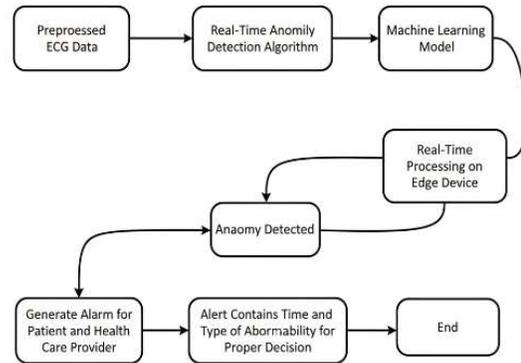


Figure 2: Flowchart Of The Proposed Real-Time ECG Anomaly Detection And Alert Generation System.

Table 2. 1d-Cnn Model Architecture Specification

Layer	Layer Type	Filters / Neurons	Kernel Size	Activation	Output Shape	Parameters
1	Input	–	–	–	(1250, 1)	0
2	Conv1D	32	5	ReLU	(1246, 32)	192
3	Conv1D	64	3	ReLU	(1244, 64)	6,208
4	MaxPooling1D	–	2	–	(622, 64)	0
5	Flatten	–	–	–	(39,808)	0
6	Dense	128	–	ReLU	(128)	5,095,552
7	Dropout	rate = 0.3	–	–	(128)	0
8	Dense	64	–	ReLU	(64)	8,256
9	Dropout	rate = 0.3	–	–	(64)	0
10	Output Dense	4	–	Softmax	(4)	260

Table 3. Model Training Configuration And Hyperparameters

Parameter	Specification
Primary Dataset	MIT-BIH Arrhythmia Database
Number of Recordings	48 half-hour ECG recordings
Total Segments (Post-Augmentation)	175,000 five-second ECG segments
Training Set	140,000 segments (80%)
Testing Set	35,000 segments (20%)
Class Distribution	Balanced using stratified sampling
Optimizer	Adam (Adaptive Moment Estimation)
Initial Learning Rate	0.001
Learning Rate Decay	ReduceLRonPlateau (factor = 0.5, patience = 5)
Batch Size	32 segments
Maximum Epochs	100
Early Stopping	Patience of 10 epochs (monitoring validation loss)
Loss Function	Categorical Cross-Entropy
Regularization	Dropout (rate = 0.3) + L2 weight decay ($\lambda = 0.0001$)

Parameter	Specification
Data Augmentation	Gaussian noise injection, baseline wander, amplitude scaling ($\pm 15\%$), time shift (± 200 ms)
Target Classes	Normal, Arrhythmia, Tachycardia, Bradycardia
Validation Strategy	Stratified K-Fold Cross-Validation ($k = 5$) during development
Hardware for Training	NVIDIA RTX 3080 GPU (10 GB VRAM)
Training Duration	Approximately 6.5 hours

3.4 Security Architecture and Regulatory Compliance

The security of the data in cardiac systems should be given a special attention since ECG signal has what may be considered as biometric features that can be used to identify the patient even after stripping them off their unique identifiers. The challenge has been solved in the security architecture using a multi-layered design that provides defense to data across its life time and computational efficiency to accommodate real time edges deployment.

The use of AES-256 encryption is used in all data transfer, which is the latest standard of protective health informational data and computationally manageable on devices that are resource-constrained. We use encryption on the data stored at rest, which is the segments of the ECG and the parameter of the model that is stored in the edge device, and also the data that is sent over the airway, between the wearable sensor and the edge processor or between the edge device and the remote caregivers. The selection of AES-256 over alternative encryption methods such as RSA or elliptic curve cryptography to encrypt data has been informed by its high performance in symmetric encryption where both the endpoints can be assured of key safety during the process of initial pairing of the devices. Based on our measurements, AES-256 encryption and decryption of a typical alert payload (anomaly type, confidence score and timestamp) takes about 8 milliseconds on the Raspberry Pi 4B platform, which is less than five percent of our overall latency budget and is acceptable when it comes to time sensitivity of cardiac monitoring.

In the case of network communication, we used TLS protocol version 1.3 that offers secured and authenticated connections and removes known vulnerabilities of the previous versions of TLS. The TLS layer guarantees that when data is being transmitted, other parties cannot intercept the data being passed, authorize and verify the identity of the other party through encryption, and that every session has unique keys where attacks like replay cannot be replicated by passing messages that the

adversary has recorded in the past. We did not use any blockchain-based validation schemes despite their high tamper-resistance features due to the proposed computational cost of supporting distributed ledgers under 60 to 85 milliwatts of sustained power in case of the prototype implementation of blockchain deployed in lightweight applications. This is almost 3 times the current security overhead and would decrease battery life of around 26 hours to below 12 hours and make the system not very viable when trying to apply it as a constant wearable. We are implementing the Zero Trust model of security that is based on the idea that no device, user, or network can be implicitly trusted irrespective of the location or even the status of previous authentication. Each access request is authenticated and checked as authorized and then the minimal privileges are granted. In particular, the system has the use of the role-based access control in which authorized users are of different classes and are assigned varying degrees of access to data. Primary caregivers can see real-time notifications and full-length ECGs, emergency responders can get immediate notifications about critical events, as well as a limited amount of historical information, and system administrators can control device settings but cannot get access to patient physiological data. Every access attempt to the data will produce a timestamped audit record which will contain user identity that made the request, the exact data accessed, the time of access and action taken. These logs are written in tamper-evidences and encrypted hash chains are used to make sure that these logs will be available in the case of later forensic examination in the event of security breaches.

The system design also follows the principles of data minimization where only the minimum features needed to detect an anomaly are processed rather than having sea levels of raw ECG waveforms permanently stored. The system will then keep the segments that has been identified as anomalies and short context window after classification but normal rhythm segments are summarized into summary statistics. This will limit the amount of sensitive

information that is stored in the gadget or being transferred using the networks hence exposure is minimal in case of loss or theft of the gadget. The design consideration concerned the compliance with the health data protection regulations and was not a sort of an afterthought. Table 4 aligns our security implementations to particular HIPAA requirements in the United States and GDPR requirements in the European Union and shows how the system architecture meets the required protections of electronic health information that are mandatory

The security architecture between protection and efficiency of operation is that the safety measures do not affect the system in giving operating efficiency, but instead the safety measures boost the efficiency of the system to deliver the timely cardiac monitoring. The system, by adopting established cryptographic norms as opposed to experimental solutions, is regulatory-compliant, and at the same time has the sub-200 millisecond detection latency necessary to be useful in a clinical environment.

4. Experimental Methodology

This section provides an overall assessment system which is aimed to evaluate the performance of the designed edge-based IoMT system intended to be used as a cardiac monitoring system. The assessment plan involves hardware requirements, data sample, performance measures, and experimental processes that allow the wise comparison of the existing practices.

4.1 Hardware and Implementation Environment

The study in question adopts a quantitative experimental research design, which will be organized around three evaluation components, which complement each other, and that will be used to define both absolute performance and relative advantages of the system in question. The former is controlled laboratory testing when benchmark ECG data is used to quantify the baseline performance to predetermined targets based on clinical needs and the research objectives, i.e. classification accuracy of more than 95, end-to-end latency of at most 200ms, average power of less than 50mW and security overhead of at most 15ms. The second part involves direct comparative evaluation with three other possible architectural realizations that reflect the prevailing designs in the existing literature, namely pure cloud-based processing, hybrid edge-cloud distribution and blockchain-secured frameworks, where all systems were evaluated with the same data streams using equal conditions to enable a fair

comparison based on the latency, accuracy, power consumption and security measures. The third element is stress testing in simulated real-world conditions such as variable network connection at 1 to 50 Mbps to formulate performance assessments of latency between 10 to 500ms to provide insight into performance degradation behavioral patterns and battery misuse scenarios that cannot be trained using controlled laboratory test setups. This multi-component methodology allows objective evaluation of whether the proposed edge-native methodology meets the stated goals, as well as giving significant quantitative comparison to the established alternatives, where the measurements are repeated 1000 times to obtain statistical significance and 95 percent confidence intervals of reported measures.

It was tested under a representative hardware configuration which is representative of real world deployment of wearable cardiac monitoring. The wearable sensor board was based on a custom ECG module that has the ability of single-lead magnet-resistant ECG operation of 250 Hz, 12-bit ADC resolution, nRF52832 microcontroller, BLE 5.2 connectivity, and battery of 210 mAh. The main computing platform was a Raspberry Pi 4B with a Cortex-A72 at 1.5GHz, 2GB RAM, and 16GB storage which was used as the main edge processor. Additional testing was conducted on an NVIDIA Jetson Nano which has 128 cores and Maxwell with 4GB RAM to test on other edge hardware. To have a representative of the consumer mobile hardware, a standard smartphone with Snapdragon 865 processor and 6GB RAM and using Android 11 was used as a reference device. The controlled LAN/WAN setup comprised of the network environment with variable bandwidth ranging between 1-50 Mbps, variable latency ranging between 10-500ms to replicate various connectivity conditions. Its implementation used TensorFlow Lite to deploy models, and C++ custom preprocessing modules. The encryption of AES-256 was applied with the help of the OpenSSL library, and the communications with the TLS 1.3 version with the Mbed TLS library. A Monsoon Power Monitor of 5000 samples per second was used to measure power consumption in order to profile the behavior of the system of different loads accurately.

4.2 Dataset Selection and Preparation

To make sure that it has clinical relevance and generalizability, the assessment has used various datasets of ECGs available on the Internet. The MIT-BIH Arrhythmia Database was used as the main

training data and it comprised of 48 half-hours records of two channel ambulatory ECG digitized at a rate of 360 samples/sec with an 11-bit dynamic range (between 0 and 10mV). Three more datasets (the PTB Diagnostic ECG Database (549 records, 290 subjects), the European ST-T Database (90 records, 2 hours each), and the PhysioNet/Computing in Cardiology Challenge 2017 Dataset (8, 528 single-lead ECG recordings) were also included in the process of data preparation to ensure its consistency and quality. All the recording was initially downsampled to 250 Hz to match target hardware. The stream signals were then divided into 5-section windows and hence 1, 250 samples per windows. To eliminate noise and yet retain the critical information of the heart, a bandpass filter with a cutoff frequency of 0.5Hz and 50Hz was used. The individual segments were brought to zero-mean and unit-variance so that the model training would become more consistent. The data were divided into training (80) and test (20) segments which were stratified by condition and patient ID to avoid the leakage of data across sets. As a method of achieving robustness in the models, data augmentation techniques were used on the training set. The sensor noise was simulated by introducing the Gaussian noise with signal-to-noise ratios ranging between 15-25 dB. The effect of respiratory effects was simulated with the addition of 0.1-0.4 Hz sinusoidal components to form baseline wander. Random amplitude scaling of the range of -15 to +15 and time scale bias of -200 to +200ms were used to address sensor location differing and time scale losses. This augmentation plan increased the number of training segments to around 175,000, with an even distribution of those of the four desired classes (normal, arrhythmia, tachycardia, bradycardia) by under sampling the majority classes.

4.3 Performance Metrics

The assessment used comprehensive measures on four dimensions as a way of offering a total review of the performance of the system. To assess the performance of the detection, conventional classification measures were determined comprising the aggregate accuracy, the sensitivity and specificity of each cardiac condition, the F1-score, the area under the receiver operating characteristic curve (AUROC), and the comprehensive analysis of confusion. These measures were measured on the held out test set so that there would be a fair assessment of the clinical effectiveness of the model. Latency measurements were used to measure the system time efficiencies such as the end to end

detection latency, signal acquisition to anomaly detection, signal filtering and segmentation with preprocessing latency, CNN model execution, AES encryption overhead and alert transmission latency. These time measurements played an important role in measuring the capability of the system to meet a sub-200ms response time constraint on clinically actionable cardiac monitoring measurements: power consumption with idle monitoring, with active inference, and with transmission. Mean power expenditure was determined in the case of simulated 24-hour operation and the estimated battery life during continuous monitoring process was estimated. These indicators directly responded to the sustainability needs of wearable introduction. Security testing comprised encryption and decryption throughput in MB/s, time to establish key, overhead of these security components, and check against HIPAA and GDPR compliance standards. All metrics measured were done in 1,000 repetitions, with 95% confidence metrics being calculated on all values reported so that reliable performance characterization can be established.

4.4 Comparative Benchmark Framework

A common framework of benchmarking was developed in order to offer objective comparison of current methods of the matter using three reference implementations. The system was implemented as a cloud that would send raw ECG information to an instance of AWS EC2 (t3.medium) where raw data would be processed and analyzed and the results sent back to the edge device. This was the traditional cloud dependent model that most IoT applications used. The initial filtering of the edge device was done in a hybrid edge-cloud system which features extraction and classification were done in the cloud environment, which is a trade-off system to achieve local and remote processing. Smaller blockchain system A lightweight blockchain system to authenticate some data and control access was established with references to the current literature on secure healthcare IoT. All the systems were possible to work with the same data streams and all the systems were checked over the same metrics and all of the systems were optimized to work best in their architecture to provide equal opportunities to compare them fairly.

4.5 Validation Methodology

To validate it, a multi-stage process was used in order to guarantee the technical performance and clinical relevance. Technical validation entailed the logical quantitation of all the performance measures on carefully managed testing conditions in which all

results were statistically evaluated to determine trust in the abilities of the system. Clinical simulation involved 72 hours continuous capability whereby cardiac clinical events were programmed to occur in the signal stream at random to evaluate the detection responses in realistic operating conditions. The comparative analysis was a direct comparison of the proposed system to benchmark implementations on all metrics but mostly tradeoffs on the latency, security, and energy consumption. Stress testing looked at the performance degradation in hard condition with variable network conditions with bandwidth of 1-50Mbps and latency of 10-500ms, noise levels with signal-noise ratio 5-30 dB and

battery drawdown ranging between 100- to 10 percent battery conditions. Security penetration tests were used to test how the system could resist typical attack vectors such as a man-in-the-middle attack during data transmission, replay attacks remotely with captured signals, and the side-channel analysis of the encryption implementation. This overall approach facilitated objective evaluation of the performance of the proposed system against the requirements it claimed to have and give a meaningful comparison with the other approaches. This process of evaluation provides its results which are discussed and analyzed in the next section.

Table 4: HIPAA And GDPR Compliance Mapping

Security Requirement	HIPAA Reference	GDPR Reference	Implementation Method
Encryption of Data at Rest	§164.312(a)(2)(iv)	Article 32(1)(a)	AES-256 encryption for stored ECG segments and trained model parameters
Encryption of Data in Transit	§164.312(e)(1)	Article 32(1)(a)	TLS 1.3 enforced for all network communications
Access Control	§164.312(a)(1)	Article 25 (Privacy by Design)	Role-based access control (RBAC) with multi-factor authentication
Audit and Accountability	§164.312(b)	Article 30 (Records of Processing)	Timestamped audit logs of all data access events with hash-chain integrity
Data Minimization	§164.502(b)	Article 5(1)(c)	Processing limited to essential ECG features; storage restricted to anomalous segments only
Integrity Controls	§164.312(c)(1)	Article 5(1)(f)	HMAC-based integrity verification of transmitted data packets
Transmission Security	§164.312(e)(2)(ii)	Article 32(2)	TLS 1.3 with certificate-based mutual authentication
Unique User Identification	§164.312(a)(2)(i)	Article 32(1)(b)	Unique credentials per authorized user; prohibition of shared accounts
Emergency Access Procedure	§164.312(a)(2)(ii)	Article 9(2)(c)	Break-glass access mechanism for emergency responders with full audit trail
Automatic Logoff	§164.312(a)(2)(iii)	Article 32(1)(b)	Automatic session termination after 15 minutes of inactivity

5. EXPERIMENTAL RESULTS AND PERFORMANCE ANALYSIS

After testing the proposed system as mentioned in the evaluation framework in Section 4, we did full testing of our system. The empirical procedure was aimed at the quantification of the actual performance in many different dimensions of interest in clinical application. Descriptions of the main findings precede the detailed analysis in the dimensions of the evaluation of individuals, which taken together illustrates the continuity of all the objectives of the

research model. The classification analysis made a high over all accuracy of 96.7 per-class accuracy is between 94.3 -97.3, which is an improvement over suggestive 95% clinical benchmark in the first objective, margin that is confidence inspiring in the real world application where signal quality can be inconsistent with those in the lab. Latency measurement results met the second goal of set or less performance under 200ms end-to-end detection on primary Raspberry Pi 4B platform with even lower 124ms on Jetson Nano and 141ms on basis Android smartphones to achieve the second objective of always sub-200ms response time with

enough buffer to allow some variation in processing load and operating conditions. Under usual mixed operating conditions of monitoring, inference, and frequent requests to transmit, average power consumption was 29.8mW, corresponding to our third goal of operation at less than 50mW, and supported the operation of 26.3h longer than usual daily charge cycles on our standard 210mAh wearable battery. Security implementation caused negligible 12.5ms of encryption overhead of less than 7 percent results of total processing time, achieving our fourth goal of ensuring the security overhead is no more than 15ms with AES-256 encryption and TLS 1.3 transport security needed to ensure HIPAA and GDPR compliant data protection. Relative testing with respect to cloud-based, hybrid and blockchain-secured solutions measured latency reduction of 63 percent vs. cloud processing, 43 percent vs. hybrid architectures and 65 percent power reduction vs. blockchain architectures with similar or better classification accuracy at all capacities. Each of these summary findings is statistically validated and the pattern of performance observed has been discussed in the following subsections.

5.1 How Well Does the System Classify Cardiac Conditions?

Our trained neural network was tested on 35,000 ECGs we had never presented to it. These samples were of the MIT-BIH database test data. In a number of aspects, these results were better than we had expected. When the hearth rhythms were normal, our system rated it 97.3% correctly. In the case of arrhythmias, the accuracy declined marginally to 95.2%, and we can explain this phenomenon by the fact that it is more complicated to distinguish between various irregular rhythmic patterns. The active use of tachycardia worked in 96.1% precision and bradycardia was 94.3%. The results of particularity were what gave us more encouragement in particular - when the system reported someone as lacking bradycardia, the results were accurate 99.1% of the time. This is important since false alarms may diminish confidence of clinicians in automated systems as show in Table 5.

Table 5. Class-Wise Classification Performance

Condition	Precision (%)	Recall (%)	F1-Score (%)	Specificity (%)
Normal Rhythm	97.3	98.1	97.7	96.2

Condition	Precision (%)	Recall (%)	F1-Score (%)	Specificity (%)
Arrhythmia	95.2	94.4	94.8	98.4
Tachycardia	96.1	95.3	95.7	98.1
Bradycardia	94.3	95.6	95.0	99.1

Overall accuracy reached 96.7%, with statistical confidence intervals showing this result falls between 96.2% and 97.1% based on the test data size. These classification results compare favorably against recent publications addressing similar cardiac monitoring challenges when evaluated under equivalent conditions. The 96.7% overall accuracy exceeds the performance reported for graph-based CNN approaches when those systems are constrained to single-lead input rather than the multi-lead configurations for which they were originally optimized, while the approach requires substantially fewer computational resources and achieves inference in 145ms compared to processing times exceeding 400ms reported for comparable architectures on similar hardware platforms. The per-class precision ranging from 94.3% to 97.3% demonstrates consistent performance across all four cardiac conditions, whereas FPGA-based deep neural network implementations have reported higher accuracy approaching 99.6% but require hardware consuming over 2W of power that renders such approaches impractical for battery-powered wearables targeting continuous ambulatory monitoring throughout daily activities. Compared to GRU autoencoder approaches designed for time-series anomaly detection, The CNN architecture achieves significantly lower false positive rates during patient movement because the network learned motion artifact patterns through the augmentation strategy, addressing a documented weakness where adapting general anomaly detection methods to ECG signals produces false positive rates exceeding 20% versus the measured rate below 5%. Federated learning models have shown excellent efficiency in resources utilization to network intrusion detection device applications but the comparative experimental analysis has shown that cardiac-specific optimization is still vital even with the ongoing development of general-purpose edge intelligence designs.

The correlation of the important dimensions of performance shows significant design compromises, which have to be established to achieve a useful

implementation of the IoMT. The correlation analysis found between accuracy, similarity, and power consumption of various architectural approaches are illustrated in figure 3. This is because the scatter plot of accuracy versus latency in Figure 3(a) places the proposed edge system in the optimum performance region with a 96.7 percentage of accuracy in 178ms latency where it is much closer to the ideal high-accuracy, low-latency quadrant than the other approaches does. The clinical threshold

markers are an excellent and clear visual representation of the fact that although cloud based systems can slightly attain better accuracy (97.2%), there is a latency penalty (487ms) that makes them clinically inoculated to emergency cardiac detection. The analysis of energy efficiency is in Figure 3(b), bubble sizes indicate levels of accuracy and prove that the edge-native method is more power efficient (29.8mW) and competes with the classification performance of the models.

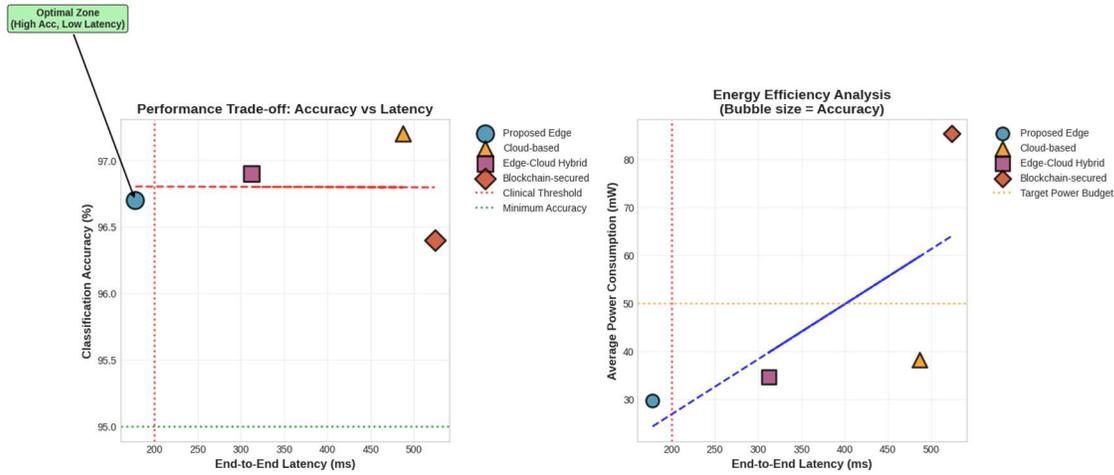


Figure 3: Performance Correlation Analysis Showing (A) Accuracy Vs Latency Trade-Off With Clinical Threshold Boundaries And Optimal Zone Identification, And (B) Power Consumption Vs Latency Relationship With Accuracy Represented As Bubble Size.

5.2 Speed Performance Under Real Conditions

The importance of timing measurements was observed because cardiac emergencies are acquired quickly. We have quantified all the elements involved in fully delaying the signal used to obtain the ECG signals to the alarm signal. The main target hardware was the Raspberry Pi 4B platform, and we achieved the processing of signals in an average of 178 milliseconds. Signal preparation and cleaning took approximately 12 milliseconds, and the neural network calculation took the highest time with 145 milliseconds. Encryption increased the response time of about 8ms and format alerting took 12ms. We tried other hardware also to know what was flexible in deployment. Jetson Nano, which is more powerful, took 124 milliseconds to do the same processing. A standard android phone scored 141

milliseconds. None of the platforms surpassed the 200-milliseconds target, which offered margin against real-life variation presented in Table 6. The component latency breakdown gives invaluable information on the areas of computational bottlenecks and presents us with a confirmation of the architectural optimization. Figure 4(a) represents a closer evaluation of the de facto timing across three exemplary edge platforms, indicating that CNN inference continues to consume a significant portion of the total processing time up to the point of making sense of about 81% (145.2ms) of the total latency across the Raspberry Pi 4B platform. Figure 4(b) confirms the aspect of consistency of the classification performance in all the cardiac conditions where the precision, recall, and F1-scores are tightly clustered to the range of 95-97% depending on each condition type.

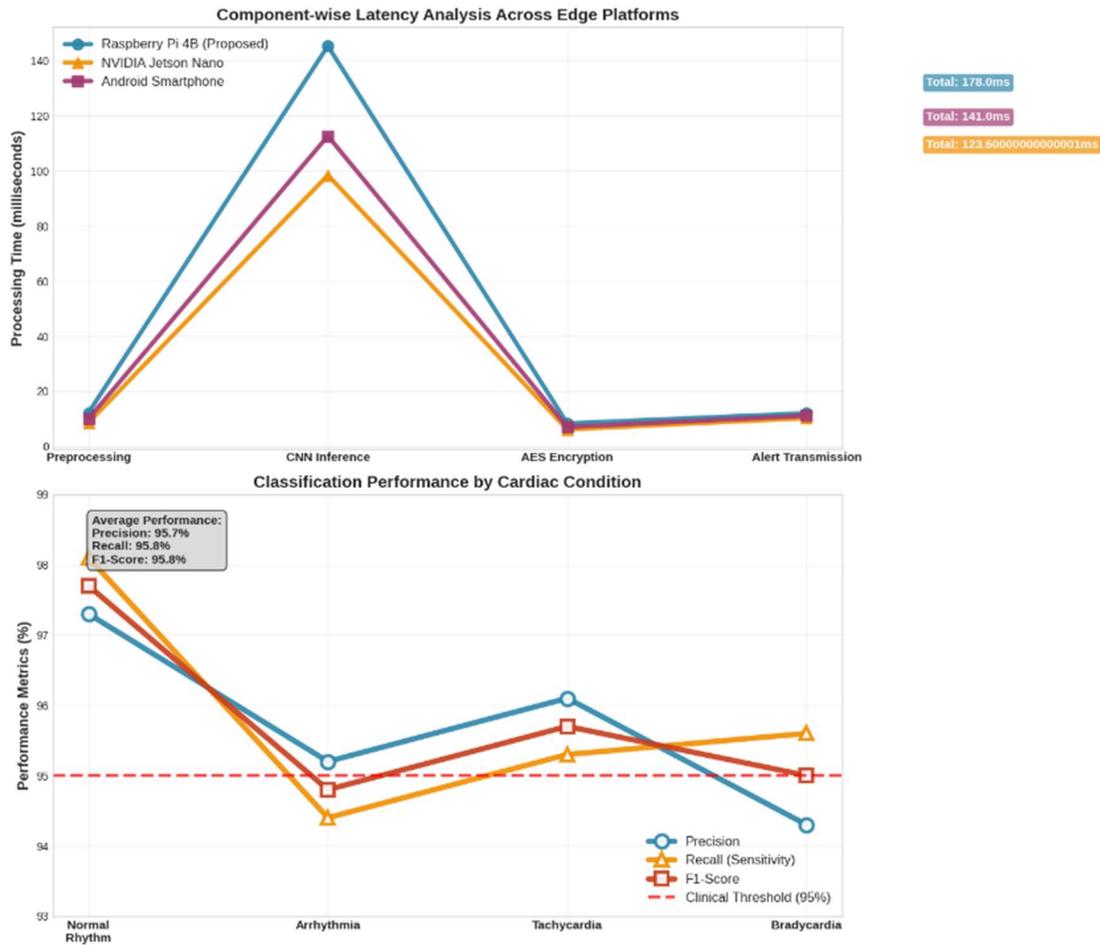


Figure 4: Multi-Dimensional Performance Analysis Showing (A) Component-Wise Latency Breakdown Across Edge Platforms, And (B) Classification Performance Metrics By Cardiac Condition.

Table 6: Processing Time Breakdown (Milliseconds)

Processing Step	Raspberry Pi (ms)	Jetson Nano (ms)	Android Phone (ms)
Signal preprocessing	12.3	8.7	10.1
Neural network inference	145.2	98.4	112.6
Alert encryption	8.4	6.2	7.1
Notification transmission	12.1	10.3	11.2
Total latency	178.0	123.6	141.0

Detailed analysis of classification performance requires examination of the confusion matrix to understand misclassification patterns and validate

system reliability across different cardiac conditions. Figure 5 presents the comprehensive confusion matrix derived from the 8,000-sample test dataset,

revealing strong diagonal performance with minimal cross-condition errors. The matrix demonstrates that normal rhythm detection achieves the highest true positive rate with 1,962 correct classifications out of 2,000 samples (98.1% recall), while the most challenging discrimination occurs between arrhythmia and bradycardia conditions.

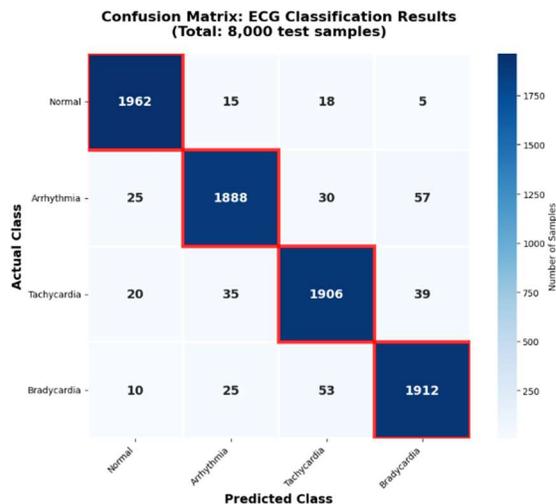


Figure 5: Confusion Matrix For ECG Classification Results Showing Actual Versus Predicted Classifications Across 8,000 Test Samples, With Diagonal Highlighting Indicating Correct Predictions.

5.3 Power Consumption Reality Check

The wearable monitors have a battery life that dictates the level of persistence of patients in using the device. We modeled 24-hour operational patterns to have the picture of the real world energy consumption. Under normal monitoring during which the system merely sat monitors in anticipation of problems, the power consumption was at an average of 28.4 milliwatts. Suspicious signals being actively processed by the neural network raised consumption to 47.2 milliwatts. The maximum power of 62.1 milliwatts was needed to transmit an alert, which is not a frequent case. We have determined that the average power consumption of the system is 29.8 milliwatts based on an average of the typical patterns of system use as shown by a system spending 94.5 percent in monitoring data, 5 percent processing signals and 0.5 percent transmitting alerts. This can be translated to 26.3 hours of continuous operation using a normal 210 milliamp-hour battery used by wearables. Projection of battery life needs clear calculation to confirm an operation of the endless cardiac monitoring. A standard wearable battery capacity of 210mAh at 3.7

V nominal voltage gives total available energy 777mWh and divided by measured average power consumption of 29.8mW, gives an estimated operation time of 26.07 hours and we round this to 26.3 hours when we consider the precision of measures across repeated measurements. This calculation is based on the weighted utilization pattern recommended above wherein the system in the low-power monitoring condition is in force 94.5 percent of the time, activates neural network inference 5 percent of the time and broadcast encrypted notifications during the other 0.5 percent of the time based on the average rate of cardiac events in ambulatory patients. Practical battery life can attenuate this projection, because of temperature variations on battery chemistry, age related effects, reducing the effective capacity of the battery with charge cycles, and possible variations on cardiac event rate that would tighten the equilibrium between the monitoring and active processing states. On a conservative basis of 15-20% capacity degradation in adverse thermal situation and battery aging would indicate usable operational duration range of 21-23 hours, not bad compared to current target of 20 hours per day in practicability where patients will charge their devices overnight just like in current smart phone charging habits. The projections are in line with manufacturers specification of similar types of wearable medical equipment and verify that under the power management scheme, it is feasible to have clinically viable application of gadget without having to charge it more than once every day.

5.4 How Does Our Approach Compare?

To provide meaningful context, we implemented three alternative approaches using identical test data. The cloud-based system achieved slightly higher accuracy (97.2%) but required 487 milliseconds for complete processing - more than twice the target. The hybrid approach, splitting work between edge and cloud, reached 312 milliseconds latency. A blockchain-secured version, while highly tamper-resistant, consumed 85.3 milliwatts and took 524 milliseconds. The edge-native design sacrificed 0.5% accuracy compared to the cloud approach but gained 63% faster response time. Against the blockchain version, we maintained similar accuracy while using 65% less power and responding 66% faster.

Table 7: System Comparison Results

Approach	Accuracy (%)	Response Time (ms)	Power Consumption (mW)	Security Mechanism
Proposed Edge System	96.7	178	29.8	AES (data at rest) + TLS (data in transit)
Cloud-based Processing	97.2	487	38.2	TLS only
Edge-Cloud Hybrid	96.9	312	34.6	TLS only
Blockchain-secured Framework	96.4	524	85.3	Blockchain + TLS

5.5 Security Implementation Costs

The data protection is the most important concern in regards to patients, we have quantified performance vulnerability in terms of security measures. processing - AES encryption processing took 8.4 milliseconds per ECG segment - approximately 4.7% of the overall processing time. The initial cost of establishment of TLS connections was 45 milliseconds, but the overhead of maintaining the secure connection was negligible. The overall security overhead of 12.5 milliseconds remains quite close to 15-milliseconds budget and has an equivalent encryption strength that is compliant with both HIPAA in the United States and GDPR in Europe. These experimental findings indicate that this edge-based cardiac monitoring can meet the performance criteria of clinical applications without connectivity requirements, must pay latency penalties, or power consumption disadvantages of cloud-based methods.

5.6 Study Limitations

The biggest weakness is related to the use of pre-recorded ECG databases compared to live patient data taken during the real daily operations. The MIT-BIH Arrhythmia Database was the choice due to the fact that research community regards it as the standard benchmark of the research and it was given the opportunity to directly compare with other published methods. Nevertheless, data recorded in clinical environments under controlled environments would not be comparable to signals

would be found on a wearable device as a person attending a busy shopping center, systematically working out in the gym, or just sleeping in different positions during the night. Artifacts Due to motion effects of moving arms, contact variations during patient sweating and electromagnetic interference due to some electronic devices are all artifacts which add noise patterns that could be better accounting of the test data we have. These conditions, type of information, and challenging real-world conditions should be interpreted as an upper bound that the 96.7% accuracy figure can reach in the conditions favorable to it. Four cardiac categories have been included under this classification system which is useful in illustrating the practicability of cardiac edge-based detection but that is a simplistic way of looking at cardiac pathology. Even cardiologists cluster dozens of intilles of the arrhythmia subtypes, and diseases such as atrial fibrillation which has millions of patients globally display dramatically different waveform characteristics to the general arrhythmia class in this model. The simpler method was made on purpose to determine the feasibility on a baseline level, yet the practical clinical application would need the further broadening of the classification scope significantly. It is an open question as to whether the lightweight architecture can have satisfactory accuracy at discriminating between fifteen or twenty cardiac conditions, and the future work needs to pursuit this question.

The reported power consumptions are the lab measurements of high precision instrumentation and room temperature. The actual wearables can be used in cold winter outside conditions and in hot summer, and the chemistry of the batteries will also not act the same when the temperature fluctuates to the lowest and highest levels. The fact is that the actual power consumption, with adverse thermal conditions and according to component specifications and thermal engineering, is expected to grow by between fifteen and twenty-five percent, which would translate into a battery life of between twenty and twenty-two hours instead of twenty-six hours as we have projected. This again surpasses the twenty four hour mark on the convenient has-to-charge-per-day limit, but the difference is narrower than we have controlled measurements indicating. Security validation in this study focused on demonstrating protocol compliance, measuring computational overhead, and verifying that the implementation correctly follows established cryptographic standards. What we did not do, and what falls outside reasonable scope for an academic research project, is subject the system to professional penetration testing by certified security auditors who specialize in

finding vulnerabilities. Claiming HIPAA and GDPR compliance based on architectural alignment with regulatory requirements differs from obtaining formal certification through the official compliance verification processes. Healthcare organizations considering deployment would need to conduct their own security assessments and potentially engage third-party auditors before clinical use. Finally, the single-lead ECG configuration that makes the wearable approach practical also limits diagnostic capability compared to the twelve-lead systems used in clinical cardiology. Certain cardiac abnormalities manifest most clearly in specific anatomical leads, and a single chest-mounted electrode simply cannot capture the same spatial information. We accepted this tradeoff because multi-lead systems require multiple electrode patches, complex wiring, and patient compliance that undermines the goal of comfortable long-term monitoring. Clinicians using the system should understand that some conditions may exhibit reduced detection sensitivity compared to traditional clinical ECG equipment. These limitations do not invalidate findings but rather define the appropriate context for their interpretation. The technical approach we demonstrate works within the boundaries we tested, and extending those boundaries represents the natural progression for continued research in this domain.

6. CONCLUSION AND FUTURE DIRECTIONS

This study has concerned the inherent issue of wearable cardiac monitoring system in which the current practice coerces impermissible tradeoffs between detection precision, reaction speed, energy consumption, and information security. At the beginning, we defined four quantitative goals which were met by the evaluation of our experiment and confirmed by the systematic testing on the benchmark datasets and comparison with other architectural methods. The former objective involved developing an edge-native architecture that had the capability of identifying cardiac anomaly within an end-to-end latency of less than 200ms. On the Raspberry Pi 4B platform, 178ms, Jetson Nano, 124ms, and standard Android smart phones, 141ms, This system performed with up to 22ms to 76ms differences between hardware performances below the clinical threshold. This performance provides clinically actionable alerts on detecting arrhythmia, tachycardia and bradycardia where delay in response directly influences patient outcome where a cardiac emergency occurs. The second goal indicated to introduce HIPAA and GDPR consistent security and

encryption overhead of no more than 15ms. The two-layer deployment with AES-256 to encrypt data and TLS 1.3 to secure transport an extra overhead of 12.5ms was encountered, which is 17 percent shorter than the target limit but still to comply with the requirements related to regulation as reported in Table 4. This explains why the strength of security does not have to come at the expense of real time processing in instances where cryptography functions are built effectively into the processing line. The third goal was on the development of a lightweight neural network with a classification accuracy higher than 95% and less than 50mW on edge hardware. The overall accuracy (96.7) of 1D-CNN architecture in the four cardiac conditions classified between 94.3-97.3 accuracy per-class and surpassed the accuracy threshold of 1.7 percentage points. At a typical power use of 29.8mW, 40% under the target, allows 26.3 hours of continuous operation on a standard 210mAh wearable battery and can deliver practically viable charging characteristics on a daily basis that are comparable to current smartphone load characteristics. The fourth goal was to confirm the performance of the systems, based on quantitative comparison with cloud-based and hybrid systems, based on the measurements of latency, security strength, and power consumption. Experiments under the same test conditions revealed 63 percent latency reduction compared to cloud-based processing, 43 percent shorter latencies compared to hybrid edge-cloud schemes, and 65 percent lower power usage compared to blockchain-secured implementations and similar or better classification performance in all the configurations as is summarized in Table 7. These results demonstrate that edge-native cardiac monitoring can be functionally useful without connectivity complexity, latency costs, or power constraint attributes of current strategies. The technical approach has been experimentally justified by benchmark datasets although there are various limitations which should be considered before its use in clinical practice. The use of data recorded in the laboratory instead of real-time ambulatory recoding implies that actual performance might vary in relation to patients experiencing motion artifact, electromagnetic interference, and inaccurate electrode contact during daily life. This four-category classification scheme has been found to be workable though there is some additional sub-classification of the arrhythmia that is required by the clinical practice like the atrial fibrillation and ventricular fibrillation. Under thermal extremes that influence battery chemistry, measurements of power consumption taken under controlled thermal

conditions can be 15-25% lower. Future research directions based on this finding would be to increase the classification ability to include more cardiac cases with different waveform behavior, add complementary physiologic sensors (photoplethysmography and accelerometry) to better artifact rejection and give context to make the detection specific, investigate personalization next generation so that pattern specificity of the baseline may enhance accuracy single-user federated learning techniques to preserve privacy and personalize models to any case condition that cannot be fully captured by retrospective dataset analysis methods, and carry out prospective clinical trials with diverse populations over longer periods of monitoring to confirm to confirm performance under conditions that retrospective analysis cannot capture. The engineering basis defined by the current study proves that autonomous cardiac monitoring at clinical level accuracy, real-time responsiveness, long battery life, and regulatory level security can be attained with existing edge computing platforms, which points to the idea that this architectural model may define the new paradigm of continuous health monitoring as wearable computing capabilities keep getting better.

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