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ROUTING METHOD IN MULTI DOMAIN SOFTWARE DEFINED NETWORKS

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ABSTRACT

This article examines the issues of routing in multi-domain software-defined networks (SDN) of large size. The advantages of routing with the help of software-defined networks technology are given. The expediency of using multipath routing in computer networks of large size is justified.

A method for dividing the network into domains by the *k*-means method is proposed. The division of the network into domains and the use of intra-domain and inter-domain routing can reduce the time complexity of routing. A centralized routing information method in the SDN controller is proposed.

A modified algorithm for multipath routing along the distance vector is proposed and substantiated. In the routing process, with the formation of a given route, routes from all intermediate sites to the destination node are formed simultaneously. This eliminates the repeated formation of routing information for the previously formed paths.

Algorithms for inter-domain and intra-domain multipath routing are proposed to simplify the re-routing procedure if the network topology changes.

Keywords: Multipath Routing, Software-Defined Networking; SDN controller, Routing domains, Domain controller, Time Complexity, Routing Algorithm, Distance Vector, re-routing

1. INTRODUCTION

Modern computer networks are characterized by large dimensions and a diverse composition of equipment. In this regard, the managing process of this type of networks becomes more complicated particularly, routing and traffic engineering. To solve such problems, software-defined networking (SDN) technology is currently used [1]. In work [2], [3] several methods and approaches were used to solve the problems of optimizing data traffic in networks using SDN. Compared with the traditional networks, routing in SDN has the advantage that the formation of routes is held centrally in the SDN controller, so more efficient routing process is achieved. The routing information for the SDN switches are updated by the SDN controller which also updates the routing tables for these switches to choose the best route based on the specified QoS criteria. Compared to distributed routing methods, the service information in centralized method doesn't need to be exchanged between network switches, result in reducing the number of control packets in the network by 60-70% [4], [5].

One controller can manage a limited number of switches. This creates problems with scalability, reliability, and network availability [6]. A distributed controller architecture was used to solve these problems, the controller can be either a distributed (flat) or hierarchical architecture, where each controller is responsible for its own domain and updates either neighboring controllers or the root controller [7]. Figure 1 shows a hierarchical twolevel domain structure of the SDN network [8]. The use of routing between domains and within domains can reduce the time complexity of routing.

Multiple paths are always found between sourcedestination pairs in large networks. This allows you to organize multipath routing. Multipath routing allows to increase the performance of the network by 10-15% by decreasing the service packets volume [9], [10]. As a result, the use of multipath routing <u>15th July 2022. Vol.100. No 13</u> © 2022 Little Lion Scientific

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allows you to quickly reroute after failures of links and network switches [11].



DC - domain controller; NC - network controller

Figure 1: Two-layer domain structure of the SDN network

The method of centralized formation of routing information makes it possible to exclude the repeated formation of routes between intermediate sections of the generated path [12], [13].

Work [14], proposed a method for balancing traffic, which, according to the centralized method of generating routing information in the SDN controller and using multipath routing, makes it possible to simplify the traffic reconfiguration procedure and ensure the most uniform network load. Wave routing algorithm is used to generate Routing information. At the same time, paths between all intermediate nodes and the final node are formed simultaneously. This makes it possible to simplify the procedure of forming routes between intermediate nodes of previously formed routes [15].

Thus, the use of centralized algorithms for multipath routing within domains and between

domains will improve the efficiency of a large SDN network. To do this, it is necessary to divide the network into the optimal number of domains and develop an efficient centralized interdomain routing algorithm

2. ROUTING METHOD IN A TWO-LAYER SDN NETWORK

Large SDN networks are divided into domains [16], [17].

The optimal division of the network into domains affects the efficiency of its function. The division of the network into domains is carried out using the *k*-mean method.

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The number of domains is determined based on the average degree of vertices of the network graph and its diameter. The average number of vertices in domains is determined by the ratio of the total number of vertices to the number of domains. As the controller (Ci) of the domain Di, vertices with the maximum degree and equidistant from each other are selected.

For example, the network (Figure 2) is divided into domains $D_1 = \{S_1, S_2, S_3, S_4, S_5, S_6, S_{14}\}, D_2 = \{S_7, S_8, S_9, S_{10}, S_{11}, S_{12}, S_{13}\}, D_3 = \{S_{15}, S_{16}, S_{17}, S_{18}, S_{19}, S_{20}, S_{23}, S_{25}\}, D_4 = \{S_{21}, S_{22}, S_{24}, S_{26}, S_{28}\}$. In this case $C_1 = S_4$; $C_2 = S_9$; $C_3 = S_{19}$; $C_4 = S_{24}$. The starting vertex (S_s) and the final vertex (S_n) of the path $P_i(S_s,S_n)$ can be in the same or in different domains. Therefore, routing in multi-domain networks is carried out separately between domains and within domains. Routing between domains and within domains is based on a modified multipath routing algorithm [18-21]

With inter-domain routing, based on the link table between domains (Table 1), a set of virtual paths is formed between domains in the network controller.



Figure 2: Structure of a domain computer network

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			D_{I}				D_2					D3				D_4	
		S5	S6	S14	S 8	S_{10}	S11	S12	S13	S15	S16	S17	S20	S23	S21	S22	S25
	S_5				0.4												
D_l	S_6					0.1				0.1							
-	S_{14}										0.3						
	S_8	0.4															
	S10		0.1							0.1							
	S_{11}															0.1	
D_2	S_{12}													0.1			
	S13														0.1		
	S_{15}		0.1			0.1											
	S_{16}			0.3													
	S_{17}																0.1
Dз	S_{20}																0.1
	S23							0.1							0.5		
	S21								0.1					0.5			
D_4	S22						0.1										
	S_{25}											0.1	0.1				

Table 1: Relationship between adjacent domains

For example, between domains D_1 and D_4 , virtual paths go through domain D_2 or D_3 . Virtual paths pass through domain $D_2 P_1(1,4) = S_5 \rightarrow S_8 \rightarrow S_{11} \rightarrow S_{22}$; $P_2(1,4)=S_5 \rightarrow S_8 \rightarrow S_{13} \rightarrow S_{21}$; $P_3(1,4)=S_6 \rightarrow S_{10} \rightarrow S_{11} \rightarrow S_{22}$; $P_4(1,4)=S_6 \rightarrow S_{10} \rightarrow S_{13} \rightarrow S_{21}$. Virtual paths pass through the D_3 domain $P_5(1,4)=S_6 \rightarrow S_{15} \rightarrow S_{23} \rightarrow S_{21}$; $P_2(1,4)=S_5 \rightarrow S_8 \rightarrow S_{13} \rightarrow S_{21}$; $P_3(1,4)=S_6 \rightarrow S_{10} \rightarrow S_{11} \rightarrow S_{22}$; $P_4(1,4)=S_6 \rightarrow S_{10} \rightarrow S_{13} \rightarrow S_{21}$.

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The network controller contains information about the set of vertices in each domain. Based on this information, the network controller determines the domain in which the final vertex S_n of the generated path P_i (S_s , S_n) is located. Then, based on the link table between adjacent domains (Table 1), the network controller selects the optimal path between domains with the initial and final vertices of the path P_i (S_s , S_n). Given the importance of ensuring the reliability and quality of data transmission in real time, this paper considers a routing method taking into account the delay metric in communication channels.

Then in each domain controller $D_j \in P_i(S_s, S_n)$ optimal non-intersecting paths are formed inside the

domains between the boundary vertices on the path $P_i(S_s,S_n)$. Paths are formed using a wave algorithm based on the distance vector.

In this case, the paths between the initial and all intermediate switches are simultaneously formed, eliminating the repeated formation of paths from the initial switch to the intermediate and final switches.

Sequential formation of paths between adjacent sets of vertices W_i and W_{i+1} . The adjacent set of vertices means the sets of vertices $W_i = \{S_i \mid i = I, i = I\}$ 2, ..., n } and $W_{i+1} = \{W_i \mid j = 1, 2, ..., n\}$, with a common set of edges $Es = \{e, where: s_i \in S_{i+1}\}$ and $sk \in S_i$. The formation of paths starts from the graph vertex S_s corresponding to the destination S_d at i = 1. Here, the set $S_1 = \{s_d\}$, and the set $S_2 = \{s_i\}$ is the set of vertices that are adjacent to the vertex s_d . Then for each commutator S_j corresponding to the vertex $s_i \in S_2$, adjacent to s_d , is entered in its route table. The formation of routes from the vertices $S_i \in$ W_i to the vertices of $Sk \in W_i$ takes place in the second routing wave. Resulting in the formation of route tables of switches S_i for vertices $s_i \in S_{i+1}$, and so on until all paths between the vertices S_s and S_d are formed.

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For each formed path $P_i(S_s, S_n)$ the distance vector $R_i(S_s, S_n) = \{S_a, M_i\}$ is set. S_a is the vertex adjacent to the vertex S_a on the path $P_i(S_s, S_n)$, M_i is the metric of the path $P_i(S_s, S_n)$. The value of the distance vector is entered into the table of distance vectors (Table 2).

Table 2: Distance vectors of the commutator S_j

Destination	Adjacent vertex	Metrics Way
S _d	S_j	M_{l}
S _d	S_r	M_2

Consider the formation of distance vectors for the path $P_i(S_1, S_5)$. In Table 3, the values of the transmission delay between adjacent nodes of the cluster are given as a metric.

Table 3: Metrics of communication channels

	S_{I}	S_2	S_3	S_4	S_5	S_6	<i>S</i> ₁₄
S_I	-	0.1	0.2	0.2			
S_2	0.1	-		0.4	0.3		
S_3	0.2		-	0.1		0.4	
S_4	0.2	0.4	0.1	-	0.3	0.2	
S_5		0.3		0.3	-	0.2	
S_6			0.4	0.2	0.2	-	0.8
S_{14}						0.8	

For $i = I W_1 = \{S_1\}$, the set of adjacent vertices $W_2 = \{S_2, S_3, S_4\}$.

Path distance vectors $P_i(S_1, S_2)$, $P_i(S_1, S_3)$, $P_i(S_1, S_3)$ are formed between the set of vertices $W_1 = \{S_1\}$ and $W_2 = \{S_2, S_3, S_4\}$ (Table 4)

TUDIE 4. DISIUNCE VECTORS OF SWITCH ST	stance vectors of switch S ₁
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Destination	Adjacent vertex	Metrics way
S_2	S_2	0.1
S_3	S_3	0.2

For I = 2 $W_2 = \{ S_2, S_3, S_4 \}$, the set of adjacent vertices $W_3 = \{ S_5, S_6, S_{14} \}$.

Between the set $W_2 = \{S_2, S_3, S_4\}$ and $W_3 = \{S_5, S_6, S_{14}\}$, distance vectors of paths $P_i(S_2, S_5), P_i(S_3, S_6), P_i(S_3, S_{14}), P_i(S_4, S_5), P_i(S_4, S_6).$

Table 5 shows the distance vector of switch S_2

Table 5: Distance vectors of switch S₂

Destination	Adjacent vertex	Metrics way
S_5	S_5	0.3

Table 6 shows the distance vector of switch S_3

Table 6: Distance vectors of S₃ switch

Destination	Adjacent vertex	Metrics way
S_6	S_6	0.4
S_{14}	S_{14}	0.8

Table 7 shows the distance vector of switch S_4

Table 7: Distance vectors of S₄ switch

Destination	Adjacent vertex	Metrics way
S_5	S_5	0.3
S_6	S_6	0.2

As a result, three minimal non-intersecting paths $P_1(1,5) = S_1$ are formed from the vertex S_1 to the vertex $S_5 \rightarrow S_2 \rightarrow S_5$; $P_2(1,5) = S_1 \rightarrow S_4 \rightarrow S_5$; $P_3(1,5) = S_1 \rightarrow S_3 \rightarrow S_6 \rightarrow S_5$.

Path $P_4(1,5)=S_1 \rightarrow S_3 \rightarrow S_{14} \rightarrow S_6 \rightarrow S_5$ intersects at the vertex S_6 with the path $P_3(1,5)=S_1 \rightarrow S_3 \rightarrow S_6 \rightarrow S_5$ with a smaller metric.

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Table 8 shows the path metrics $P_i(1,5)$ of switch S_1

Table 8: Distance vectors of switch S_I

Destination	Adjacent vertex	Metrics way
S_5	S_2	0.4
S_5	S_3	0.8
S_5	S_4	0.5

3. ALGORITHM FOR THE FORMATION OF DISTANCE VECTORS

Notations:

 S_d : top of destination

 S_s : top of the path

 D_s : top domain S_s

 D_d : top domain S_d

 $W_{i+l} = \{ s_j \}$: vertex set adjacent to vertex set $S_i = \{ s_j \}$

 $R_j(s_d, s_i)$: path vector from vertex s_j to vertex s_d in the direction of vertex s_i

 $p_j(s_d, s_i)$: path from vertex s_j to vertex s_d

 $l_{i,j}$: path link between vertices s_i and s_j

 M_i : Path metric P_j

 $m_{i,j}$: Path link metric

 C_i : criterion for uniform loading of the path P_i .

 TS_j : table of path vectors of the vertex (switch) S_j

 TD_j : domain controller path vector table D_J

 TN_j : network controller path vector table S_j

 BS_i : set of adjacent vertices domain D_i

WD: many domains

 WS_i : set of domain vertices D_i

k: number of path domains P_j (s_d , s_i)

- 1. Begin/* formation of paths P_j (S_d , S_i) from vertex s_j to vertex s_d */;
- 2. if $R_j (s_d, s_i) \in TS_j$ then go to 35 /* TS_j table contains path */;
- 3. if $S_d \in WS_j$ and $S_s \in WS_j$ then go to 23 /* S_d and S_s are in the same domain */;
- 4. if $R_j (s_d, s_i) \in TN_j$ then go to 35; /* *TS* table contains the path to S_d */;

- 5. begin /* Domain definition D_i top S_d */;
- 6. i = 1;
- 7. if $S_d \in D_i$ then d:=i; go to 10;
- 8. i = i + 1;
- 9. if i < k go to 7;
- 10. end;
- 11. Begin /*formation of a vector of paths between domains D_s and D_d
- 12. i = 1;
- 13. $S_i = \{ s_d \};$
- 14. form $S_{i+1} = \{ s_j \mid i=1,..,k \};$
- 15. For all $s_j \in S_{i+1}$ determine R_j (s_d , s_i);
- 16. $R_j(s_d, s_i) \rightarrow TS_j /* \text{ put } R_j(s_d, s_i)$ into $TS_j */;$
- 17. $P_j(s_d, s_i) = P_i(s_d, s_m) + l_{i,j};$
- 18. Determine M_i ;
- 19. $M_i \rightarrow TS_j /* \text{ put } M_i \text{ in } TS_j */; ;$
- 20. Determine D_i ;
- 21. $D_i \rightarrow TS_j /* \text{ bring } D_i \text{ in } TS_j */;$
- 22. if $S_s \in s_{i+1}$ then go to 15;
- 23. $S_i := S_{i+1};$
- 24. go to 4
- 25. end
- 26. for j := l step 1 to k do
- 27. Begin /* forming a vector of paths within the domain D_J
- 28. i = one;
- 29. $S_i = \{s_s\};$
- 30. form $S_{i+1} = \{ s_j \mid i = 1, ..., k \};$
- 31. For all $s_j \in S_{i+1}$ determine $Rj(s_d, s_i)$;
- 32. $R_j (s_d, s_i) \rightarrow TS_j /* \text{ put } R_j (s_d, s_i)$ into $TS_j /* ;$
- 33. $p_j(s_d, s_i) = P_i(s_d, s_m) + l_{i,j};$
- 34. Determine M_i ;
- 35. $M_i \rightarrow TS_j /*$ put M_i in $TS_j */$;
- 36. if $s_s \in S_{i+1}$ then go to 21;
- 37. $S_i := S_{i+1};$
- 38. go to 4
- 39. end
- 40. $R_j (S_s, S_d) \rightarrow TS_s /*$ the path vector value is entered into the path vector table of the domain switch $D_s */$;
- 41. end

Figure 3 shows the result of the formation of paths within the domains included in the path $P(S_1, S_{28})$. The optimal path between nodes S_s and S_n is chosen based on the minimum packet transmission delay.

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Figure 3: path formation $P(S_1, S_{28})$

As a result, for the path $P(S_1, S_{28})$ at the vertex S_1 , the path vector $R_1(S_1, S_{28}) = \{S_4, M_1\}$ with the metric $M_l = 1.2$ is formed.

4. PATH RECONFIGURATION

The presence of several vectors of distances to a given vertex at each vertex of the generated path allows dynamic reconfiguration of the path. In case

of channel overload $S_6 \rightarrow S_{15}$ by 50%, the this case, a new path will be formed between the vertices S_1 and S_{28} (Figure 4) through the domain D_2 with a delay equal to 1.3. This is only 10% more than the delay on the path P_1 (1,28) before the S_6 channel is overloaded $\rightarrow S_{14}$.



Figure 4: path reconfiguration $P(S_1, S_{28})$ when channel S_6 is overloaded $\rightarrow S_{14}$

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As a result, for the path $P(S_1, S_{28})$ at the vertex S_1 , the path vector $R_1(S_1, S_{28}) = \{S_2, M_1\}$ with the metric $M_1 = 1.3$ is formed.

For example, when overloading the link $L(S_{22}, S_{28})$ paths $R_1(S_1, S_{28})$ the data stream will be redirected according to the distance vector $R_2(S_5, S_{28}) = \{S_{24}, M_2\}$ along the path $S_{22} \rightarrow S_{24} \rightarrow S_{28}$. The transmission delay will increase by 0.1 and become 1.4 instead of 1.3. In this case, the recalculation of the entire path $R_1(S_1, S_{28})$ is excluded in the process of information transfer.

Route correction in the network controller and domain controllers can be done statically or dynamically, depending on the type of network.

5. CONCLUSION

The paper proposes a method for multi-path routing of multi-domain software-defined networks, which, due to the presence of a central SDN controller in the network, reduces the time for generating multiple routes. The time complexity of path formation is reduced due to the proposed method of dividing the network into the optimal number of routing domains using the k-means method, which allows reducing the time complexity of routing. The proposed algorithm for multipath routing along the distance vector allows you to dynamically rebuild the route in the process of information transfer.

In the future, when forming a route, the fuzzy logic method can be used [22], [23] to ensure uniform loading of computer network channels.

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